

# Emittance and Beam Size Distortion Due to Linear Coupling

G. Parzen

December 1992

Collider Accelerator Department  
**Brookhaven National Laboratory**

**U.S. Department of Energy**

USDOE Office of Science (SC)

Notice: This technical note has been authored by employees of Brookhaven Science Associates, LLC under Contract No. DE-AC02-76CH00016 with the U.S. Department of Energy. The publisher by accepting the technical note for publication acknowledges that the United States Government retains a non-exclusive, paid-up, irrevocable, world-wide license to publish or reproduce the published form of this technical note, or allow others to do so, for United States Government purposes.

## **DISCLAIMER**

This report was prepared as an account of work sponsored by an agency of the United States Government. Neither the United States Government nor any agency thereof, nor any of their employees, nor any of their contractors, subcontractors, or their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, completeness, or any third party's use or the results of such use of any information, apparatus, product, or process disclosed, or represents that its use would not infringe privately owned rights. Reference herein to any specific commercial product, process, or service by trade name, trademark, manufacturer, or otherwise, does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States Government or any agency thereof or its contractors or subcontractors. The views and opinions of authors expressed herein do not necessarily state or reflect those of the United States Government or any agency thereof.

AD/AP-51

Accelerator Development Department  
Accelerator Physics Division  
BROOKHAVEN NATIONAL LABORATORY  
Associated Universities, Inc.  
Upton, NY 11973

**Accelerator Physics Technical Note No. 51**

**Emittance and Beam Size Distortion Due to Linear Coupling**

G. Parzen

December 1992

# Emittance and Beam Size Distortion Due to Linear Coupling

G. Parzen

Brookhaven National Laboratory

December 1992

## 1. Introduction

At injection, the presence of linear coupling may result in an increased beam emittance and in increased beam dimensions. Results for the emittance in the presence of linear coupling will be found. These results for the emittance distortion show that the harmonics of the skew quadrupole field close to  $\nu_x + \nu_y$  are the important harmonics. Results will be found for the important driving terms for the emittance distortion. It will be shown that if these driving terms are corrected, then the total emittance is unchanged,  $\epsilon_x + \epsilon_y = \epsilon_1 + \epsilon_2$ . Also, the increase in the beam dimensions will be limited to a factor which is less than 1.414. If the correction is good enough, see below for details, one can achieve  $\epsilon_1 = \epsilon_x$ ,  $\epsilon_2 = \epsilon_y$ , where  $\epsilon_1, \epsilon_2$  are the emittances in the presence of coupling, and the beam dimensions are unchanged. Global correction of the emittance and beam size distortion appears possible.

## 2. The Emittance for Coupled Motion

One definition for the emittances when the particle motion is coupled was given by Edwards and Teng.<sup>1</sup> In four dimensions, one can go from the coordinates  $x, p_x, y, p_y$  to an uncoupled set of coordinates  $v, p_v, u, p_u$  by the transformation<sup>1</sup>

$$x = R v$$
$$x = \begin{pmatrix} x \\ p_x \\ y \\ p_y \end{pmatrix} \quad v = \begin{pmatrix} v \\ p_v \\ u \\ p_u \end{pmatrix} \quad (2.1)$$
$$R = \begin{pmatrix} I \cos \varphi & \overline{D} \sin \varphi \\ -D \sin \varphi & I \cos \varphi \end{pmatrix}.$$

$I$  and  $D$  are  $2 \times 2$  matrices.  $I$  is the  $2 \times 2$  identity matrix.  $\bar{D} = D^{-1}$  and  $|D| = 1$ .  $R$  is a symplectic matrix

$$\begin{aligned}\bar{R} R &= I \\ \bar{R} &= \tilde{S} \tilde{R} S\end{aligned}\tag{2.2}$$

$$S = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{bmatrix}.$$

$\tilde{R}$  is the transpose of  $R$ .

$v, p_v$  and  $u, p_u$  are uncoupled. Thus  $v, p_v$  satisfy differential equations with periodic coefficients whose solutions have the form

$$v = \beta_1^{\frac{1}{2}} \exp(i\psi_1)\tag{2.3}$$

$$p_v = \beta_1^{-\frac{1}{2}} (-\alpha_1 + i) \exp(i\psi_1).$$

A second solution exists with  $\psi_1, \beta_1, \alpha_1$  replaced by  $\psi_2, \beta_2, \alpha_2$ . As in the case of 2 dimensional motion

$$\epsilon_1 = \gamma_1 v^2 + 2\alpha_1 v p_v + \beta_1 p_v^2\tag{2.4a}$$

is an invariant.  $\gamma_1 = (1 + \alpha_1^2) / \beta_1$ . Similarly,  $\epsilon_2$  is an invariant,

$$\epsilon_2 = \gamma_2 u^2 + 2\alpha_2 u p_u + \beta_2 p_u^2.\tag{2.4b}$$

For two dimensional motion, one can find  $\alpha, \beta$  from the one turn transfer matrix  $M(s + L, s)$ .

In 4 dimensions,  $\alpha_1, \beta_1$  and  $\alpha_2, \beta_2$  can be found from the one turn transfer matrix. The process is quite involved<sup>1</sup>, and using Eq. (2.4) to find  $\epsilon_1, \epsilon_2$  when the transfer matrix is known is also involved.

A second definition of the emittance was suggested by A. Piwinski<sup>2</sup> which seems easier to apply. The emittance  $\epsilon_1$  is defined by

$$\epsilon_1 = \left| \tilde{x}_1^* S x \right|^2\tag{2.5a}$$

$x_1$  is the 4 vector for the eigenfunction of the transfer matrix, which are assumed to be  $x_1, x_2 = x_1^*, x_3, x_4 = x_3^*$ .

Since  $\tilde{x}_1^* S x$  has the form of the Lagrange invariant<sup>3</sup>  $\epsilon_1$  is an invariant. It will be shown below that  $\epsilon_1$  defined by Eq. (2.5) and  $\epsilon_1$  defined by Eq. (2.4) are the same. In a similar way,  $\epsilon_2$  is defined by

$$\epsilon_2 = \left| \tilde{x}_3^* S x \right|^2 \quad (2.5b)$$

Note that  $x_1$  and  $x_3$  have to be normalized so that

$$\tilde{x}_1^* S x_1 = \tilde{x}_3^* S x_3 = 2i \quad (2.6)$$

Analytic expressions for  $x_1, x_3$  were given in a previous paper.<sup>4</sup> These results for  $x_1, x_3$  when put in Eq. (2.5) give an analytic expression for  $\epsilon_1$  and  $\epsilon_2$ .

To show that  $\epsilon_1, \epsilon_2$  defined by Eqs. (2.4) and Eqs. (2.5) are equal, one may note that since  $v, p_v, u, p_u$  are uncoupled coordinates, the eigenfunctions in this coordinate system may be written as

$$v_1 = \begin{bmatrix} \beta_1^{\frac{1}{2}} \\ \beta_1^{-\frac{1}{2}}(-\alpha_1 + i) \\ 0 \\ 0 \end{bmatrix} \exp(i\psi_1), \quad v_3 = \begin{bmatrix} 0 \\ 0 \\ \beta_2^{\frac{1}{2}} \\ \beta_1^{-\frac{1}{2}}(-\alpha_2 + i) \end{bmatrix} \exp(i\psi_2) \quad (2.7)$$

One can then show that

$$\tilde{v}_1^* S v_1 = \tilde{v}_3^* S v_3 = 2i,$$

and

$$\left| \tilde{v}_1^* S v \right|^2 = \gamma_1 v^2 + 2\alpha_1 v p_v + p_v^2,$$

which is  $\epsilon_1$  according to Eq. (2.4).

One can show that since  $x = Rv$  and  $R$  is symplectic, that

$$\left| \tilde{x}_1^* S x \right|^2 = \left| \tilde{v}_1^* S v \right|^2, \quad (2.8)$$

and thus the  $\epsilon_1$  defined by Eq. (2.5) is the same as  $\epsilon_1$  defined by Eq. (2.4). One may note that  $x_1 = R v_1$ .

It also can be shown that

$$\int dx dp_x dy dp_y = \epsilon_1 \epsilon_2, \quad (2.9)$$

where the integral is over the region of 4-space which lies inside the two surfaces

$$\begin{aligned}\epsilon_1(x, p_x, y, p_y) &= \epsilon_1 \\ \epsilon_2(x, p_x, y, p_y) &= \epsilon_2\end{aligned}\tag{2.10}$$

This can be shown by transforming the integral in Eq. (2.10) from the  $x$  coordinates to the  $v$  coordinates and using the result  $|R| = 1$ .

### 3. Analytical Results for the Emittance Distortion and its Correction

Analytical results for the eigenfunctions of the  $4 \times 4$  transfer matrix were found in Ref. 4. These are summarized in the following:

$$\begin{bmatrix} x \\ p_x \\ y \\ p_y \end{bmatrix} = G \begin{bmatrix} \eta_x \\ p_{\eta x} \\ \eta_y \\ p_{\eta y} \end{bmatrix} \quad (3.1)$$

$$\begin{aligned} G &= \begin{bmatrix} G_x & 0 \\ 0 & G_y \end{bmatrix} \\ G_x &= \begin{bmatrix} \beta_x^{\frac{1}{2}} & 0 \\ -\alpha_x \beta_x^{-\frac{1}{2}} & \beta_x^{-\frac{1}{2}} \end{bmatrix}, \quad G_y = \begin{bmatrix} \beta_y^{\frac{1}{2}} & 0 \\ -\alpha_y \beta_y^{-\frac{1}{2}} & \beta_y^{-\frac{1}{2}} \end{bmatrix} \\ \eta_x &= A \exp(i\nu_{xs}\theta_x) \left[ 1 + \sum_{n \neq -p} f_n \right] \\ \eta_y &= B \exp(i\nu_{ys}\theta_y) \left[ 1 + \sum_{n \neq p} g_n \right] \\ f_n &= \frac{\nu_{xs} - \nu_x}{\Delta\nu} \frac{2\nu_x b_n \exp[-i(n+p)\theta_x]}{(n - \nu_x - \nu_y)(n+p)} \\ g_n &= \frac{\nu_{ys} - \nu_y}{\Delta\nu^*} \frac{2\nu_y c_n \exp[-i(n-p)\theta_y]}{(n - \nu_x - \nu_y)(n-p)} \\ \Delta\nu &= (1/4\pi\rho) \int ds (\beta_x \beta_y)^{\frac{1}{2}} a_1 \exp[i(-\nu_{xs}\theta_x + \nu_{ys}\theta_y)] \\ b_n &= \frac{1}{4\pi\rho} \int ds (\beta_x \beta_y)^{\frac{1}{2}} a_1 \exp[i(n - \nu_y)\theta_x + \nu_y\theta_y] \\ c_n &= \frac{1}{4\pi\rho} \int ds (\beta_x \beta_y)^{\frac{1}{2}} a_1 \exp[i\nu_x\theta_x + (n - \nu_x)\theta_y] \\ \theta_x &= \psi_x/\nu_x, \quad \theta_y = \psi_y/\nu_y \end{aligned} \quad (3.2)$$

$\nu_{xs}, \nu_{ys}$  are the solutions of

$$\nu_x = \nu_{ys} + p, \quad (\nu_{xs} - \nu_x)(\nu_{ys} - \nu_y) = |\Delta\nu|^2 \quad (3.3)$$



$\nu_x, \nu_y$  are assumed to be close to the resonance line  $\nu_x = \nu_y + p$ .  $p_{\eta x}$  and  $p_{\eta y}$  can be found using

$$p_{\eta x} = (1/\nu_x) d\eta_x/d\theta_x, \quad p_{\eta y} = (1/\nu_y) d\eta_y/d\theta_y \quad (3.4)$$

The  $A$  and  $B$  coefficients are determined by the condition on the eigenfunctions

$$\tilde{x}^* S x = 2i \quad (3.5)$$

This gives the relationship<sup>4</sup>

$$|A|^2 (\nu_{xs}/\nu_x) + |B|^2 (\nu_{ys}/\nu_y) = 1 \quad (3.6)$$

There are two solutions of Eq. (3.3) corresponding to the two normal modes. For the mode for which  $\nu_{sx} \rightarrow \nu_x$  when  $a_1 \rightarrow 0$ , we will put  $\nu_{xs} = \nu_1$ ,  $\nu_{ys} = \nu_1 - p$ . For the mode for which  $\nu_{ys} \rightarrow \nu_y$  when  $a_1 \rightarrow 0$ , we will put  $\nu_{ys} = \nu_2$ ,  $\nu_{xs} = \nu_2 + p$ .

For the  $\nu_1$  mode

$$\begin{aligned} B_1 &= -\frac{\nu_1 - \nu_x}{\Delta\nu} A_1 \\ |A_1|^2 \left( \frac{\nu_1}{\nu_x} + \frac{(\nu_1 - p)}{\nu_y} \left| \frac{\nu_1 - \nu_x}{\Delta\nu} \right|^2 \right) &= 1. \end{aligned} \quad (3.7a)$$

For the  $\nu_2$  mode

$$\begin{aligned} A_2 &= -\frac{\nu_2 - \nu_y}{\Delta\nu^*} B_2 \\ |B_2|^2 \left( \frac{\nu_2}{\nu_y} + \frac{(\nu_2 + p)}{\nu_x} \left| \frac{\nu_2 - \nu_y}{\Delta\nu} \right|^2 \right) &= 1. \end{aligned} \quad (3.7b)$$

The eigenfunctions being known, one can now compute  $\epsilon_1$  and  $\epsilon_2$

$$\epsilon_1 = \left| \tilde{x}_1^* S x \right|^2 = |\eta_1^* S \eta|^2 \quad (3.8)$$

since  $G$  is symplectic.

$$\eta_1 = \begin{bmatrix} \eta_{x1} \\ p_{\eta x1} \\ \eta_{y1} \\ p_{\eta y1} \end{bmatrix} \quad (3.9)$$

one finds

$$\begin{aligned}
\epsilon_1 = & |\eta_{x1}|^2 p_{\eta x}^2 + |p_{\eta x1}|^2 \eta_x^2 - \eta_x p_{\eta x} (p_{\eta x1}^* \eta_{x1} + \text{c.c.}) \\
& + |\eta_{y1}|^2 p_{\eta y}^2 + |p_{\eta y1}|^2 \eta_y^2 - \eta_y p_{\eta y} (p_{\eta y1}^* \eta_{y1} + \text{c.c.}) \\
& + p_{\eta x} p_{\eta y} (p_{\eta x1}^* p_{\eta y1} + \text{c.c.}) \\
& + \eta_x \eta_y (p_{\eta x1}^* p_{\eta y1} + \text{c.c.}) \\
& - p_{\eta x} \eta_y (\eta_{x1}^* p_{\eta y1} + \text{c.c.}) \\
& - \eta_x p_{\eta y} (p_{\eta x1}^* \eta_{y1} + \text{c.c.})
\end{aligned} \tag{3.10}$$

One can now find analytic expressions for  $\epsilon_1$  by substituting for  $\eta_1$  from Eqs. (3.1) to (3.7) into Eq. (3.10). This result is usually quite complicated. One interesting case is when a correction system has been used to cancel the  $b_n$  and  $c_n$  for  $n \simeq \nu_x + \nu_y$ , which generate the larger terms in the expressions for the eigenfunctions. Let us assume that enough  $b_n, c_n$  have been corrected so that, from Eq. (3.2), the eigenfunctions can be written as

$$\begin{aligned}
\eta_x &= A \exp(i\nu_{xs}\theta_x) \\
\eta_y &= B \exp(i\nu_{ys}\theta_y) \\
p_{\eta x} &= iA \exp(i\nu_{xs}\theta_x) \\
p_{\eta y} &= iB \exp(i\nu_{ys}\theta_y)
\end{aligned} \tag{3.11}$$

It has been assumed that the different resonance has also been corrected, and that  $\nu_x, \nu_y$  is very close to the nearby difference resonance  $\nu_x - \nu_y = p$ , so that  $\nu_{xs}/\nu_x \simeq 1$  and  $\nu_{ys}/\nu_y \simeq 1$ . It will be seen that correcting the  $b_n, c_n$  for  $n \simeq \nu_x + \nu_y$  and the nearby different resonance will essentially correct the emittance distortion and the beam size distortion.

Putting the corrected results for the eigenfunctions Eq. (3.11) into the emittance result Eq. (3.10) one finds

$$\begin{aligned}
\epsilon = & |A|^2 (p_{\eta x}^2 + \eta_x^2) + |B|^2 (p_{\eta y}^2 + \eta_y^2) \\
& + p_{\eta x} p_{\eta y} (A^* B + \text{c.c.}) \\
& + \eta_x \eta_y (A^* B + \text{c.c.}) \\
& - p_x \eta_y (-iA^* B + \text{c.c.}) \\
& - \eta_x p_{\eta y} (-iA^* B + \text{c.c.})
\end{aligned} \tag{3.12}$$

There are two solutions of interest corresponding to how well one can correct  $\Delta\nu$ ,

$$\begin{aligned} \text{Case 1. } |\Delta\nu| &\ll |\nu_x - \nu_y - p| \\ \text{Case 2. } |\nu_x - \nu_y - p| &\ll |\Delta\nu| \end{aligned} \quad (3.13)$$

For the first case,  $|\Delta\nu| \ll |\nu_x - \nu_y - p|$ , then the coefficients  $A, B$  in the eigenfunctions satisfy<sup>4</sup>

$$\begin{aligned} |A_1| &= 1 & B_1 &= 0 \\ |B_2| &= 1 & A_2 &= 0 \end{aligned} \quad (3.14)$$

Then for case (1) Eq. (3.12) gives

$$\begin{aligned} \epsilon_1 &= \epsilon_x \\ \epsilon_2 &= \epsilon_y \end{aligned} \quad (3.15)$$

where use has been made of the results

$$\begin{aligned} \eta_x + p_{\eta x}^2 &= \gamma_x x^2 + 2\alpha_x x p_x + \beta_x p_x^2 = \epsilon_x \\ \eta_y + p_{\eta y}^2 &= \gamma_y y^2 + 2\alpha_y y p_y + \beta_y p_y^2 = \epsilon_y \end{aligned} \quad (3.16)$$

Thus in case 1,  $\epsilon_1, \epsilon_2$  are the same as  $\epsilon_x, \epsilon_y$ .

For case (2),  $|\nu_x - \nu_y - p| \ll |\Delta\nu|$  then<sup>4</sup>

$$\begin{aligned} |A_1| &= |B_1| = 1/\sqrt{2} \\ |A_2| &= |B_2| = 1/\sqrt{2} \\ A_1^* B_1 + A_2^* B_2 &= 0 \end{aligned} \quad (3.17)$$

Then for case (2), Eq. (3.12) gives

$$\epsilon_t = \epsilon_1 + \epsilon_2 = \epsilon_x + \epsilon_y \quad (3.18)$$

We no longer have  $\epsilon_1 = \epsilon_x, \epsilon_2 = \epsilon_y$  as in case (1) however  $\epsilon_t$  is not increased by the linear coupling.

Thus, if one corrects enough of the  $b_n, c_n$  for  $n \simeq \nu_y + \nu_x$  and also corrects  $\Delta\nu$ , the driving term of the nearby difference resonance,  $\nu_x - \nu_y = p$ , then the emittance distortion has also been corrected. We will either obtain  $\epsilon_1 = \epsilon_x, \epsilon_2 = \epsilon_y$  or  $\epsilon_1 + \epsilon_2 = \epsilon_x + \epsilon_y$  depending on how well  $\Delta\nu$  has been corrected.

#### 4. Analytical Results for the Beam Size Distortion and its Correction

In the previous section, results were found for the emittance distortion, and it was found that if the  $b_n, c_n$  for  $n \simeq \nu_x + \nu_y$  and  $\Delta\nu$  are corrected, then the emittance distortion is also largely corrected. For 4 dimensional motion, the connection between the beam size and the emittance is not as simple as it is in the 2 dimensional uncoupled case. In this section the maximum beam size will be computed when the  $b_n, c_n$  and  $\Delta\nu$  are corrected. It will be shown that the beam size distortion is also largely corrected, although in one case it may be increased by a factor which is  $\leq 1.414$ .

The particle motion can be written in terms of the eigenfunctions  $x_1, x_2, x_3, x_4$  as

$$x = a_1 x_1 + a_2 x_2 + a_3 x_3 + a_4 x_4 \quad (4.1)$$

where

$$x = \begin{bmatrix} x \\ p_x \\ y \\ p_y \end{bmatrix} \quad (4.2)$$

$$x_2 = x_1^*, x_4 = x_3^* \text{ and } \tilde{x}_i^* S x_i = 2i, x_i^* S x_j = 0, i \neq j$$

The  $a_i$  can then be found

$$\begin{aligned} a_1 &= (1/2i) \tilde{x}_1^* S x \\ a_3 &= (1/2i) \tilde{x}_3^* S x \end{aligned} \quad (4.3)$$

and thus

$$|a_1| = \frac{1}{2} \epsilon_1^{1/2}, \quad |a_3| = \frac{1}{2} \epsilon_2^{1/2} \quad (4.4)$$

If the  $b_n, c_n$  and  $\Delta\nu$  have been corrected so that the eigenfunctions are given by Eq. (3.11), then  $x$  and  $y$  of the eigenfunctions are given by

$$\begin{aligned} x &= \beta_x^{1/2} A \exp [i (\nu_x \theta_x)] \\ y &= \beta_y^{1/2} B \exp [i \nu_y \theta_y]. \end{aligned} \quad (4.5)$$

$x$  and  $y$  are then given by

$$\begin{aligned} x &= (\beta_x \epsilon_1)^{\frac{1}{2}} |A_1| \cos [\nu_1 \theta_x + \delta_1] + (\beta_x \epsilon_2)^{\frac{1}{2}} |A_2| \cos [(\nu_2 + p) \theta_x + \delta_2] \\ y &= (\beta_y \epsilon_1)^{\frac{1}{2}} |B_1| \cos [(\nu_1 - p) \theta_y + \delta_1] + (\beta_y \epsilon_2)^{\frac{1}{2}} |B_2| \cos [\nu_2 \theta_y + \delta_2] \end{aligned} \quad (4.6)$$

$\delta_1, \delta_2$  are the phases of  $a_1$  and  $a_3$ .

$x_{\max}$  and  $y_{\max}$  are then

$$\begin{aligned} x_{\max} &= (\beta_x \epsilon_1)^{\frac{1}{2}} |A_1| + (\beta_x \epsilon_2)^{\frac{1}{2}} |A_2| \\ y_{\max} &= (\beta_y \epsilon_1)^{\frac{1}{2}} |B_1| + (\beta_y \epsilon_2)^{\frac{1}{2}} |B_2| \end{aligned} \quad (4.7)$$

As was done for the emittance, we will find  $x_{\max}$  for the two cases given by Eq. (3.13).

For case 1,  $|\Delta\nu| \ll |\nu_x - \nu_y - p|$  then

$$\begin{aligned} |A_1| &= 1, & |B_1| &= 0 \\ |A_2| &= 0, & |B_2| &= 1 \\ \epsilon_1 &= \epsilon_x, & \epsilon_2 &= \epsilon_y \end{aligned} \quad (4.8)$$

Then Eq. (4.7) gives

$$\begin{aligned} x_{\max} &= \sqrt{\beta_x \epsilon_x} \\ y_{\max} &= \sqrt{\beta_y \epsilon_y} \end{aligned} \quad (4.9)$$

and there is no growth in beam size.

For case 2,  $|\nu_x - \nu_y - p| \ll |\Delta\nu|$  then

$$\begin{aligned} |A_1| &= |B_1| = 1/\sqrt{2} \\ |A_2| &= |B_2| = 1/\sqrt{2} \\ \epsilon_t &= \epsilon_1 + \epsilon_2 = \epsilon_x + \epsilon_y \end{aligned} \quad (4.10)$$

Eq. (4.6) then gives for  $x_{\max}, y_{\max}$

$$\begin{aligned} x_{\max} &= (\beta_x/2)^{\frac{1}{2}} \left( \epsilon_1^{\frac{1}{2}} + \epsilon_2^{\frac{1}{2}} \right) \\ y_{\max} &= (\beta_y/2)^{\frac{1}{2}} \left( \epsilon_1^{\frac{1}{2}} + \epsilon_2^{\frac{1}{2}} \right) \end{aligned} \quad (4.11)$$

Since  $\epsilon_2 = \epsilon_t - \epsilon_1$ , then as one varies  $\epsilon_1$  from  $\epsilon_1 = 0$  to  $\epsilon_1 = \epsilon_t$ ,  $x_{\max}$  reaches its maximum at  $\epsilon_1 = \epsilon_2 = \epsilon_t/2$ . Thus

$$\begin{aligned} x_{\max} &\leq (\beta_x (\epsilon_x + \epsilon_y))^{\frac{1}{2}} \\ y_{\max} &\leq (\beta_y (\epsilon_x + \epsilon_y))^{\frac{1}{2}} \end{aligned} \quad (4.12)$$

For the case where  $\epsilon_x = \epsilon_y$ , then  $x_{\max} \leq 1.4 (\beta_x \epsilon_x)^{\frac{1}{2}}$  and the coupling may increase  $x_{\max}$  by the factor 1.414. So in case (2)  $|\nu_x - \nu_y - p| \ll |\Delta\nu|$ , then when the  $b_n, c_n$  and  $\Delta\nu$  are corrected one may still have a beam size increase of the factor 1.414.

## 5. References

1. D. Edwards and L. Teng, IEEE 1973 PAC, p. 885 (1973).
2. A. Piwinski, DESY 90-113 (1990).
3. E.D. Courant and H. Snyder, Ann. Phys. **3**, 1 (1958).
4. G. Parzen, BNL Report AD/AP-49 (1992).