



BNL-104549-2014-TECH

AGS/AD/Tech Note No. 118;BNL-104549-2014-IR

THE TRANSVERSE COHERENCE DAMPERS

E. C. Raka

March 1976

Collider Accelerator Department
Brookhaven National Laboratory

U.S. Department of Energy

USDOE Office of Science (SC)

Notice: This technical note has been authored by employees of Brookhaven Science Associates, LLC under Contract No.E(30-1)-16 with the U.S. Department of Energy. The publisher by accepting the technical note for publication acknowledges that the United States Government retains a non-exclusive, paid-up, irrevocable, world-wide license to publish or reproduce the published form of this technical note, or allow others to do so, for United States Government purposes.

DISCLAIMER

This report was prepared as an account of work sponsored by an agency of the United States Government. Neither the United States Government nor any agency thereof, nor any of their employees, nor any of their contractors, subcontractors, or their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, completeness, or any third party's use or the results of such use of any information, apparatus, product, or process disclosed, or represents that its use would not infringe privately owned rights. Reference herein to any specific commercial product, process, or service by trade name, trademark, manufacturer, or otherwise, does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States Government or any agency thereof or its contractors or subcontractors. The views and opinions of authors expressed herein do not necessarily state or reflect those of the United States Government or any agency thereof.

Accelerator Department
BROOKHAVEN NATIONAL LABORATORY
Associated Universities, Inc.
Upton, New York

AGS DIVISION TECHNICAL NOTE

No. 118

E.C. Raka
March 3, 1976

THE TRANSVERSE COHERENCE DAMPERS

Introduction

Since March 1973 a feedback damping system has been used to control the vertical transverse instability present, below the transition energy of ≈ 8 GeV, during normal operation of the Brookhaven AGS at intensities greater than $\approx 4.5 \times 10^{12}$ /pulse. Approximately one year later provision was also made to damp an incipient instability in the horizontal plane which could arise at somewhat higher intensities. Both systems are essential to the operation of the AGS at high intensities i.e. $> 6 \times 10^{12}$ /pulse.

The present damping systems are based on a prototype which was used in early studies of the transverse instability.¹ Details of the design requirements are given in Ref. 1. To summarize the basic principle, one senses the motion of the center of charge of the beam by means of pick-up electrodes. This signal is filtered, amplified, and transmitted to a pair of deflecting coils located $\approx 1/4$ of a betatron wavelength downstream. The system is narrow band in that it can damp only the lower order coupled bunch modes; $n = 9, 8, 10$ i.e. those modes where the bunched beam acts as a dc beam.

For these modes the spectrum of the difference signal will contain the frequencies $(n-\nu)f_0$, $Mf_0 \pm (n-\nu)f_0$, $2Mf_0 \pm (n-\nu)f_0$ etc., where M is the number of bunches and f_0 the rotation frequency. If we assume that the resistive wall impedance is responsible for the instability the lowest frequency line will predominate.² Clearly, however, significant antidamping at the other frequencies should be avoided. If the bunches are unequal in intensity, then some signal at $mf_0 \pm (n-\nu)f_0$ where $m = 1$ to $(M-1)$, $(M+1)$ to $(2M-1)$, etc., will also be present. These lines will also appear if

any of the bunches oscillate independently. However, the relative amplitudes would be larger in this case. Damping of these oscillations will in general not occur since the narrow band system sees only the average position of all the bunches and hence the phase of the resultant signal will not be correct.

Description of the System

A block diagram of the feedback damping system is shown in Fig. 1. The cathode followers are mounted on the vacuum chamber and consist of a 6922 (E88CC) connected in parallel whose input capacity of $\approx 11 \mu\text{f}$ in series with the 40 K resistors forms the single filter in the loop. This attenuates the high frequency components of the bunched signal which would otherwise over-drive the tubes at high beam intensities. A 3 db point of $\approx 380 \text{ kc}$ provides adequate margin for satisfactory damping of the n=9 mode for all reasonable values of tune below the transition energy.

The difference amplifier is a $\mu\text{A}733\text{IC}$ operated at a single ended gain of ≈ 28 . An Analogue Devices 46J or K is used as a summing amplifier line driver so that the overall gain is ≈ 55 to $> 12 \text{ MHz}$. The coil driver consists of two 8233 tubes in parallel giving a current gain of $\approx 82 \text{ mA/V}$ to well beyond the self-resonant frequency of the coils ($\approx 4.4 \text{ MHz}$).

In the spring of 1974 a new coil assembly was installed providing a two-turn horizontal as well as a two-turn vertical coil. The leads were brought out at the upstream end rather than downstream and the coils have the following dimensions. Both are 92 in. long with the vertical wires separated by 4 in. and located at $\pm 1.25 \text{ in.}$ about the chamber center while the horizontal wires are separated by 4.25 in. and are located at $\pm 2 \text{ in.}$ above and below the chamber center. On the median plane then the vertical coils has a strength of $\approx .11 \text{ gauss/amp}$ and hence it can produce a transverse $\Delta p = B\ell = .77 \times 10^{-5} \text{ BeV/c amp}$. The horizontal coil has a field that varies somewhat more with the radial position of the beam. We take the average strengths over a 2.5 in. aperture as .0767 gauss/amp giving a $\Delta p = .54 \times 10^{-5} \text{ BeV/c amp}$.

A differential gain adjustment is provided by employing a FET in series with a 1K resistor to form a variable attenuator at each input to the 733. An operational amplifier provides the necessary inversion so that a single input can vary the gain in opposite directions in each channel. This is used to balance out the signal due to any orbit errors.

at the PUE location. For the horizontal, of course, a null can only be obtained for one position of the beam. In principle the gain could be programmed as a function of beam position but this has not been necessary so far.

Initially the pick-up electrodes were located at straight section B-3 and the deflecting coils at B-10. Since injection is at A-20 the radiation was rather high in the vicinity of the difference amplifier which was located on the AGS floor next to the main magnet girder. In January 1975 the entire system was moved to A-3 and A-10 where the radiation is minimal. Since that time no component failure has occurred as opposed to at least one definite malfunctioning of a 733 in the old location.

System Performance

The damping rate of the feedback loop can be written as¹

$$D = \frac{\Delta p}{p} \frac{v \sin [n\theta - (n-v)\omega_0 T]}{4\pi v \bar{y}_0 (y-T)} \quad (1)$$

where Δp is the transverse momentum imparted by the coils; p the beam momentum; v its velocity, ν the betatron wave number, ω_0 the beam angular frequency, θ the angular separation between the pick-up electrodes and the deflecting coils; T the signal time delay between these two points and $\bar{y}_0(t-T)$ the average position of the beam as seen by the electrodes. One can also define $\alpha = 2\pi D/\omega_0$ such that any initial displacement of the beam will decay like $e^{-\alpha N}$ where N is the number of revolutions after the perturbation ($|\alpha| \ll 1$). Then we can write in view of the above

$$\alpha = \frac{\Delta p}{p} \frac{\bar{\beta}}{2} \frac{\sin [n\theta - (n-v)\omega_0 T]}{\bar{y}_0(t-T)} \quad (1a)$$

where $\bar{\beta} = R/v$.

In the above equations we have written \bar{y}_0 to imply that the beam position is measured at $\beta = \bar{\beta}$ in an AG machine. If this is not true as in the present case we can write $\bar{y}_0 = \sqrt{\beta/\beta_0} y_0$ where β_0 is the value of β at the PUE location. Since the coil is located about the center of a 10 ft straight section where $\beta = \bar{\beta}$ we can write (1a) as

$$\alpha = \frac{\Delta p}{p} \frac{\sqrt{\beta/\beta_0}}{2} \frac{\sin [n\theta - (n-v)\omega_0 T]}{y_0(t-T)} \quad (1b)$$

Now $\Delta p = Ky_0$ where K depends upon the pick-up electrode sensitivity, the beam intensity, and the gain characteristics of the electronics including the deflection coils. The damping rate D is then given by

$$D = \sqrt{\frac{\beta_0}{\beta}} \frac{K}{4\pi p v} v \sin \varphi = \frac{K \omega_\infty \sqrt{\beta \beta_0} \sin \varphi}{4\pi \gamma m_0 c} \quad (2)$$

where $\varphi = [n\theta - (n-v)\omega_0 T]$ and $\omega_\infty = c/R$. Also we can write

$$\alpha = \frac{\sqrt{\beta_0 \beta_0}}{2p} K \sin \varphi \quad (2a)$$

for the damping rate per revolution. The maximum damping rate ($\sin \varphi \approx 1$) thus depends upon K for a given beam momentum p . If we ignore for the moment the frequency characteristics of the filter then K is just the gain from pick-up electrodes to deflection coils in units of momentum/displacement. We have for the vertical PUE differential sensitivity $\approx .08$ volts/cm per 10^{12} protons and for the horizontal $\approx .096$ volts/cm 10^{12} . Thus

$$K_H = \frac{.096 \text{ V} \times .65 \times 55}{\text{cm} \times 10^{12} \text{ protons}} \times .08 \frac{\text{amp}}{\text{volt}} \times .54 \times 10^{-5} \frac{\text{BeV}}{\text{c-amp}} = \frac{152 \times 10^{-8} \text{ BeV}}{\text{cm} \times 10^{12} \text{ c}}$$

where .65 is the gain of the cathode follower into 180Ω and

$$K_V = .08 \frac{\text{volt}}{\text{cm} \times 10^{12}} \times .65 \times 55 \times .082 \frac{\text{amp}}{\text{volt}} \times .77 \times 10^{-5} \frac{\text{BeV}}{\text{amp} \cdot \text{c}} = \frac{181 \times 10^{-8} \text{ BeV}}{\text{cm} \times 10^{12} \text{ c}}$$

The maximum damping rate at $\gamma = 1.7$ and 5×10^{12} protons is

$$D_V = \frac{181 \times 10^{-7}}{2 \times 1.7 \times .938 \text{ BeV/c}} \frac{\text{BeV}}{\text{c} \cdot \text{cm}} \cdot \frac{.371 \times 10^6}{\text{sec}} \sqrt{14.7 \cdot 21.8 \times 10^2 \text{ cm}} = 3769 \text{ sec}^{-1}$$

and

$$D_H = \frac{152 \times 10^{-7}}{2 \times 1.7 \times .938} \times .371 \times 10^8 \sqrt{14.7 \cdot 10.5} = 2197 \text{ sec}^{-1}$$

The maximum observed vertical growth rate in the absence of damping was $\approx 500 \text{ sec}^{-1}$ at a $\gamma \approx 1.65$ and an intensity $> 6 \times 10^{12}$. Hence we have a damping rate about eight times the observed growth rate since both are

directly proportional to the beam intensity. In the horizontal plane the growth rate when the instability occurs has always been less than twice the vertical value at the same intensity. Thus the horizontal system gain is also quite adequate. These growth rates are for the $(9-\nu)$ coupled bunch mode in both cases. It should be noted however that "m" the within the bunch mode number^{2,3} is zero for the vertical oscillations and one for the horizontal due to the much larger value of $\xi = (d\nu/\nu)/(dp/p)$, the chromaticity, in the horizontal plane than in the vertical plane.

Now let us find the maximum α at injection ($\gamma = 1.213$) for 10^{13} and the $(9-\nu)$ component of any initial displacement from the equilibrium orbit. We obtain

$$\alpha = \frac{\sqrt{14.7 \times 21.8 \times 10^2 \times 181 \times 10^{-7}}}{2 \times 1.213 \times .938} = .0142 \dots$$

Thus it would take about 70 revolutions or $\approx 340 \mu\text{sec}$ for the $(9-\nu)$ component to be reduced to $1/e$ of its initial value. This is comparable to the spiraling time of the unaccelerated beam with normal B . With multi-turn injection however successive revolutions will have different phases of oscillation so there is no way that the system can adequately control injection errors. In general the system has negligible effect at injection and also at high energy (due to the $1/\gamma$ term in D or α) so it is allowed to remain sensitive at all times.

Next let us consider how φ varies in the AGS. For the A-3, A-10 spacing we have $\theta = 10.7^\circ$ and $T \approx 125$ nsec (100 for the cable and 25 for the electronics) for the feedback loop. For $\gamma = 1.7$ $f_0 \approx 300$ kc and if $\nu = 8.8$ we obtain for $n = 9$ a $\varphi = 93.6^\circ$ and 60 kc as the principal frequency in the difference signal spectrum. At $\nu = 8.6$, $\varphi = 90.9^\circ$ with 120 kc as the principal frequency and for $\nu = 8.9$, $\varphi \approx 95^\circ$ and the $n = 9$ mode frequency is 30 kc. The lowest observed coherent frequency was ≈ 13 kc for a $\gamma \approx 1.3$ and a $\nu_x \approx 8.94$ for which $\varphi \approx 96^\circ$. Thus we see that for the $n = 9$ mode there is no significant variation in φ over the normal range of AGS parameters.

In order to include the effect of the filter on the damping rate we must multiply K by $(e^{-i \arctan f/f_c} / \sqrt{1+(f/f_c)^2})^2$ where $f_c \approx 380$ kc and $f = |n-\nu|f_0$. Thus at 60 kc the gain is still maximum but the total phase is $\Phi = \varphi + \arctan(f/f_c) = 103.6^\circ$ and $\sin \Phi = .972$ so that the damping

rate is essentially the same as quoted above. For 120 kc $\Phi = 108.4^\circ$ and $\sin \Phi \cong .95$ while the gain K is reduced by about 5% and the overall damping rate by $\approx 10\%$. At these frequencies the damping coils and driver contribute no significant phase lag.

With the system as described above adequate damping was obtained at intensities up to $\approx 7 \times 10^{12}$ protons/pulse. During most of 1974 the AGS was operated with the horizontal tune above the vertical tune from injection until $\gamma \cong 1.5$. At times $\nu_x > 8.9$ and at intensities near 7×10^{12} the horizontal damper could not adequately control the resulting instability. In early 1975 the horizontal tune was lowered to ≤ 8.7 and the vertical was kept in the region of 8.8-8.9. Under these conditions the horizontal instability was essentially absent at 7×10^{12} but above this value occasional blow-up in the vertical plane could occur. This was suppressed by programming the vertical sextupoles at about 6 A starting 10 to 15 msec after injection. With this combination intensities of 9.8×10^{12} were reached. It should be noted that the above sextupole current doubled the vertical chromaticity at $\gamma \approx 1.5$ and decreased the horizontal value $\approx 25-30\%$. The horizontal instability returns at intensities $\approx 7 \times 10^{12}$ under these conditions but the damper was able to suppress it up to the 9.8×10^{12} intensity peak achieved prior to February 19, 1976.

Observations made on the nature of the vertical blow-up during the rare pulses when it occurred indicated that a significant signal at the $(9-\nu_y)$ frequency was present which grew with the instability. This could also be seen on the envelope of an rf difference signal showing the individual bunches. It should be remarked that with the damper turned off, coherence would occur on every pulse with a faster growth rate and starting closer to the injection energy. This behavior along with the higher intensity needed for the growth to occur suggested that it might be due to the damping system itself. See Appendix C for discussion of this point. In order to test this possibility the response of the loop was modified so as to give a 12 db per octave roll-off for frequencies ≈ 25 kc or greater. The sense of the feedback was reversed³ because now $\Phi \cong \pi + \phi$ and the overall gain was changed so that $|K|$ was the same as before at ≈ 42.7 kc. Details of the change are described in Appendix A.

In late January 1976 this modification was tested in the vertical loop. It was immediately apparent that the performance had been improved.

since it was possible to operate at intensities $> 8 \times 10^{12}$ without the sextupole program and without any vertical blow up. Subsequently, an intensity of 1.03×10^{13} was reached in early February 1976 again without the need of sextupoles.

Conclusion

By putting in the 12 db/octave filter the gain for higher order modes is reduced so drastically that any damping or antidamping action by the system is negligible. Thus as the AGS intensity increases one still might expect growth in one of the higher order coupled bunch modes or in case of unequal bunch population, individual bunch instabilities.^{2,7}

If such instabilities do eventually occur at intensities $> 10^{13}$ then some nominal control is possible using the sextupoles to vary the chromaticities, but nothing further can be expected from the present damping system. An entirely new system with wide band electronics operating on the individual bunches would have to be employed.

In closing I should acknowledge the invaluable assistance of Mr. E. Gill in carrying out this work.

References

1. E. Raka, "Damping Coherent Oscillations in the AGS", IEEE Trans. Nucl. Sci. NS-14, No. 3, 1091 (1967).
2. F. Sacherer, "Transverse Bunched Beam Instabilities", Proc. 9th Int. Accel. Conf., p.347 (1974).
3. G.H. Reese, "Servo Theory for the Control of Coherent Betatron Oscillations in Nimrod", NIRL/R/99 (1965).
4. E. Courant, H. Snyder, "Theory of the Alternating Gradient Synchrotron", Annals of Physics, Vol. 3, No. 1 (1958).

ECR/lsk

Distr: Dept. Admin.
MCR Operators
Oper. Coord.
Accel. Dept. Physicists

Appendix A

The loop response was modified as follows. For the input RC to the cathode followers R was changed to 401 KΩ and C to 68 μμ plus the ≈ 11 μμf shunt capacity. Thus $\omega C_i R_i = 1$ for 5 Kc and it was decided to control the low frequency response by making the output coupling capacitor driving the terminated 180 Ω cable .176 μμf. This also results in $\omega C_c R_c = 1$ at 5 Kc (all other low frequency time constants being $\gg 31.7 \mu\text{sec}$). The response then can be written as

$$\frac{Ae^{j\theta} (f/f_c)}{1 + (f/f_c)^2}$$

where $f_c = 5 \text{ Kc}$ and $\theta = \pi/2 - 2 \arctan (f/f_c)$ where negative θ represents a phase lag and $A/2$ is the gain at f_c ($\approx .36$). Next the $\mu\text{A} 733$ gain was increased to the maximum possible i.e. ≈ 180 single ended. Then the 46 J was used as a combination differentiator, integrator, summing amplifier. If we call $R_D C_D$ the differentiation elements and $R_i C_i$ the integration elements then they were chosen so that $R_D C_i = R_i C_D = \tau_c = 31.7 \mu\text{sec}$ with $R_D/R_i = 10$ and $R_D = 39 \text{ K}$. With $C_D = 8200 \mu\mu\text{f}$ and $C_i = 820 \mu\mu\text{f}$ $f_c = 1/2\pi\tau_c \approx 5 \text{ Kc}$ we have for the gain of this stage

$$\frac{2 \times 10 e^{j\theta} (f/f_c)}{1 + (f/f_c)^2}$$

where θ is the same as above and the factor of two comes from summing both outputs of the 733. Thus the total gain is \approx

$$\frac{2590 e^{j2\theta} (f/f_c)}{[1 + (f/f_c)^2]^2}$$

which at 42 Kc is ≈ 35.7 i.e. the nominal low frequency gain of the previous configuration. At this frequency $2\theta = 152.8^\circ$ of lag so for the in mode $\phi = 94.4^\circ$ and $\Phi = -180^\circ + 152.8^\circ + 94.4^\circ = -67.2^\circ$ where we subtracted 180° because the sense of the feedback was reversed. Thus the damping rate for 42 Kc is $\approx 92\%$ of the maximum values calculated earlier. It is obvious

how the gain scales with frequency but let us compare the value at 3.6 MHz with the earlier configuration. We obtain $\approx .005$ for this combination vs 3.75 for the previous filter. Due to stray capacities this large a reduction is not achieved but it is still greater than two orders of magnitude.

As a final example, let us calculate the damping rate at $f = 13$ Kc for the $n = 9$ mode. The gain is 290 and $2\theta = 95.85^\circ$ so that $\Phi = 12.15^\circ$ and $\sin \Phi = .21$ so the damping rate is $.21 \times 290/35.7 \cong 1.71$ larger than the maximum calculated earlier. Because of the higher gain of this system in the region around 5 Kc, care must be taken to minimize noise pick-up or generation (by the 6922 tubes) at these frequencies.

Finally we should remark that because the input RC to the cathode followers was increased by a factor of ≈ 70 the high frequency components of the input signal are greatly attenuated so there should be no chance of overdriving them at intensities much larger than 10^{13} . This reduction is so great that even though the 733 gain was increased somewhat there seems to be no further need for the variable attenuators at its input since any difference signal due to an orbit error will be negligible. At present the above modification has been installed in both the vertical and horizontal damping loops.

Appendix B

Orbit Bump Due to Damping Coils:

There is always a dc current flowing in the two-turn deflecting coils of ≈ 130 mA. The resulting orbit deflection is given by⁴

$$y(\varphi) = \frac{\beta^{\frac{1}{2}} \nu}{2 \sin \pi \nu} \int_{\varphi}^{\varphi+2\pi} f(\Psi) \cos \nu (\pi + \varphi - \Psi) d\Psi$$

where $\varphi = \int ds / \beta \nu$. For our two-turn coil of length ℓ centered about $\Psi = 0$ we can write

$$y(\varphi) = \frac{\beta^{\frac{1}{2}}(\varphi)}{2 \sin \pi \nu} \frac{\Delta B}{B_0} \int_{-\ell/2}^{\ell/2} \cos / (\pi + \varphi) \beta^{\frac{1}{2}} ds$$

where B_0 is the momentum of the protons and ΔB the field due to the coil. At 200 MeV $B_0 = 2.15 \times 10^3$ Kg/cm and for the vertical deflecting coil $\ell = 233$ cm. $\Delta B = .11$ gauss/amp and for β we take the average value at the center of the coil $\bar{\beta} = R/\nu$ so that

$$y(\varphi) = \frac{\sqrt{\beta(\varphi) \bar{\beta}}}{2 \sin \pi \nu} \cos \nu (\pi + \varphi) 1.55 \times 10^{-6}$$

If $\nu \varphi \approx \pi/2$ then we can be close to a $\beta_{\max} \approx 22$ meters vertically and we obtain

$$y_{\max} \approx -\frac{1}{2} \sqrt{22 \times 15} \times 1.55 \times 10^{-4} \text{ cm} = -1.4 \times 10^{-3} \text{ cm}$$

and, of course, somewhat less for the horizontal coil.

Appendix C

As mentioned earlier, when a bunched beam oscillates in the coupled bunch mode n there will be present in the difference signal spectrum the frequencies $(n-\nu) f_0$, $[M \pm (n-\nu)] f_0$, $[2M \pm (n-\nu)] f_0$, etc. depending upon the bunch width. The relative amplitudes of these lines will also depend upon "m", the within the bunch mode number, and the frequency $f_{\xi} = \xi \nu f_0 / \eta$ where $\eta = \gamma_{tr}^{-2} - \gamma^{-2}$. We should also note that these frequencies are to be considered negative or positive depending upon whether the wave velocity $R[M \pm (n-\nu)] \omega_0 / [M \pm n]$ etc. is less than or greater than the particle velocity $\omega_0 R$. For M bunches there are only M distinct coupled bunch modes $n = 0, 1, (M-1)$ and $2\pi n/M$ is the phase difference between bunches.

Now, so far we have considered only the loop response at the lowest frequency line for the $n = 9$ coupled bunch mode. The damping rates calculated previously are only valid for a DC beam or one that is not only tightly bunched and for which $\xi \approx 0$. Neither of these conditions prevail in the AGS particularly in the region of $\gamma = 1.5 - 1.7$ where vertical growth could occur with the damper active. In order to calculate the damping rate for the bunched beam we need the loop response at $(21-\nu)f_0$, $(3+\nu)f_0$, $(33-\nu)f_0$ and $(15+\nu)f_0$ since these frequencies will be present in the spectrum of the difference signal for the "m=0" within the bunch mode. Assuming as before that $\gamma = 1.7$ and $\nu = 8.8$ we obtain for $f = 12.2 f_0 = 3.66$ MHz a $\bar{\theta} = 224.7 + 83.9 + 11 - 159.3 = 160.3^\circ$. Since $\sin \bar{\theta} = .337$ and the filter gain is 0.1 at this frequency the nominal damping rate is .039 that of the maximum low frequency value. For $n = 3$, $f = 11.8 f_0 = 3.54$ MHz and $\bar{\theta} = 32.1 + 84 + 11 - 162 = -34.9^\circ$ and $\sin \bar{\theta} = -.572$ which means antidamping. The filter gain is .11 here so the rate is -.063 times the low frequency value. We have included here 11° of lag due to the coil and driver in calculating the $\bar{\theta}$'s. The system response at 23.8 & $24.2 f_0$ is negligible since in addition to the factor of two reduction from the filter these frequencies are well above the self resonant frequency of the coil (≈ 4.4 MHz) and most of the current will be shunted by the stray capacity.

In calculating the effective damping rate we proceed in a manner similar to that used in Ref. 2 for obtaining the growth rate for a bunched beam due to the resistive wall impedance. That is we sum the loop response over the bunch spectrum with the value at each line weighted by the square of the amplitude (hence the energy)

$$D_o = \frac{\sum_n D(f_n) h_o(f_n - f_g)}{\sum_n h_o(f_n - f_g)}$$

where $h_o(f) = |\tilde{p}_o(f)|^2$ and \tilde{p}_o is the Fourier transform of the center of charge motion for the $m = 0$ mode. It can be written as

$$\tilde{p}_o = \frac{2 \cos(\pi \ell \omega / 2)}{[1 - (\pi \ell \omega / \pi)^2]}$$

where ℓ is the bunch length. The frequencies f_n are just the five lines mentioned above where those for $n = 9, 21, 33$ are considered negative in evaluating h_o and those for $n = 3, 15$ are considered positive. With $\ell \approx .140 \mu\text{sec}$, $f_g \approx 3.63 \text{ MHz}$ and $f_o = 300 \text{ kc}$ we obtain for $\sum h_o \approx 9.88$ and for the numerator $D_v (2.5 - 4 \times .063 + .44 \times .034) = 2.26 D_v$ where D_v is the maximum low frequency damping rate calculated previously. Hence the effective damping rate of the loop for the $n = 9$ coupled bunch mode ($m = 0$) for the parameters chosen is $\approx .23 D_v$ or less than twice the observed growth rate for the gain quoted above. We see that the antidamping for the $n = 3$ line results in only a 10% reduction of the total. This rate will not be significantly different at lower values of γ where a slightly larger value is expected.

Since the system functioned satisfactorily below 7×10^{12} protons/pulse and its gain is \sim to intensity as is the resistive wall growth rate, one cannot explain the anomalous growth of the $n = 9$ coupled bunch mode in the range of $\gamma = 1.5 - 1.7$ if the threshold for the instability at these energies is the same for the range of $\gamma = 1.25 - 1.5$. However, if this is not the case, then the slight expected difference in damping rate noted above when the safety margin is less than two might be an explanation for the occasional growth of this mode. In order to settle this question, a series of growth rate and threshold measurements would have to be made by turning the damper off at different values of γ .

Finally, it should be remarked that the increased vertical chromaticity produced by the vertical sextupoles was such as to reduce the growth rate for the $m = 0$ mode. This, of course, increases f_{ξ} and hence reduces further the effective damping rate. The loop response modifications discussed in Appendix A leaves only one term in the sum of the numerator for D_0 but makes its magnitude much more dependent upon the value of $(9-\eta) f_0$.

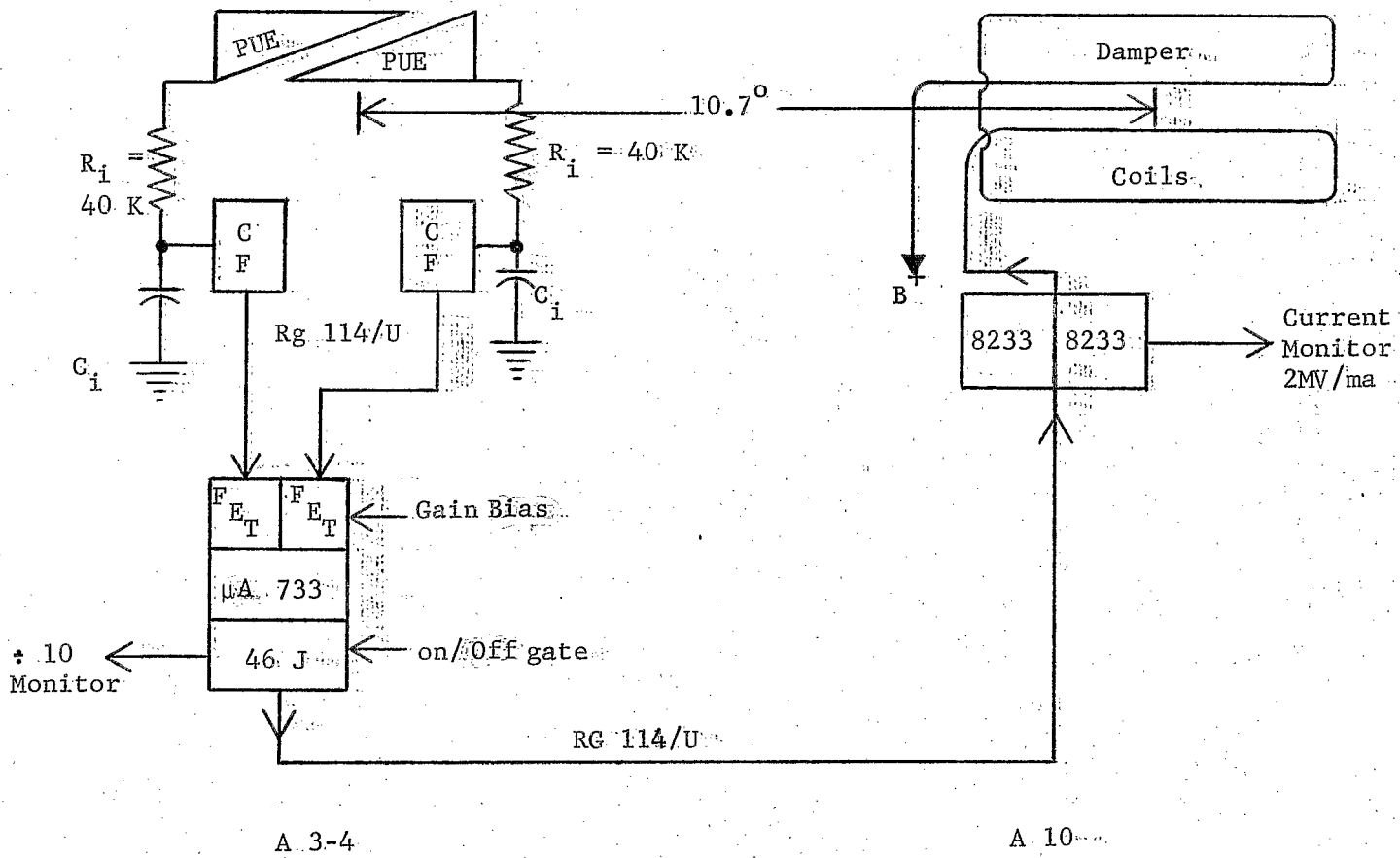


Figure 1