

### BNL-101795-2014-TECH AD/RHIC/RD/13;BNL-101795-2013-IR

### Tevatron Beam Position Monitor System

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February 1988

Collider Accelerator Department Brookhaven National Laboratory

### **U.S. Department of Energy**

USDOE Office of Science (SC)

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#### AD/RHIC-RD-13

Tevatron Beam Position Monitor System

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R. Shafer

Los Alamos National Laboratory

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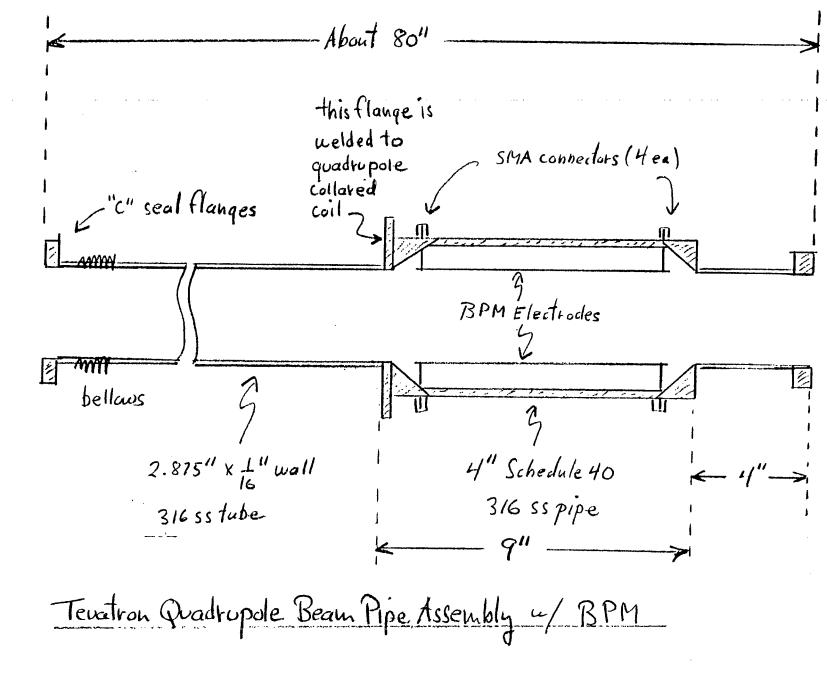
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1. Overall Arrangement

1) About 220 beam monitors (110 x, 110 y) around 6280 m circumference. Tune = 19.4, so 5x and 5y monitors per betatron wavelength 2) Position monitors are 2 electrode stripline geometry, 4 kelvin, welded to guadrupoles 3) All electronics is located in 24 Service Buildings, above ground and outside radiation area. 4) Cables to electronics are up to 200 m long. 5) Completely parallel signal processing - no multiplexing of monitors. 6) Electronics is modular: RF electronics in NIM modules. Digital " in multibus 7) Local intelligence - Two Zilog 280 microprocessors. PROMs - local storage of programs. RAM - stores dounloaded set parameters - stores requested data files. - stores part-mortem files 8) Communication - CAMAC serial highway. 9) Beau loss monitor is integral part of system.

2. 2. Beam Position Monitors beam at T.(w) Ia(w) beam  $2 = 20 \, \mathrm{cm}$ 1) Electrodes: 50 ohm transmission lines Very directional when particle velocity = signal velocity 3) Non resonant structure: can calculate 2/n 4) Monitors welded to quadrupoles (X -> Fquad; y -> Dquad) 5) Alignment scheme using wire on quad magnetic axis (Ref 8) 6) All 4 cables brought out through cryostat 7) Coax suitches select outputs for p or plan operation 8) Cables to electronics R68 (foam) up to 200m long



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9) Major problem

Ceramic in RF connector at 4 kelvin was cracking due to martensitic transformation in 3046 stainless steel. Solved by using Cu-Ni alloy - Clow yield point)

10) Minor problem

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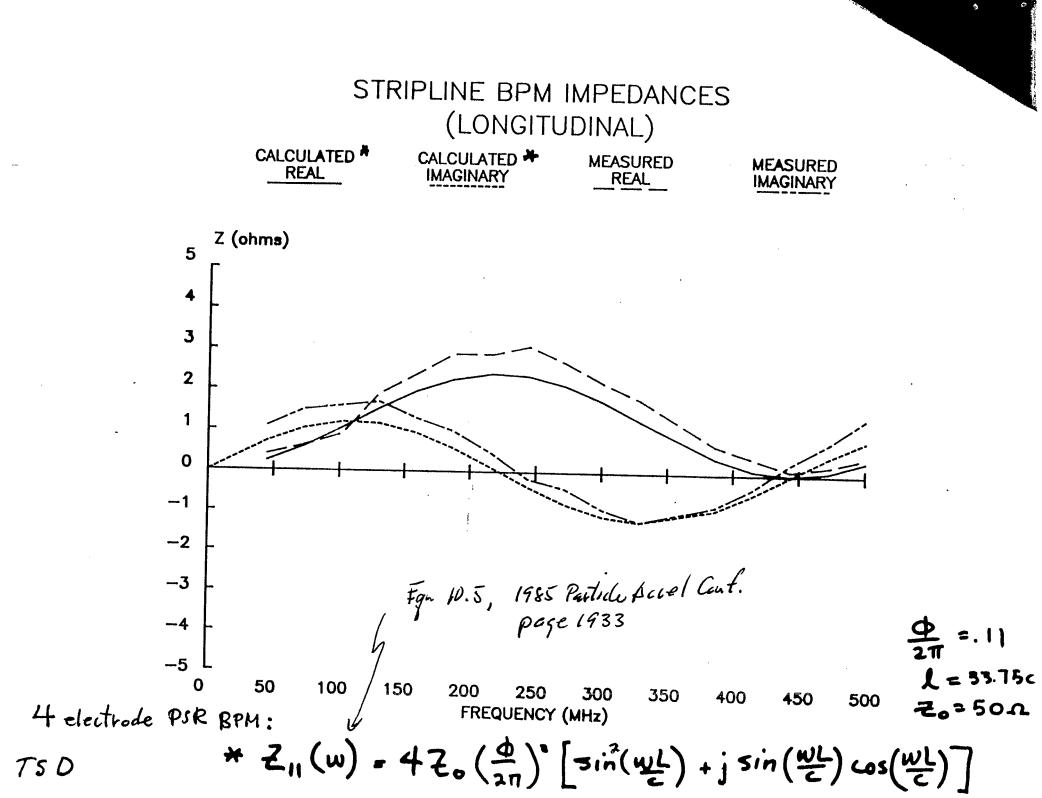
Contact connections in connectors at 4 kelvin not 100% reliable. Only 99.6%. . \_\_\_ \_\_\_

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4. 3. Basic Equations for Beam Position Monitor 1) Assume Gaussian beam bunch (rms bunch length o)  $I_{6}(t) = \frac{eN}{\sqrt{2\pi\sigma}} \exp\left[\frac{-t^{2}}{2\sigma^{2}}\right]$ 2) Fourier Transform (wo/27 = bunching frequency)  $I_{b}(t) = \langle I_{b} \rangle + 2 \langle I_{b} \rangle \sum_{m} I_{m} \cos(m \omega_{o} t)$  $\langle I_6 \rangle = e N \omega_0$  $I_{b}(u) = \sqrt{2} \langle I_{b} \rangle \exp\left(\frac{-u^{2}\omega^{2}\sigma^{2}}{7}\right)$ t.m.s. 3) Pickup signals In and IB : Ir >Ih  $I_{A} = -I_{b} \frac{\varphi_{0}}{2\pi} \left[ 1 + \frac{4}{\sigma} \left( \frac{k_{0}}{h} \right) \cos \theta \sin \left[ \frac{\varphi_{0}}{2\pi} \right] + \cdots \right]$  $I_{B} = -I_{b} \frac{\varphi_{b}}{2\pi} \left[ 1 + \frac{4}{\varphi} \left( \frac{k_{o}}{b} \right) \cos \theta_{o} \sin \left[ \frac{\pi}{2} + \frac{\varphi_{b}}{2} \right] + \cdots \right]$ This is electrostatic analysis; beam at (to, 00) 4) Sensitivity Sx for beam displaced distance x in monitor of radius b and electrode angle Øo:  $\frac{S_{x}}{X} = \frac{20 \log \log \left(\frac{T_{A}}{T_{B}}\right)}{X} = \frac{1}{X} \left(\frac{T_{A}}{T_{R}}\right) = \frac{160}{b \ln 10} \frac{\sin \left(\frac{4}{b}/2\right)}{3}$ 

4. BPM Coupling Impedance

1) For electrode pair Z<sub>c</sub>(u) = Re Z<sub>c</sub>(us + j Im Z<sub>c</sub>(u) =  $2 Z_o \left(\frac{\#_o}{2\pi}\right)^2 \left[ \sin^2\left(\frac{\omega \ell}{c}\right) + j \sin\left(\frac{\omega \ell}{c}\right) \cos\left(\frac{\omega \ell}{c}\right) \right]$ (derived in Ref. 4) (satisfies kramers-krönig relations) 2) Signal pouer P(u) = Ib<sup>2</sup>(u) Re Zc(u) =  $2 Z_o \left(\frac{46}{2\pi}\right)^2 S(u^2 \left(\frac{u l}{2\pi}\right) I_b^2(u)$ 3) Longitudinal corpling impedance  $\frac{\mathcal{Z}_{n}(u)}{h} = I_{\frac{u}{h}} \frac{\mathcal{Z}_{c}(u)}{h} = \frac{2\mathcal{Z}_{0}}{h} \left(\frac{\mathcal{L}_{0}}{2\pi}\right)^{2} \frac{\sin(u\ell)}{c} \cos\left(\frac{u\ell}{c}\right)$ General comments 1) Beam behaves like current source Generally good idea to keep Plus > - 40 dBm (10<sup>2</sup> watts) 2) at processing frequency 3) Zu(u) inductive at low frequencies, but becomes capacitive at higher frequencies. Wire measurements confirm this.



6. 3. Intrinsic Monitor Resolution  $\frac{\delta x}{h} \approx \frac{1}{2\sqrt{2}} \sqrt{\frac{P_{N}}{P}}$ (see Ref 4 eqn 9.1) Ps= signal power in bandwidth B (per electrode) PH= noise paret in bandwidth B KTB for thermal noise (-114 dBm for B= 1MH+) b = monitor aperture radius Example - HERA-p cold monitor 1010 protons per bunch bunch frequency 10.4 MHZ bunch length (tms)  $\frac{60 \text{ cm}}{4.71 \times 3 \times 10^{10}} = 0.42 \text{ Msec}$ Processing frequency 104 MH2 Bandwidth 10 MHZ Amplifier N.T. 39B 36° Pickup bo 40cm 2.8 cm 50 2  $P_{s} = 2_{o} \left(\frac{90}{2\pi}\right) \sin^{2}\left(\frac{\omega \ell}{c}\right) \left(\operatorname{Nef}_{\ell}\right) \exp\left[-\omega^{2}\sigma^{2}\right] = .0753 \, \mathrm{mW}$ = -(1 dBm) $P_{\rm H} = -114 dBm + 10 dB + 3 dB = -101 dBm$  $\frac{\delta x}{6} = \frac{1}{2.8} (3 \times 10^{5}) \approx 10^{5} \implies \delta x \sim 0.3 \text{ microns}$ 

this performance is obtainable using Schottley monitor techniques, but not using AM-PM. For AM-PM circuits add about 20dB hoise, so resolution about lox wolge. In addition, if a wide band amplifier is used in circuit prior to limiter, the limiter will be sensitive to the wide-band noise power of amplifier, unless a narrow-band filter is used on amplifier output.

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Resolution, Dynamic Range, and Signal to Noise  
to obtain a position resolution Sx in a pickup with  
half-aperture b, the ratio of signal power to noise  
power is:  

$$\frac{5x}{5} \approx \frac{1}{2\sqrt{2}} \sqrt{\frac{P_{H}}{P_{e}}}$$
  
Ideally, if there is no electromagnetic noise (EMI),  
 $(P_{H})_{dBm}^{=} -114 \, dBm \times Baulwidth in 10142$ .  
Suppose we had a 100:1 Variation in signal amplitude  
(40dB), a some half aperture and a resolution require-  
ment of 0.1 mm ( $\frac{5x}{5} = \frac{1}{500} \approx \frac{P_{S}}{P_{H}} = 45 \, dB$ ), and a noise  
figure of 20 dB. The minimum signal power at full  
intensity is cassuming no EVII):  
KTB (B=101441) -104 \, dBm  
hoise figure + 20 \, dB  
resolution + 45  
dynamic range + 40  
Tatal + 1 \, dBm

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6. RF Signal Processing
1) Uses frequency domain amplitude to phase conversion technique (see attached)
Reasons: a) Very fast real-time normalized position signal 5 to 10 RF cycles -> 150 micron position precision.
b) Very large dynamic range. Not limited by granularity of digitizers.
c)_Signal amplitudes nearly independent of bunch length 5. In time domain processing (bittons in PETRA) signal amplitude proportional to 1/02.
2) Use proton bunching frequency (53 MHz) for both fixed target and collider operation
3) Narrow band fitter at 53 MHZ required for collider operation Use Nr shorted coax. Center frequency matched to 0.1%.
4) AM-PM conversion done using 4 power combiners and 1 90° coax phase delay.
5) Limiters are AM 685 comparators matched to better than ±1° over SOdB dynamic range.

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9. 6) Phase detector is double-balanced mixer. 7) Frequency for processing chosen to be 53 MHz rather than 106 MHz be cause: a) Signal amplitude less dependent on o (buch length) 6) Limiters work better at lover trequencies c) More power at longer bunch lengths. 8) Biggest problem areas a) Matching of Limiters - matched plug-in limiter modules with computer b) Band paus fitters: cald not achieve satisfactory matching using lumped components Q Cables had to be matched to ± 5° or better. 9) Bean intensity signal uses a) Homodyne linear detector circuit b) home-built 3 decade logarithmic amplifier circuit.

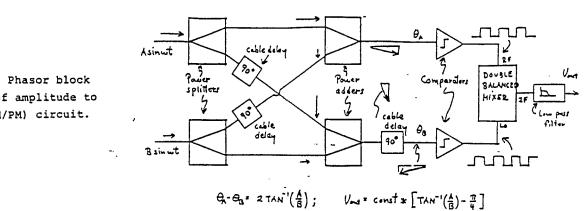
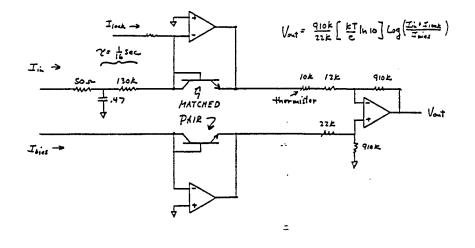


Figure 1. Phasor block diagram of amplitude to phase (AM/PM) circuit.

Figure 2. Basic circuit for a four decade integrating logarithmic amplifier.





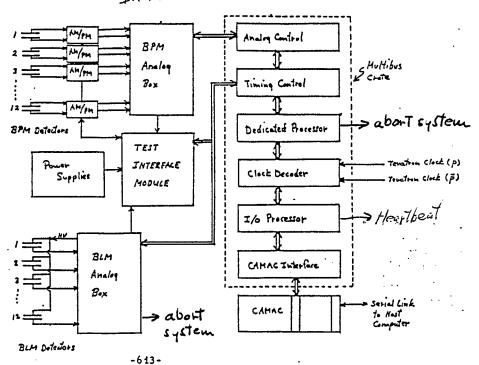
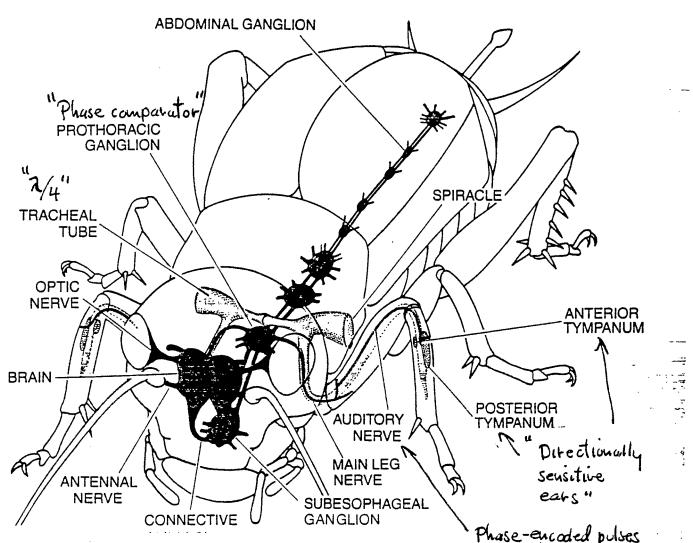


Figure 3. Block diagram of a typical BPM/BLM station.

Neuron-Based Amplitude-to-Phase Converter



TRACHEAL-TUBE ARRANGEMENT (blue) dominates the cricket's peripheral auditory system. It connects the two "ears," which are curious structures below the knee of each foreleg. On each side of the body a large, funnel-shaped upper branch of the roughly Hshaped tube leads to an opening called a spiracle at the body surface; the tube's lower branch descends through the foreleg to a position between the ear's two tympana, which are auditory membranes overlying an array of receptor cells. Hence sound reaches each ear not only externally, from the enviroment, but also internally, by way of sound pressure within the tracheal tube. The cricket's central nervous system (red) consists of a sequence of ganglia (aggregates of neurons), which are linked by pairs of connectives, or bundles of the fibers sent out by the neurons. The frontmost ganglion is the brain, with its optic and antennal nerves. Next comes the subesophageal ganglion, followed by three thoracic ganglia and several abdominal ones. Sensory signals from the array of receptor cells under the auditory tympana enter the prothoracic ganglion, which is the frontmost thoracic ganglion.

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## LETTERS

#### To the Editors:

In "The Federal Support of Mathematics" [SCIENTIFIC AMERICAN, May, 1985], Edward E. David, Jr., has argued convincingly that research and education in mathematics are threatened unless funds are increased substantially in the near future.

Being concerned with the relations between technology and the educational system, we find, however, that this problem (which exists also in other industrialized countries, including our own) has deeper roots. In particular we should like to point out that the general opinion of what mathematics is, and can do, is antiquated and incorrect. Everyone knows there are great opportunities for creative work in both the technical and the natural sciences, but to most people outside the scientific community mathematics appears to be static and sterile. In our opinion this is at least part of the reason it has been difficult to convince politicians and administrators of the importance of mathematics and to attract gifted young people.

The role of elementary education in mathematics in forming most people's concept of the subject is therefore of great importance. If it is true—and we are sure it is—that most pupils leave school with an impression of mathematics as meaningless jiggling around of formulas and proving of obvious statements, financial measures alone will not produce durable results.

It is necessary to develop new educational methods that will allow more people outside the scientific community to appreciate the value of mathematics and to take part in the public debate about its role in society.

#### JENS BJORNEBOE

#### GUNHILD NISSEN

Roskilde, Denmark

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#### To the Editors:

The article "Cricket Auditory Communication," by Franz Huber and John Thorson [SCIENTIFIC AMERICAN, December, 1985], describes an auditory-neuron direction-finding system that is remarkably similar in concept to an electronic system developed to measure the position of particle beams in the accelerators at the Fermi National Accelerator Laboratory.

In both systems, the common problem is to measure the relative power of two signals to within a fraction of a decibel when the absolute power levels can vary by 40 or 50 decibels. In the accelerator, passage of the beam between two small electrodes induces signals whose relative amplitudes are directly related to the position of the beam. These two in-phase signals are symmetrically split and recombined in quadrature (that is, with a 90-degree relative phase shift), so that the phase difference of the two resultant output signals varies by about 6.6 degrees per decibel of amplitude difference between the two input signals.

In the cricket, the relative external sound pressure on the two tympana is determined by the orientation of the cricket in relation to its chirping mate. The coupling of the two tympana by the tracheal tube apparently makes the conversion from amplitude to phase. The result is that the relative amplitudes of the two input signals are completely encoded in the relative phase of the two output signals. In the cricket, since there is little useful information in the amplitude of the nerve impulses from the auditory receptors, the omega neurons in the prothoracic ganglia must measure the relative phase of the two nerve signals. This is apparently accomplished by the reciprocal inhibition function in the omega-1 cells by a mechanism similar to that of two cross-coupled monostable multivibrators in an electronic system. The beamposition system differs from this only in that the phase-detection circuit generates an analogue signal proportional to the phase difference with an accuracy equivalent to about a tenth of a decibel in the ratio of the input signals.

The amplitude-to-phase conversion scheme was chosen to measure the beam position as it accomplished the necessary function with a minimal amount of signal processing. It is interesting that genetic selection in the cricket led to a similar result.

Robert E. Shafer

Batavia, Ill.

To the Editors:

I should like to correct a possible wrong impression conveyed in the article entitled "The Search for Proton Decay," by J. M. LoSecco, Daniel Sinclair and me, which appeared in the June 1985 issue of *Scientific American*.

The first publication applying unified gauge-theoretical ideas to the problem of proton decay was by Jogesh C. Pati and Abdus Salam and appeared in *Physical Review Letters* in 1973. This paper marked the beginning of a development of a class of theories that led to the current widespread belief that protons do indeed decay. Following this early work, in 1974 Howard Georgi and Sheldon Lee Glashow discussed the so-called minimal SU(5) theory, putting forward a quantitative prediction of the proton lifetime (which has since been ruled out by the Irvine-Michigan-Brookhaven experiment described in our Scientific American article). As we mentioned in our article, long before the advent of a theory, evidence for proton decay was sought by experimentalists. This increasingly stringent series of experiments led William Kropp and me to propose (in mid-1975) a dedicated experiment designed to check proton stability more sensitively.

After we had several long discussions with Salam at the University of California at Irvine, during a visit he made for the express purpose of discussing the experimental status of proton decay, Pati and Salam spoke with officials of the U.S. Department of Energy, urging them to support our proposal. Not persuaded that the problem was worthy of further study (because the existing theory of Pati and Salam gave no firm prediction and the subsequent Georgi-Glashow theory was still numerically vague), they took no action for some time.

Meanwhile my colleagues at Irvine and Case Western Reserve University and I continued to ponder the results we had obtained during the previous decade in the deep South African mine and succeeded in pushing the limits somewhat further. Having held for some 25 years the general belief that conservation laws should be tested experimentally, it was gratifying to me that Pati and Salam had provided a base of a more specific kind and I was anxious to pursue the matter.

The increasingly attractive possibility that a unified gauge theory was compatible with—and even called for—an unstable proton under a wide range of assumptions was considered further by Georgi, Helen R. Quinn and Steven Weinberg, who spearheaded the continuing advance toward a testable quantitative prediction. This development, bolstered by the success of the gauge theory of electroweak interactions, led to a changed climate regarding expanded experimental tests, and the past seven years have seen a burst of activity worldwide.

I hope these remarks will help to clarify the record regarding the seminal contributions of the theorists Pati and Salam to the increasingly central problem of proton decay.

FREDERICK REINES

Irvine, Calif.



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2/1/89 10 h Real-Time Normalized Position Signel  $V_{\text{out}} = V_o \left[ -\tan^{-1} \left(\frac{A}{B}\right) - \frac{\pi}{4} \right]$  $\frac{A}{R} = \operatorname{Tan} \int \frac{V_{aut}}{V_{a}} + \frac{\pi}{4} \int$  $\frac{80}{4} \times \approx \left(\frac{A}{B}\right)_{1R} = 20 \log \left\{ \operatorname{Tan}\left[ \frac{V_{out}}{V_{o}} + \frac{\pi}{4} \right] \right\}$ Real-time normalized position output without need for a division (e.g. A-B). Normalization prior to digitization reduces dynamic range requirements of digitizer Log tan function (above) is nearly linear in Vont. It is easily linearized after digitization in software using lookup table which converts digitizer cants to displacement in mm.

7. Digital Signal Processing
1) Completely parallel system. One ADC per monitor. Every monitor digitized up to four times per revolution [T=2]urec
2) Sample and hold gate timing based on
a) Fast self-triggered "beam-present" signal using comparator with computer-set threshold on beam intensity signal (± 10 nsec)
in combination with
b) External-clock generated beam permit signal. (± 100 nsec)
3) One 8-bit ADC per monitor. Successive approximation with 10 MHZ clock. About \$30 each.
4) Resolution: Analog, 5 MHZ BW ~ 30 mictons ", few KHZ ~ 3 " Digital, LSB granularity ~ 150 "
5) Biggest oversight: Inability of digital system to measure very small slow orbit distortions.
6) Non-linear BPM response corrected digitally in host computer.

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- 8. Beam Loss Maintor System
- 1) Sealed-glass construction; l'atur pure arqui qas; 110 cm<sup>3</sup> active volume.
- 2) Fast, close-spaced electrode design (2kV, 1 cm gap)
- 3) Response 70 nano Coulombs/Rad ion collection time ~ 200 microsec electron " " ~ 1 "
- 4) Linearity up to 10 Rads instantaneous quod " 100 " " teasonable
- 5) Leakage current ~ 30 fempto amps at 2 kV
- 6) 4 decade logarithmic amplifier circuit (InA to louA)
- 7) Time constant 1/16 sec to match magnet beam-induced quench response (8mW or 1mJ per gram)
- 8) Hard-wired (with computer-downloaded threshold settings) into beam abort system.
- 9) Low maintenance no circulating gas system
- 10) Spaced every 30 m around fing (at every BPM). 11) Integral part of BPM system.

12) Beam loss in superconductor to create a quench; a) Instantaneous (<1/16sec) 1 m J/gram of 50 Rads 6) slow (7 '116 sec) SmW/qram or 800 Rads/sec 13) Biggest problems with beam loss monitor a) Cannot differentiate between Main Ring and Tevatron losses. Main Ring Funs at high intensity to create plats. b) Non-unitorm spacial response along Tevatron. 30m spacing between ion chambers. Located at suspected loss points (i.e. F and D quads) so relatively insensitive to losses in dipoles. .. . . . ..... -----\_\_\_\_\_ ...... ----\_\_\_\_\_ ------------. . \_\_\_\_\_ 

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14. 9. Communications and Timing two communication channels: 1. CAMAC serial highway a) Point-to-point; host -> one of 24 service buildings b) host -> electronics parameter downloading parameter set verification host electronics data readback host = electronics ..... initiate Prom routines host > electronics 2. 10 MHZ clock with encoded & bit trigger events a) broadcast host -> all electronics b) 256 different trigger events encoded on clock 16 reserved for beam position system using diphase code. c) Real-time ± 100 nsec d) Two lines; I for protons (clockwise) 1 for plars (counterclock wise)

## 10. Typical Dounloaded Parameters

1. Beam intensity trigger threshold for "beam present" signal 2. Beam present enable gate delay (0 to 25.6, usec) and width (o to 1.6 usec) 3. Number of averages in multi-turn measurement (8, 16, 32, 64) 4. Repeat time interval of multi-turn averaging (1,2,4,8,16 msec) 5. Beam alarm and beam about thresholds for low B field and high B field (four values) for position limits (rarely used) \* 6. Same for beam loss monitor limits 7. Beam loss monitor high voltage setting ( DAC -> DCTO DC conv) 8. Multiplicity of beam position or loss monitors to trigger abort. 9. Mask bit to duable all functions of an individual channel 10. Mask bit to disable abort function of induidual channel. 11. Select fixed target or collider operation (sets certain delays) 12. Select p or bbar operation 13. Other similar items

15.

Note: All downloaded parameters are loaded into write/tead registers and read back for verification

\* Beam position system measured only beam centroids, and was insensitive to beam size. Beam loss monitor was sensitive to beam halo.

16. 11. Typical Diphase-encoded "Events" on 10 MHz Clock 1) Prepare for beam - prevents all self-test ratines. 2) End of beam - prohibits beam injection, allows self tests. 3) Reset Clock "To". 4) Abort in progress (stops post-mortem FIFO memory). 5) Low B (magnetic) field ? selects about and alarm 6) High B (magnetic) field ? position and beam loss limits 7) Take a single-turn measurement; store in cache RAM.\* 8) Store next multiturn measurement in cache RAM. 9) Begin a turn-by-turn measurement. **\_\_** - · -------\*cache RAM is a 4 byte memory register readable by CAMAC serial highway.

# 12. Typical Self-Test Features

All self-test proceedures are stored in local PROMS and carried out under microprocessor control when initiated by host (VXX) computer. Results of tests are stored in RAM for readback by host. Tests can only be initiated when station is in beam-disable mode (beam injection prohibited).

- 1) Test BPM cable continuity through BPM to 50 r back termination
  - 2) Inject 53 MHZ RF (0, ± 3dB ubalance) Auto RF circuit and perform "normal" signal processing
- 3) Measure all de pouer supply voltages

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4) Ramp BLM power supply down and up, and perform "normal" signal processing on induced charge in circuit (2 picoFarads x 2 kV = 4 nano Calombs)

s) Heartbeat (continuous test) - missing pulse triggers abort system etc.

- 13. Some Typical Data Readback Formats
- All readback effete stored in RAM for rapid readback by host. Timing of data acquisition (if necessary) controlled by "event" on IOMHZ clock.

- All Stations
- 1) Single turn measurement: x position, x position, intensity, beau
- 2) Muttiturn measurement: X position, Y position, beam loss
- 3) Post Morten memory the SIZ most recent x and y positions and BLM measurements.

## Only 2 Stations

1. Turn-by-turn measurement. One point per turn for both X and Y for up to 1024 turns (now 7, 1,000,000) Signal processing includes Fast Fourier Transform for tune measurements.

## Other operations

- 1. Data archiving for storing data for later comparison to other measurements
- 2. Display of difference plots: (New data vs old data)

Figure 4. Flash display showing horizontal position, vertical position, and intensity vs. location around the Tevatron for the first turn.

single-turn

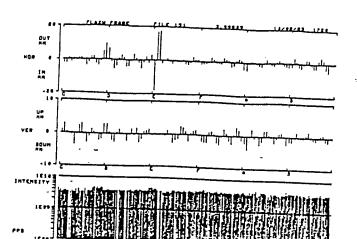
Figure 5. Profile display showing details of the horizontal orbit vs. location around the ring.

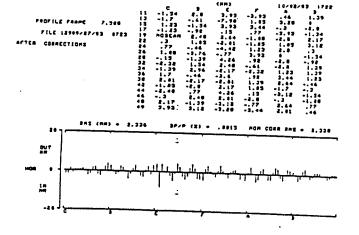
multi-turn

Figure 6. Profile display showing horizontal and vertical orbits, and beam loss vs. location around ring.

### multi-torn

Beam





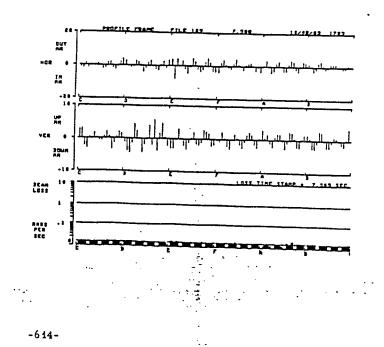


Figure 7. Turn-by-turn plots for "pinged" beam. In this case, the coupling is weak and the tune spread is small. The x and y positions are shown for 1024 turns. The Fast Fourier Transform represents the tune range from 19.10 to 19.50.

1.5 mm kick in X plane. Note the ISO micton LSB resolution in y plane data.

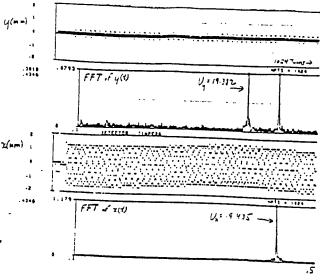


Figure 8. Similar to Figure 7 except that the betatron coupling is strong.

Strong X-y capling later corrected with stew quadtupoles.

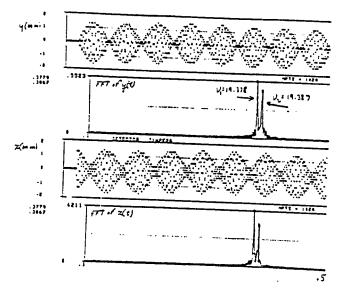
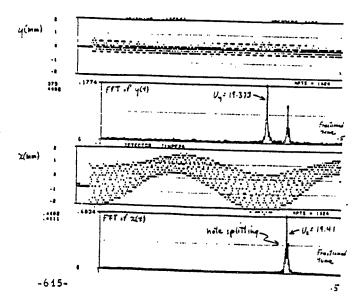


Figure 9. This rather unusual turn by turn plot shows weak coupling between the two betatron modes,

'Snake" due to coherent synchrotron oscillation seen by monitor in dispersive tegion.



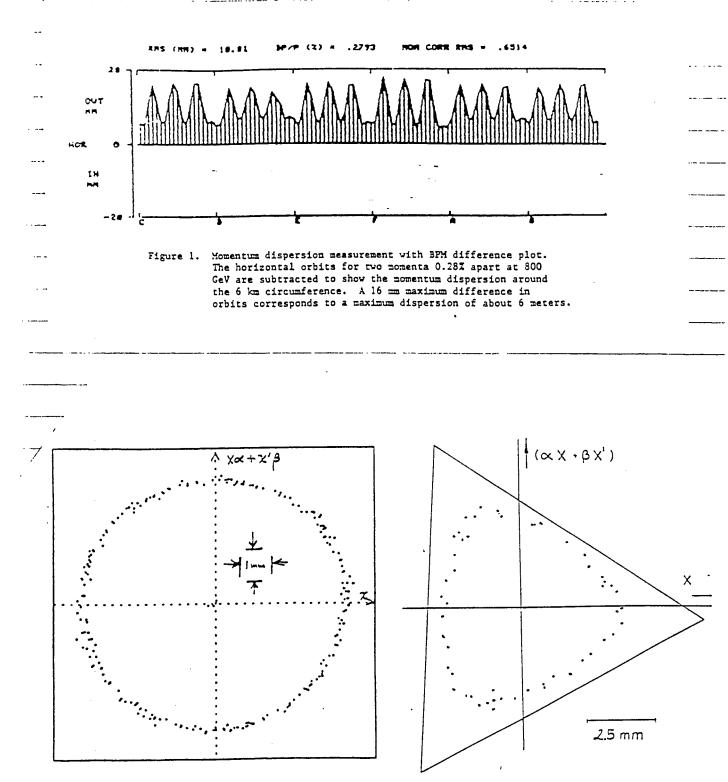


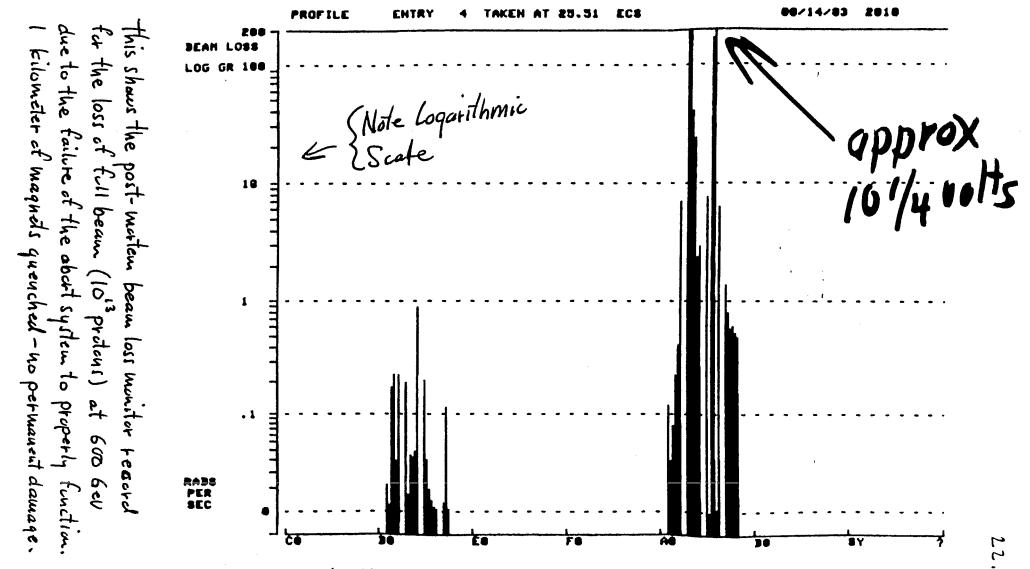
Figure 3. Measured phase space trajectory of coherent horizontal betatron oscillation in Tevatron. Amplitude is about 4 cm. Each point represents one revolution of beam.

(F. Willeke et.al.)

Figure 4. Similar to Figure 3 except that the horizonta tune is near 19.33 and sextapoles have been energized. The triangle represents the calculated limit of stability (separatrices).

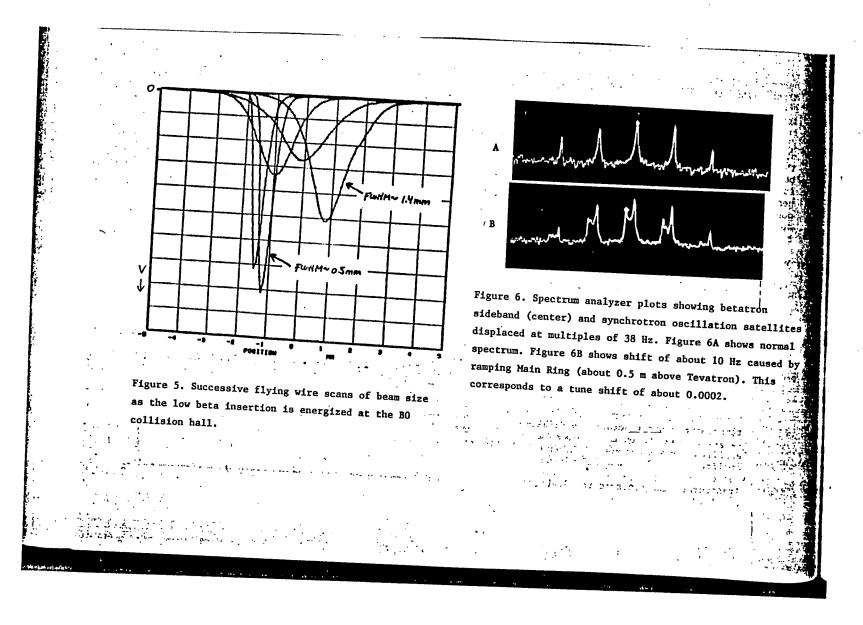
21.

600 Gev/Quench at All



ان و است می است. است است می موجه می بدود است می معنون و <del>است موجه معنون است از است است است است است است است است ا</del>

23. 14. Comments on Other Beam Diagnostics 1. Flying Wite Scanner - best beam protile monitor at Fermi. Invented by Gus Voss, Ewan Paterson, Tom Collins at CEA. Used extensively by Lyn Evans (SPS) and at Fermilab. 2. DCCT (Unser transformer). Good for measuring total circulating current, including protons in wrong RT buckets, or not in any. Hence poor monitor of protons in correct RE bucket. Wide band longitudinal pickup (low coupling impedance) gap - transit time factor = sin (ug/2c) ( wg/2c) set (wg/2c)=1 at 56Hz to minimize gap capacitance  $g = \frac{2C}{\omega} = \frac{2 \times 3 \times 10^{10}}{2\pi \times 5 \times 10^{9} H_{2}} = \frac{1.9 \text{ cm}}{(1 \text{ ength for 56H}_{2})}$ Meke it long enough to see (52 MHz and) 208 MHZ isolated bunches; heighbor buckets 96 nsec -9.6 nsec in order to see particles in neighboring 208 MHz RF buckets : pickup length = 1.44 meters long



\* 5

24. 2.16 cr 2.88 - 1.44 meters meters is better) > beam eight som connectors oster pipe diameter ratio =  $exp\left[\frac{50}{60x8}\right]$  = 1.11 No ferrite or NZ-51 tiles needed. 4. Shottky monitor. CERN system at 10.7 MHz Fermi 21.4 Fermi uses double-down-conversion scheme with phase-locked local oscillators to convert schotlky band (h=448.5) to base band h=77.5 signal . h=448.5 BPF BPF 6=77 h=1113 Phase locking local oscillators to RF prevents drifting of signal as RF frequency is adjusted. Conversion of schotlky band to base band (0 to 47 kHz) allows use of commercial FFT spectrum analyzers.

## 15. Références

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