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## The Residual ?-Shift Due to Random Skew Quadrupole Errors

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## **U.S. Department of Energy**

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The Residual *v*-Shift Due to Random Skew Quadrupole Errors

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The V- shift due to the vandom Q, The random a, introduces two Coupled modes with Y-volues V, and V2. The x-motion and the y-motion how have both V-values Vi and V2  $x = ()e^{ix0} + ()e^{ix_20}$  $y = () e^{iy_{2}\theta} + () e^{iy_{2}\theta}$ The Y, V2 Can differ appriably the original Vx, Vy. from Is this N-shift due to 9, dangerous Review of the D-shift due to random b. The b, N-shift is easier to Understand. lines The resonances Mx 1/2 + My 1/2 = integen one considered dangerous Yy if a time modulation of the Y-values is present. a 11-shift due to bi 1833 •8 Yx which shifts Vx Yy but of the resonance freebox is considered dangerous.

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The expected V-shifts in RHIC are  

$$[V_i - V_2]_{\text{max}} \simeq los \times lo^{-3}$$
 for  $\beta^* = 6$   
 $[V_i - V_2]_{\text{max}} \simeq 250 \times lo^{-3}$  for  $\beta^* = 2$ 

The N-Shifts due to 9, Cannot be Corrected with b, Correctors Such as GF and QD.

The V-shifts due a, and b, an given by  $|Y_{1} - Y_{2}| = 2 \left\{ \left( \frac{y_{x} - y_{y}}{2} \right)^{2} + \frac{y_{y}}{2} \right\}^{1/2}$   $= \frac{1}{4\pi\rho} \int ds \left( \frac{y_{x} - y_{y}}{2} \right)^{1/2} a_{1} e_{x\rho} \left( \frac{y_{x} - y_{y}}{2} \right)^{1/2}$   $V_{av} = \left( \frac{y_{1} + y_{2}}{2} \right)^{1/2} = \left( \frac{y_{x} + y_{y}}{2} \right)^{1/2}$ 

Where Vx, Xy are V-velues when 9, =0. Above correct to first order in 9. 2

bi Correctors can be used to move Yx, My The best one can do Is make Yx=Yy and then | V,-V2) = ) 5 V, ] You cake controlled using the b, correctors.

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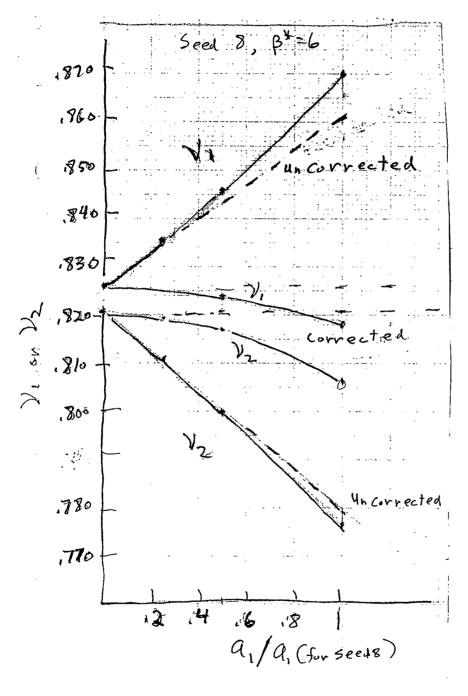
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$\beta^{\star} = b$			p*=2		
(	Un Corrected	Corvected	uncorrected corrected		
Nseed	V. V2 Vi-12/10	× v. v2 1, -1/2/10-3	V, V2 1Vi-V. 1/10-3 V, V2 1V-V21/10-3		
)	.8441,801 43	.825 .814 6	.3541.796 58 .828.822 6 .935.707 228 .838 .819 19		
$\left(\begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \end{array} \\ \end{array} $	.868,789 79 .855,795 60 .864,783 81	822 811 11 826 829 6 944 815 9	,935 707 228 838 819 14 ,819 783 86 829 825 4 ,883 772 111 830 823 7		
- 5	.8:4.783 81 .841,820 21	894 .815 9 .832 .818 14	.872 778 94 .836 .820 16		
6	.824,815 9 .836,818 18	828 820 8 820 822 8	848 805 43 832 821 847 840 7 852 834 8		
	,872,772,100 ,845,805 40	.820 .805 15 .826 .821 5	895 .741 154 838 818 20 866 .785 81 .828 .822 6		
10	.854 811 43	.827 .821 4	891 .749 142 . 827 .822 5		

The a fair number of Machines there  
is a large residual 
$$[Y_1 - Y_2]$$
. In 3 cases for  
 $\beta^* = 6$  and for 5 cases for  $\beta^* = 2$ , the  
residual  $[Y_1 - Y_2]$  is about  $11 \times 10^{-3}$  to  $20 \times 10^{-3}$ .  
This appears to be due to terms in  $[Y_1 - Y_2]$   
achich go like  $q_1^2$  or higher powers of  $q_1$ .

(4)

3, , 1/2 Versus Q,



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Local Correction System It appears that the correction of the residual [V,-V2] requires a more local Correction system Apossible local correction is the a correctors here QD in the arcs. Using these correctors, assaming each a corrector can be individually powered, the following [V,-V2] was a chieved

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ļ					
ļ		BX = 6			
!	AL .O				
ļ	Need	Global Corvection	Local Greetlon		
		V,-V2V10-3	12,-12/10-3		
			18, 9001-		
	8	15	6.4		
	85	13	6.6		
	2	10	5,0		
				1 	1
		-			······
		<u> </u>			
	3	20			
<u> </u>	7	18	7.2		
	6		6.7	·	
	5	16	4,0	······································	
	2	19	7.5		i
		1			
Ĺ	1	· · · · · · · · · · · · · · · · · · ·		•	/
ļ	Eurth	er correction	could be a	chieved	by Making Yx=Yy
	1	a de la companya de l			1 5
	Using_	b, Correctors.			
<u> </u>		د الله الله المعادية ا المو		: 	
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- 1) How well can 4-families of 915 Correctors per sextent do?
- 2) What measurements can one do to help set the local a, Correctors?