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Proposed RHIC 160 MHz RF System

J. Griffin

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Collider Accelerator Department

Brookhaven National Laboratory

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Proposed RHIC 160 MHz RF System

J. Griffin

Fermilab

July 15, 1988

PROPOSED RHIC 160 MHR (H=2052) RF SYSTEM

Start out with a reasonable set of specs and boundary conditions. Do what comes naturally (to me at least) and look for insurmountable obstacles.

Requirements and assumptions

I assume a maximum <u>cle</u> beam current of 0.3 A, 57 or 114 bunches (with 03 or 6 missing).

RF voltage ranging from a soolel upward to maximum affordable or 11.5 My, whichever comes first.

(16 conifies, see by each with tomit time factor v c.9)

No comments on low frequency enstern at this time.

- · Hypothetical cavity and PA
- · Bean bunch shape, F.T., of current recipe.
- · Operation during storage

 11 vf system

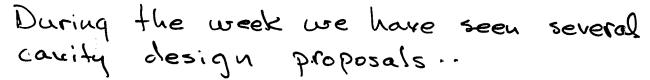
 beam loading compensation (dehuing)

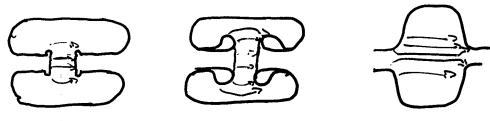
 fast tuner slow tuner

 feed-back loop (or loops)

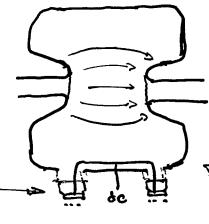
 amplitude control

 transient problem
- · operation during switching from low freg system.
- · Operation during acceleration
- · Suggestions or wild and unruly comments





Take average-compromise-use superfish
Result (my quess):



tube andes - Balanced coupling loop, no coupling capacitor or decoupling cheke.

Assume Social! generated by 100 lity (Two tukes delivering so low each)

Time constant T: 30 = 51 / sec.

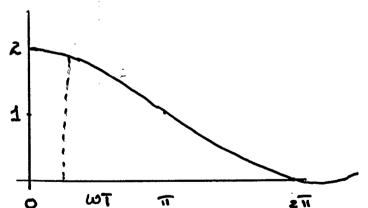
(usher unloaded - or driven by tetroder)

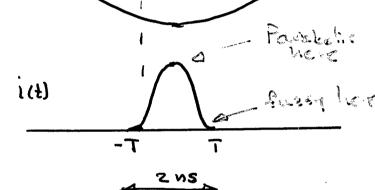
Assume bunch line charge projection

$$i(t) = I_m \cos^2 \frac{\pi t}{2T} \quad |t| \le T$$

$$= 0 \quad |t| > T$$

Normalized F.T.





EHN 4.001 FA

The F.T., normalized to 2, gives the factor by which one must multiply the Sc current to get the rf current at freq. w for bunch half width T.

Here WT = 1 Factor is 1.87

RF current I: = (1.87)(028) = 0.22 A

RF generator current (referred to gap)
for 800 JeV

Note - if tubes are operating at Va = 20 kV and of swing is full anode voltage, then step-up ratio is 40:1.

Can we simply detune to compensate for beam loading?

Note- Butomatic tuning (or detuning) feedback system probably uncomfostable with detuning angle > 60°.

One does not want to detune more than half (less is better) than one rotation band (78.16 kHz).

Detuning angle

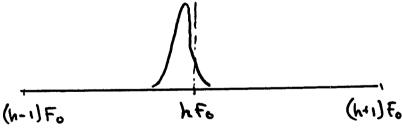
$$\tan \Theta = \frac{ii}{io} \cos Q_S = \frac{ii}{io}$$

Since 95=180°

akent en relation boud.

Caxity half-power bandwidth

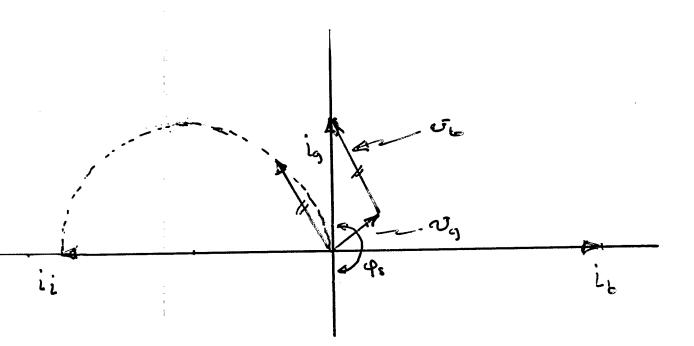
$$\nabla t^{\frac{5}{4}} = \frac{\omega}{t}$$
 also



So: During store, steady state beam loading can easily be accounted for by a local cavily tuning feedback system.

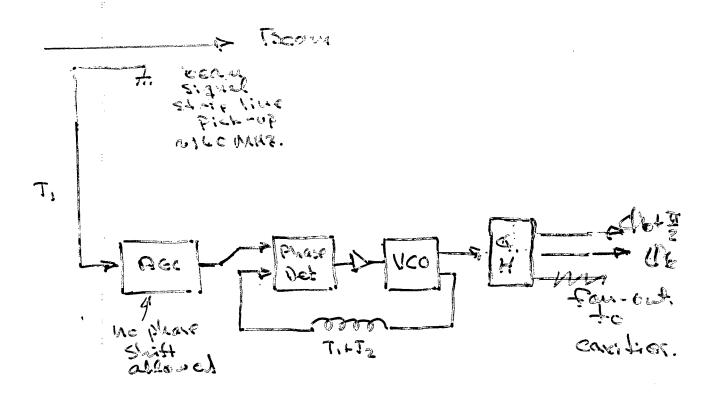
Note-Dehning is correct sign to establish Robinson Stability.



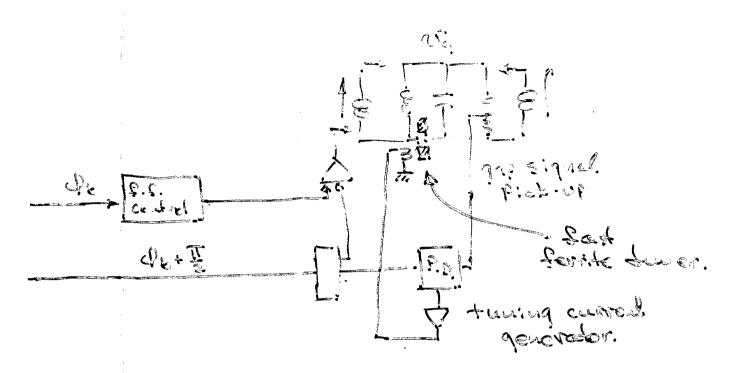


The net gap voltage is in quadrulure with the beam current, as required for stationary bucket, and it is in phase with the generator current, so the load looks real to the generator (vf power source).

It is important to note here that if a bit of feed-forward current is introduced of the beam current phase, the detuning angle will be decreased just as if the beam current had been reduced. This would allow a decrease in the generator current and the net gap voltage, accompanied by a return back to the maximum value (n60°) of the detuning angle.



This system makes signals available at each if station at the beam phase and at the beam phase to The, as regulired to create a stationary bucket above townshow.



A phase objected compasses the gap voltage phase with the a representative of the generator current phase Ofth and determes the carify so that for that compassed is generator current the lead looks real.

Tuning. We need about ± 10 lette.

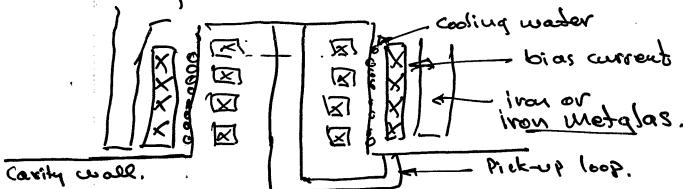
Tund stored energy AM = 2 Af = 2.5 x10-4

AW = (2.5 x10-4)(2.6) = 6x10-4 Jowles

Since one count bias all of the stored energy out of ferrite, better store about 10-3 Joules

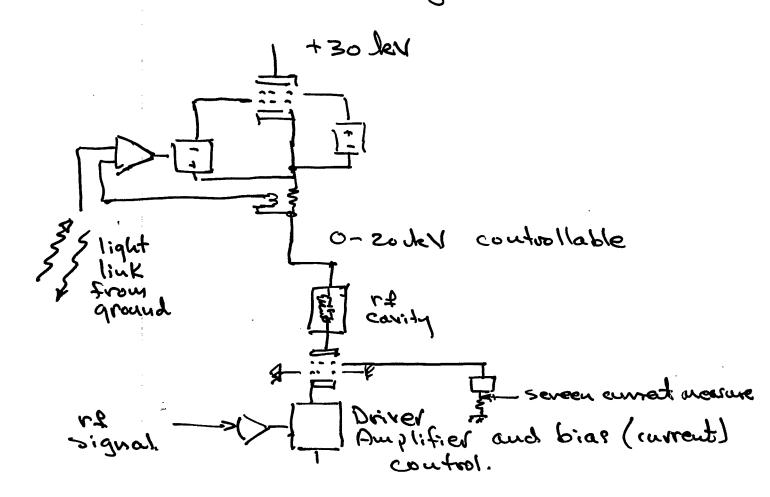
Using Yt Ga microwsve ferrite QN 3000 $P = \frac{\omega_{\text{Wst}}}{Q} = \frac{(10^9)(10^{-3})}{3 \times 10^{-3}} \stackrel{?}{=} 300 \text{ wats.}$

At 1 us/ec one needs 300 ec ferrite, not much. Contained in cylindrical can on cavity wall. Evacuated ??



the can should be slotted longitudinally to allow rapid endoy of bias flux to ferrite.

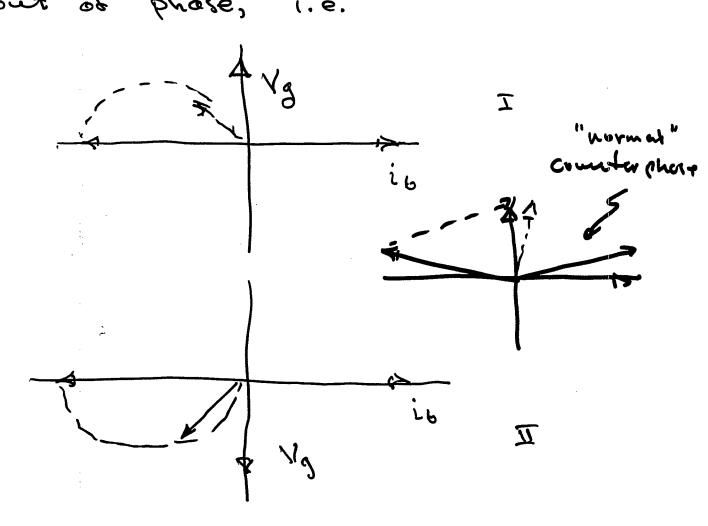
Each Power amplitier should have a controllable series tube modulator so that its anode voltage can be adjusted quickly and precisely between zero and maximum (say zo lev).



A feelback loop, sensing the sreen current of the PA tubes feeds a signal to the driver amplifier which adjusts the P.A. current so that the anode of voltage swing is from he to below the screen voltage (n too v) (and, of course up to 2 va also). When the anode voltage swings below the seven, a sharp rise in Isg can be detected easily.

Now we have precise control of the phase and amplitude of the earity, how do we control the total voltage?

By operating pairs of cavities 180° out of phase, i.e.



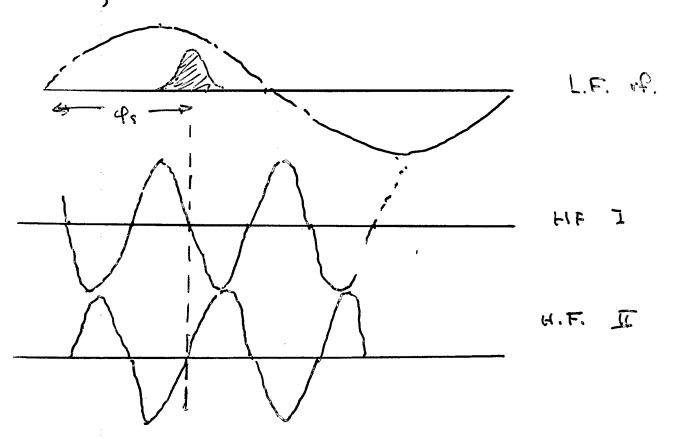
IF I and I are each operating at, say too lev (requiring some feel. Eliminated if full beam intensity) and I is raised to 800 lev. net stationary bucket voltage goes to 400 lev.

subsequently II can be lowered to a south then jumped in phase by 180 degrees so that it adds to I. At this time I is dropped by sooth (800 ->600 using series tube modulator program) Then each can be raised as needed. Finally all carities are in phase at, say, half voltage, and all raised to maximum as needed.

Note that since there is always ended, the result of all + and - detuning will be Robinson stable.

During acceleration all high frequency cavities are operated at about the 300 level and all counterphased as above, providing no net voltage save for error level which will generate only a locussing or de socussing slopp. Since bunches are much longer, Irp is smaller and lower generator current can be used with adequate detuning angle.

During acceleration:



There may be substantial beam induced veltage in H.F. system anyway, so this is a means of controlling it.

Note - at Fermilab protons and antiprotons

Pass in opposite directions through the
same cavities. (& conities, 4 for each)

The cavities are phased and located

so that protons see only 4 conities

and antiprotons the other 4. The phases,

(i.e. azimuthal position) of Pis can be
adjusted w.v.t. Ps.



The H.F. Eyetem must near be templeded over the entire of range. This can be have with a slow medianical tuner so long as the fast ferrite tuner has the range to correct small errors enrouse. Ferrite tuner range might have to be increased by n x 2 over earlier suggestion.

During acceleration the H.F. system is supposed to be "Robinson neutral".

The low frequency system should be defuned to compensate for beam loading and provide Robinson stability.

This means that the phases and amplitudes of the cavities can be maintained sufficiently well so that one specie sees negligible interference from the cavities directed at the other.

control one should be able to control
the amplitude to a few hundred who
in a few hundred by. v 170.

So far I have invoked "local" amplitude and detuning feedback, but no local of feedback. I did require some measure of controlled feed forward.

CONCLUSION

I have not yet encountered any insurmountable obstacles. Everything looks manageable in a fairly straighterward manner.

Suggestions

- · Get a summer student (or etc.)

 to build a full scale cavity out

 of wood (or something). Two half-shells.

 Cover with thin copper foil (or Al.).

 Measure everything transfer radio,

 tuning range, sparious modes-etc.

 Make Photographs-
- Since both cavities (or systems) are to operate simultaneously, look into possibility of making a cavity to do both jobs simultaneously.

 (i.e. low freq now n so MHz.)
- Simulate acceleration with small amount of property phased sixth harmonic of either sign.

Adar Arcion

Rough Cost Estimate-

Per of Station-

RF carify	35 K
Power Amp. w/ driver	40 K
series tube modulator	1 so K
Tuning bias supply Ferrite tunes	40 K
Ferrite tunes	15 K
control electronics	30 K

280 K

Does not include anode power supplies.

One for each eight stations

Z × 30 leV 100 A - ?!

Computer interface etc.