

Magnetic Field Calculation of Helical Dipole Coils

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1. Introduction

The magnetic field of helical coils has been examined by several authors [1,2,3,4,5]. The aim of this paper is to give the expression of multipole of helical magnets for the coil design. In addition, the comparison between the analytical and numerical calculations is presented for the simple helical dipole coils.

2. The Magnetic Field of Helical Coils

The treatment of this section follows Morgan's [4] most closely. 3-dimensional Laplace's equation in circular cylindrical coordinates is as follows,

$$\nabla^2 \phi = \frac{\partial^2 \phi}{\partial r^2} + \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} + \frac{\partial^2 \phi}{\partial z^2} = 0 \quad (1)$$

Since the winding is periodic in z with a pitch length L , the general solution is,

$$\phi_h(r, \theta, z) = \sum_{n=1}^{\infty} (c'_n I_n(nkr) + d'_n K_n(nkr)) \{a'_n \cos(n(\theta - kz)) + b'_n \sin(n(\theta - kz))\} \quad (2)$$

where $k = 2\pi/L$, $I_n(nkr)$ is the modified Bessel function of the first kind of order n , and $K_n(nkr)$ is the modified Bessel function of the second kind of order n . Of the two, $I_n(nkr)$ is finite at $r=0$ and increases to the infinity with radius, and $K_n(nkr)$ is infinite at $r=0$ and decreases with radius. Then, the solution nearer the axis than conductors has the form with $d'_n = 0$, and the solution outside the conductors has the form with $c'_n = 0$.

Considering the form of the ascending series of $I_n(nkr)$,

$$I_n(nkr) = \sum_{j=0}^{\infty} \frac{1}{j! (n+j)!} \left(\frac{nkr}{2} \right)^{2j+n} \quad (3)$$

For the scalar potential nearer the axis than conductors of helical coil, we can define the following form,

$$\phi_h(r, \theta, z) = -B_{ref} r_0 \sum_{n=1}^{\infty} (n-1)! \left[\frac{2}{nkr_0} \right]^n I_n(nkr) \{ -a_n \cos(n(\theta - kz)) + b_n \sin(n(\theta - kz)) \} \quad (4)$$

where we follow the European Definition for the multipole coefficients, a_n, b_n , which is different from the American Definition. The relationships between these coefficients are,

a_n (European) = $-a_{n-1}$ (American) : skew multipole coefficient of the $2n$ -pole

b_n (European) = b_{n-1} (American) : normal multipole coefficient of the $2n$ -pole

The asymptotic form for this scalar potential as $k \rightarrow 0$ ($L \rightarrow \infty$) is,

$$\lim_{k \rightarrow 0} [\phi_h(r, \theta, z)] = \phi_{2d}(r, \theta) \quad (5)$$

$$\phi_{2d}(r, \theta) = -B_{ref} r_0 \sum_{n=1}^{\infty} \frac{1}{n} \left(\frac{r}{r_0} \right)^n (-a_n \cos(n\theta) + b_n \sin(n\theta)) \quad (6)$$

where $\phi_{2d}(r, \theta)$ is the scalar potential nearer the axis than conductors of 2-dimensional non-spiral coil.

From this scalar potential, the interior magnetic field of helical coil is,

$$\begin{cases} B_r(r, \theta, z) = -\frac{\partial \phi_h}{\partial r} = B_{ref} r_0 \sum_{n=1}^{\infty} n! \left[\frac{2}{n k r_0} \right]^n k I'_n(n k r) \left\{ -a_n \cos(n(\theta - k z)) + b_n \sin(n(\theta - k z)) \right\} \\ B_\theta(r, \theta, z) = -\frac{1}{r} \frac{\partial \phi_h}{\partial \theta} = B_{ref} r_0 \sum_{n=1}^{\infty} n! \left[\frac{2}{n k r_0} \right]^n \frac{I_n(n k r)}{r} \left\{ a_n \sin(n(\theta - k z)) + b_n \cos(n(\theta - k z)) \right\} \\ B_z(r, \theta, z) = -\frac{\partial \phi_h}{\partial z} = B_{ref} r_0 \sum_{n=1}^{\infty} (-k) n! \left[\frac{2}{n k r_0} \right]^n I_n(n k r) \left\{ a_n \sin(n(\theta - k z)) + b_n \cos(n(\theta - k z)) \right\} \end{cases} \quad (7)$$

In this case,

$$B_y(r=0, \theta=0, z=0) = B_\theta(r=0, \theta=0, z=0) = B_{ref} b_1 \quad (8)$$

Then, $B_y(0,0,0)=B_{ref}$ with the definition of $b_1=1$. The above expressions are same with those given in the Appendix of a paper by J. Blewett et al., with the condition that $B_{ref}=B_0$, $b_1=1$, and other multipole coefficients are zero. On the both cases of helical and 2 dimensional non-spiral dipole coils, B_{ref} are the central dipole field, which are different. Similarly, the multipole coefficients, a_n , b_n , are different for both coils. However, the above expressions are beneficial for the comparison.

On the situation that the currents are confined to lie on the surface of a circular cylinder of radius a , the surface currents will give rise to a discontinuity of the components B_z , B_θ , at the interface of radius a , but the radial component B_r will pass continuously through this interface. Then, the exterior magnetic field of helical coil is,

$$\begin{cases} B_r(r, \theta, z) = B_{ref} r_0 \sum_{n=1}^{\infty} n! \left[\frac{2}{n k r_0} \right]^n k \frac{I'_n(n k a)}{K'_n(n k a)} K'_n(n k r) \left\{ -a_n \cos(n(\theta - k z)) + b_n \sin(n(\theta - k z)) \right\} \\ B_\theta(r, \theta, z) = B_{ref} r_0 \sum_{n=1}^{\infty} n! \left[\frac{2}{n k r_0} \right]^n \frac{I'_n(n k a)}{K'_n(n k a)} \frac{K_n(n k r)}{r} \left\{ a_n \sin(n(\theta - k z)) + b_n \cos(n(\theta - k z)) \right\} \\ B_z(r, \theta, z) = B_{ref} r_0 \sum_{n=1}^{\infty} (-k) n! \left[\frac{2}{n k r_0} \right]^n \frac{I'_n(n k a)}{K'_n(n k a)} K_n(n k r) \left\{ a_n \sin(n(\theta - k z)) + b_n \cos(n(\theta - k z)) \right\} \end{cases} \quad (9)$$

The values of B_{ref} , a_n , b_n can be determined for the current element. Applying Ampere's law for a closed path in $z=\text{constant}$ plane enclosing the current element at radius a , we can obtain the following equation,

$$(B_{\theta, out} - B_{\theta, in})|_{r=a} = \mu_0 j_z \Delta a \quad (10)$$

Then, the normal multipoles B_n and the skew multipoles A_n , in addition, the normal multipole coefficients b_n and the skew multipole coefficient a_n are obtained with the Wronskian relation,

$$I_n(n k a) K'_n(n k a) - I'_n(n k a) K_n(n k a) = -\frac{1}{n k a} \quad (11)$$

as follows,

$$\begin{cases} A_n = B_{ref} a_n = \frac{\mu_0}{\pi} \frac{1}{2^n(n-1)! r_0} k a^2 (n k r_0)^n K'_n(n k a) \Delta a \int j_z \sin(n(\theta - k z)) d\theta \\ B_n = B_{ref} b_n = \frac{\mu_0}{\pi} \frac{1}{2^n(n-1)! r_0} k a^2 (n k r_0)^n K'_n(n k a) \Delta a \int j_z \cos(n(\theta - k z)) d\theta \end{cases} \quad (12)$$

With the definition of $b_1=1$, $B_{ref} = B_1$

Then, for four helical line currents with dipole symmetry,

helical line current #1 : current +I , radius a, angle ϕ ,
 helical line current #2 : current - I , radius a, angle $\pi - \phi$,
 helical line current #3 : current - I , radius a, angle $\pi + \phi$,
 helical line current #4 : current +I , radius a, angle $-\phi$,

Bref, a_n , b_n at $z=0$, are calculated as follows,

$$\begin{cases} A_n = B_{ref} a_n = \frac{\mu_0}{\pi} \frac{1}{2^n(n-1)! r_0} k a^2 (n k r_0)^n K'_n(n k a) \Delta a \sum_{i=1}^4 \frac{I_i}{a \Delta \theta \Delta a} \sin n\phi_i \Delta \theta \\ B_n = B_{ref} b_n = \frac{\mu_0}{\pi} \frac{1}{2^n(n-1)! r_0} k a^2 (n k r_0)^n K'_n(n k a) \Delta a \sum_{i=1}^4 \frac{I_i}{a \Delta \theta \Delta a} \cos n\phi_i \Delta \theta \end{cases} \quad (13)$$

where the following relation between the current and the current density is used with the real cross section S of the conductor and the projected cross section S_z of the conductor on the $z=\text{constant}$ plane.

$$j = \frac{I}{S} \quad (14)$$

$$S = S_z \sin \alpha \quad (15)$$

where α is the pitch of the winding so that the relationships between the above-mentioned k and α are $k = 1/(a \tan \alpha)$. Then,

$$j_z = j \sin \alpha = \frac{I}{S} \sin \alpha = \frac{I}{S_z} \quad (16)$$

Due to the dipole symmetry, $A_n=0$ for $n=1, 2, 3, 4, \dots$, and $B_n=0$ for $n=2, 4, 6, \dots$,

$$B_n = \frac{4\mu_0}{\pi} I \frac{1}{2^n(n-1)! r_0} k a (n k r_0)^n K'_n(n k a) \cos n\phi \quad (17)$$

for $n=1, 3, 5, \dots, \infty$.

With the following relation,

$$K'_n(n k a) = - \left(K_{n-1}(n k a) + \frac{1}{k a} K_n(n k a) \right) \quad (18)$$

we can obtain the following expression,

$$B_n = - \frac{4\mu_0}{\pi} I \frac{1}{2^n(n-1)! r_0} (n k r_0)^n (k a K_{n-1}(n k a) + K_n(n k a)) \cos n\phi \quad (19)$$

for $n=1, 3, 5, \dots, \infty$.

Especially, for $n=1$,

$$B_{ref} = B_1 = - \frac{2\mu_0}{\pi} I k (k a K_0(k a) + K_1(k a)) \cos \phi \quad (20)$$

Similarly, for four helical current blocks with dipole symmetry,

helical current block #1 : current density $+j_z$, radii a_1, a_2 , limiting angles ϕ_1, ϕ_2 ,

helical current block #2 : current density $-j_z$, radii a_1, a_2 , limiting angles $\pi - \phi_1, \pi - \phi_2$,

helical current block #3 : current density $-j_z$, radii a_1, a_2 , limiting angles $\pi + \phi_1, \pi + \phi_2$,

helical current block #4 : current density $+j_z$, radii a_1, a_2 , limiting angles $-\phi_1, -\phi_2$,

$B_{ref} = B_1$, b_n are calculated as follows,

$$\begin{aligned} B_n &= \frac{4\mu_0}{\pi} j_z \frac{1}{2^n(n-1)! r_0} (n k r_0)^n \frac{1}{n} (\sin n\phi_2 - \sin n\phi_1) \int_{a_1}^{a_2} k a^2 K'_n(n k a) da \\ &= -\frac{4\mu_0}{\pi} j_z \frac{1}{2^n(n-1)! r_0} (n k r_0)^n \frac{1}{n} (\sin n\phi_2 - \sin n\phi_1) \times \\ &\quad \int_{a_1}^{a_2} a (k a K_{n-1}(n k a) + K_n(n k a)) da \end{aligned} \quad (21)$$

for $n=1, 3, 5, \dots, \infty$.

$$b_n = \frac{B_n}{B_1} \quad (22)$$

3. Magnetic Field Calculation of Helical Coils with the Biot and Savart's Law

The treatment of this section follows Smythe's [6]. The conductor position (x_h, y_h, z_h) of the right-handed helical coil is described, using the angle ϕ , as follows,

$$x_h = a \cos(\phi + \phi_0), \quad y_h = a \sin(\phi + \phi_0), \quad z_h = a \phi \tan \alpha, \quad (23)$$

where a is the radius of helical coil, α is the pitch of the winding so that the relationships between the above-mentioned k and α are $k = 1/(a \tan \alpha)$. First of all, using the Biot and Savart's Law, we calculate the magnetic field of the following position (x_p, y_p, z_p) on the axis,

$$x_p = 0, \quad y_p = 0, \quad z_p = z, \quad (24)$$

The components of the vector $\vec{R} = (R_x, R_y, R_z)$ from the helical coil to the position (x_p, y_p, z_p) on the axis, and the conductor element vector $\vec{ds} = (dx_h, dy_h, dz_h)$ are,

$$\begin{cases} R_x = x_p - x_h = -a \cos(\phi + \phi_0), \\ R_y = y_p - y_h = -a \sin(\phi + \phi_0), \\ R_z = z_p - z_h = z - a \phi \tan \alpha, \end{cases} \quad (25)$$

$$\begin{cases} dx_h = -a \sin(\phi + \phi_0) d\phi, \\ dy_h = a \cos(\phi + \phi_0) d\phi, \\ dz_h = a \tan \alpha d\phi, \end{cases} \quad (26)$$

The y component B_y of the magnetic field of the right-handed helical coil with the current I are,

$$B_y(z) = \frac{\mu_0 I}{4\pi} \int \frac{[\vec{ds} \times \vec{R}]_y}{|\vec{R}|^3} = -\frac{\mu_0 I \tan \alpha}{4\pi a} \int_{\varphi_1}^{\varphi_2} \frac{\cos(\varphi + \varphi_0) + \left(\varphi - \frac{z}{a \tan \alpha}\right) \sin(\varphi + \varphi_0)}{\left\{1 + \left(\varphi - \frac{z}{a \tan \alpha}\right)^2 \tan^2 \alpha\right\}^{3/2}} d\varphi \quad (27)$$

The other components B_x , B_z are described similarly.

For the infinite long helical coil, $\phi_i = -\infty$, $\phi_f = \infty$, The y component B_y at $z=0$ is,

$$\begin{aligned} B_{y,z=0} &= -\frac{\mu_0 I \tan \alpha}{4\pi a} \int_{-\infty}^{\infty} \frac{\cos(\varphi + \varphi_0) + \varphi \sin(\varphi + \varphi_0)}{\{1 + \varphi^2 \tan^2 \alpha\}^{3/2}} d\varphi \\ &= -\frac{\mu_0 I \tan \alpha}{4\pi a} \int_{-\infty}^{\infty} \left\{ \frac{\cos \varphi + \varphi \sin \varphi}{\{1 + \varphi^2 \tan^2 \alpha\}^{3/2}} \cos \varphi_0 + \frac{-\sin \varphi + \varphi \cos \varphi}{\{1 + \varphi^2 \tan^2 \alpha\}^{3/2}} \sin \varphi_0 \right\} d\varphi \end{aligned} \quad (28)$$

where the second term of integrand vanishes, as it is odd. Then,

$$\begin{aligned} B_{y,z=0} &= -\frac{\mu_0 I \tan \alpha}{4\pi a} \cos \varphi_0 \int_{-\infty}^{\infty} \frac{\cos \varphi + \varphi \sin \varphi}{\{1 + \varphi^2 \tan^2 \alpha\}^{3/2}} d\varphi \\ &= -\frac{\mu_0 I}{2\pi a \tan \alpha} \left(\frac{1}{\tan \alpha} K_0\left(\frac{1}{\tan \alpha}\right) + K_1\left(\frac{1}{\tan \alpha}\right) \right) \cos \varphi_0 \\ &= -\frac{\mu_0 I}{2\pi} k (k a K_0(k a) + K_1(k a)) \cos \varphi_0 \end{aligned} \quad (29)$$

Then, for four helical line currents with dipole symmetry, the transverse field magnitude at axis of the helical winding B_{ref} is obtained as follows,

$$\begin{aligned} B_{ref} &= -\frac{\mu_0}{2\pi a \tan \alpha} \left(\frac{1}{\tan \alpha} K_0\left(\frac{1}{\tan \alpha}\right) + K_1\left(\frac{1}{\tan \alpha}\right) \right) \{I \cos \varphi - I \cos(\pi - \varphi) - I \cos(\pi + \varphi) + I \cos(-\varphi)\} \\ &= -\frac{2\mu_0 I}{\pi a \tan \alpha} \left(\frac{1}{\tan \alpha} K_0\left(\frac{1}{\tan \alpha}\right) + K_1\left(\frac{1}{\tan \alpha}\right) \right) \cos \varphi \\ &= -\frac{2\mu_0 I}{\pi} k (k a K_0(k a) + K_1(k a)) \cos \varphi \end{aligned} \quad (30)$$

This result is the same with the above expression of Eq.(20) which is obtained with the different method.

Similarly, for four helical current blocks with dipole symmetry,

$$\begin{aligned} B_{ref} &= \int_{a_1}^{a_2} B_{ref}(a, \varphi) a da \int_{\varphi_1}^{\varphi_2} d\varphi \\ &= -\frac{2\mu_0 j}{\pi} k \int_{a_1}^{a_2} (k a K_0(k a) + K_1(k a)) a da (\sin \varphi_2 - \sin \varphi_1) \\ &\equiv -\frac{2\mu_0 j}{\pi} k \bar{a} (k \bar{a} K_0(k \bar{a}) + K_1(k \bar{a})) \Delta a (\sin \varphi_2 - \sin \varphi_1) \end{aligned} \quad (31)$$

For the off-axis position (x_p, y_p, z_p) ,

$$x_p = r \cos \theta, y_p = r \sin \theta, z_p = z, \quad (32)$$

The components of the vector $\vec{R} = (\vec{R}_x, \vec{R}_y, \vec{R}_z)$ from the helical coil to the position (x_p, y_p, z_p) on the axis, and the conductor element vector $d\vec{s} = (dx_h, dy_h, dz_h)$ are,

$$\begin{cases} R_x = x_p - x_h = r \cos \theta - a \cos (\varphi + \varphi_0), \\ R_y = y_p - y_h = r \sin \theta - a \sin (\varphi + \varphi_0), \\ R_z = z_p - y_h = z - a \varphi \tan \alpha, \end{cases} \quad (33)$$

$$\begin{cases} dx_h = -a \sin (\varphi + \varphi_0) d\varphi, \\ dy_h = a \cos (\varphi + \varphi_0) d\varphi, \\ dz_h = a \tan \alpha d\varphi, \end{cases} \quad (34)$$

Then, the magnetic field of the off-axis position of the helical coils expressed as follows,

$$\begin{aligned} B_x(r, \theta, z) &= \frac{\mu_0 I}{4\pi} \int \frac{[\vec{ds} \times \vec{R}]_x}{|\vec{R}|^3} \\ &= \frac{\mu_0 I}{4\pi} \int_{\varphi_i}^{\varphi_f} \frac{(z - a \tan \alpha \varphi) a \cos (\varphi + \varphi_0) - (r \sin \theta - a \sin (\varphi + \varphi_0)) a \tan \alpha}{\{r^2 + a^2 - 2 r a \cos \{\theta - (\varphi + \varphi_0)\} + (z - a \tan \alpha \varphi)^2\}^{3/2}} d\varphi \end{aligned} \quad (35)$$

$$\begin{aligned} B_y(r, \theta, z) &= \frac{\mu_0 I}{4\pi} \int \frac{[\vec{ds} \times \vec{R}]_y}{|\vec{R}|^3} \\ &= \frac{\mu_0 I}{4\pi} \int_{\varphi_i}^{\varphi_f} \frac{\{r \cos \theta - a \cos (\varphi + \varphi_0)\} a \tan \alpha + (z - a \tan \alpha \varphi) a \sin (\varphi + \varphi_0)}{\{r^2 + a^2 - 2 r a \cos \{\theta - (\varphi + \varphi_0)\} + (z - a \tan \alpha \varphi)^2\}^{3/2}} d\varphi \end{aligned} \quad (36)$$

$$\begin{aligned} B_z(r, \theta, z) &= \frac{\mu_0 I}{4\pi} \int \frac{[\vec{ds} \times \vec{R}]_z}{|\vec{R}|^3} \\ &= \frac{\mu_0 I}{4\pi} \int_{\varphi_i}^{\varphi_f} \frac{(r \sin \theta - a \sin (\varphi + \varphi_0))(-a \sin (\varphi + \varphi_0)) - \{r \cos \theta - a \cos (\varphi + \varphi_0)\} a \cos (\varphi + \varphi_0)}{\{r^2 + a^2 - 2 r a \cos \{\theta - (\varphi + \varphi_0)\} + (z - a \tan \alpha \varphi)^2\}^{3/2}} d\varphi \end{aligned} \quad (37)$$

These equations can be calculated numerically, and are used for the comparison with the analytical calculations.

4. Comparison between the analytical and numerical calculations

For four helical line currents with dipole symmetry of current $+I$, radius a , angle ϕ , with

Radius of helical line current $a = 0.05$ m,

Angle of helical line current $\phi = \pi/6$,

Current $I = -1 \times 10^5$ A,

Pitch length $L = 2$ m,

$k = 2\pi/L = 1/(a \tan \alpha) = \pi$,

Pitch of the winding $\alpha = \tan^{-1}(1/0.05 \pi)$,

Reference radius for multipole $r_0 = 0.03$ m,

as shown in Fig.1-1 and Fig.1-2, the comparison between the analytical and numerical calculations is made. The numerical calculation is made for the helical coil with the infinite length, that is, $\phi_i = -\infty$, $\phi_f = \infty$ with the numerical integration of Eqs.(35)-(37), using Mathematica [7]. The results are shown in Fig.1-3 to Fig.1-10. The agreement between the analytical and numerical calculations is quite good. The multipole coefficients derived from the numerical calculation for each component of magnetic field at $z=0$ of the middle of the helical coil are shown in Table 1-1, with the value of $B_{ref} = 1.41117$ T for B_{ref} of Eq.(7). In Table 1-1, the b-r means the normal multiple coefficients derived from the radial component of field B_r , the b-theta means that of B_θ , and the b-z means that of B_z . These multipole coefficients are equivalent to those shown in Table 1-3. In addition, The multipole coefficients of the non-helical dipole are shown for the comparison with those of the helical dipole in Table 1-3. The calculation of the non-helical dipole is made for the infinite length and the same current I with that of the helical dipole. For the helical coil with the length of one period $L (= 2$ m), furthermore, the multipole coefficients derived from the numerical calculation for each component of magnetic field are shown in Table 1-2, with the value of $B_{ref} = 1.41416$ T for B_{ref} of Eq.(7).

At $z=0$ of the middle of the helical coil, the dipole field $B_{y,z=0}$ at the axis depends on the length of the coil, as shown in Figs.1-11 and 1-12. From the analytical and numerical methods for the infinite length, using Eq.(20) or (29), and the numerical method for the finite length of one period $L (= 2$ m), the dipole field $B_{y,z=0}$ at the axis are calculated, using Eq.(27), as follows,

$$\begin{aligned} B_{y,z=0} &= 1.41117 \text{ T (analytical calculation for the infinite length),} \\ B_{y,z=0} &= 1.41115 \text{ T (numerical calculation for the infinite length),} \\ B_{y,z=0} &= 1.41416 \text{ T (numerical calculation for the finite length of one period } L=2 \text{ m),} \end{aligned}$$

The dipole field $B_{y,z=0}$ on the axis at $z=0$ of the middle changes periodically with the length of the helical dipole coil. This dependence on the length for $B_{y,z=0}$ of the helical dipole is different from that of the non-helical one.

Similarly, for four helical current blocks with dipole symmetry of current density $+j_z$, radii a_1, a_2 , limiting angles ϕ_1, ϕ_2 , with

$$\begin{aligned} \text{Inner radius of helical line current } a_1 &= 0.05 \text{ m,} \\ \text{Outer radius of helical line current } a_2 &= 0.06 \text{ m,} \\ \text{Inner angle of helical line current } \phi_1 &= 0, \\ \text{Outer angle of helical line current } \phi_2 &= \pi/3, \\ \text{Length } L &= 2 \text{ m,} \\ \text{Current } I &= -2 \times 10^5 \text{ A,} \\ \text{Current density } j_z &= 347 \text{ A/mm}^2, \\ k = 2\pi/L = 1/(a \tan \alpha) &= \pi, \\ \text{Pitch of the winding } \alpha &= \tan^{-1}(1/0.05 \text{ } \pi), \\ \text{Reference radius for multipole } r_0 &= 0.03 \text{ m,} \end{aligned}$$

as shown in Fig.2-1 and Fig.2-2, the comparison between the analytical and numerical calculations is made. The numerical calculation is made for the helical coil with the finite length of one period, using the code OPERA-3d [8] for the 3-dimensionial magnetic field calculation. The results are shown in Fig.2-3 to Fig.2-8. The agreement between the analytical and numerical calculations is quite good. The multipole coefficients derived from the numerical calculation for each component of the magnetic field at $z=0$ of the middle of the helical coil are shown in Table 2-1, with the value of $B_{ref} = 2.4627$ T for B_{ref} of Eq.(7). These multipole coefficients are equivalent to those shown in Table 2-2. In addition, The multipole coefficients of the non-helical dipole are shown for the comparison with

those of the helical dipole in Table 2-2. The calculation of the non-helical dipole is made for the same current I and the same z -directional current density j_z with those of the helical dipole, but the current densities j for both of the helical and non-helical dipoles are different.

At $z=0$ of the middle of the helical coil, the dipole field $B_{y,z=0}$ at the axis also depends on the length of the coil. For the infinite length, using Eq.(21), and for the finite length of one period L , the dipole field at the axis are calculated as follows,

$$B_{y,z=0} = 2.45618 \text{ T (analytical calculation for the infinite length),}$$

$$B_{y,z=0} = 2.4627 \text{ T (numerical calculation for the finite length of one period } L=2 \text{ m),}$$

The dipole field at the axis, B_{ref} of Eq.(7) derived for the helical coil with the infinite length is constant, but the dipole field B_{ref} of this helical coil with the finite length depends on the position as shown in Fig.2-9. This means that Eq.(7) is not correct for the end portion of this helical coil.

5. Conclusion

An analytical expressions for the magnetic field and the multipole for the helical coils have been given. The expression of the multipoles for the helical coil is more effective to optimize the cross sectional configuration of the helical coil than those of the non-helical coil. Further investigation is needed for obtaining the expression of the multipole for the ends of a helical coil.

6. Acknowledgments

The author is indebted for helpful discussions and comments to Prof. T. Katayama of RIKEN and Institute of Nuclear Physics, University of Tokyo.

Appendix. The Magnetic Field of 2-dimensional Dipole Coils

On the European Definition, the scalar potential nearer the axis is as follows, [9]

$$\phi(r, \theta) = -B_{ref} r_0 \sum_{n=1}^{\infty} \frac{1}{n} \left(\frac{r}{r_0}\right)^n (-a_n \cos n\theta + b_n \sin n\theta) \quad (A1)$$

Similarly, the vector potential is as follows,

$$A_z(r, \theta) = -B_{ref} r_0 \sum_{n=1}^{\infty} \frac{1}{n} \left(\frac{r}{r_0}\right)^n (a_n \sin n\theta + b_n \cos n\theta) \quad (A2)$$

The treatment of this section follows Me β and P. Schmüser's [10]. For four helical line currents with dipole symmetry, of current $+I_z$, radius a , angle ϕ , at the position (r, θ) of $r < a$, the multipole expansion of the vector potential is as follows,

$$A_z(r, \theta, a, \phi) = 2 \frac{\mu_0 I_z}{\pi} \sum_{n=1}^{\infty} \frac{1}{n} \left(\frac{r}{a}\right)^n \cos n\phi \cos n\theta \quad (A3)$$

where, $n=1, 3, 5, \dots, \infty$

Then, the normal multipoles B_n , the multipole coefficients b_n , and with the definition of $b_1=1$, the dipole field B_{ref} are as follows,

$$B_n = -\frac{2\mu_0}{\pi} I_z \frac{1}{r_0} \left(\frac{r_0}{a}\right)^n \cos n\phi \quad (A4)$$

$$B_1 = B_{ref} = -\frac{2\mu_0}{\pi} I_z \frac{\cos \phi}{a} \quad (A5)$$

$$b_n = \frac{B_n}{b_n} = \left(\frac{r_0}{a}\right)^{n-1} \frac{\cos n\phi}{\cos \phi} \quad (A6)$$

Similarly, for four helical current blocks with dipole symmetry, of current density $+j$ ($=+j_z$), radii a_1, a_2 , limiting angles ϕ_1, ϕ_2 , at the position (r, θ) of $r < a$, the multipole expansion of the vector potential is as follows,

$$\begin{aligned} A_z(r, \theta) &= \int_{a_1}^{a_2} A_z(r, \theta, a, \phi) a da \int_{\phi_1}^{\phi_2} d\phi \\ &= -2 \frac{\mu_0 j}{\pi} \sum_{n=1}^{\infty} \frac{1}{n} r^n \frac{1}{2-n} (a_2^{2-n} - a_1^{2-n}) \frac{1}{n} (\sin n\phi_2 - \sin n\phi_1) \cos n\theta \end{aligned} \quad (A7)$$

Then, the multipoles are as follows,

$$B_n(r_0) = -\frac{2\mu_0}{\pi} j \frac{1}{n} \frac{r_0^{n-1}}{2-n} \{ \sin(n\phi_2) - \sin(n\phi_1) \} [a_2^{2-n} - a_1^{2-n}] \quad (A8)$$

$$B_1 = B_{ref} = -\frac{2\mu_0}{\pi} j (\sin \phi_2 - \sin \phi_1) [a_2 - a_1] \quad (A9)$$

$$b_n = \frac{B_n}{B_1} = \frac{1}{n} \frac{r_0^{n-1}}{2-n} \frac{\{ \sin(n\phi_2) - \sin(n\phi_1) \} [a_2^{2-n} - a_1^{2-n}]}{(\sin \phi_2 - \sin \phi_1) [a_2 - a_1]} \quad (A10)$$

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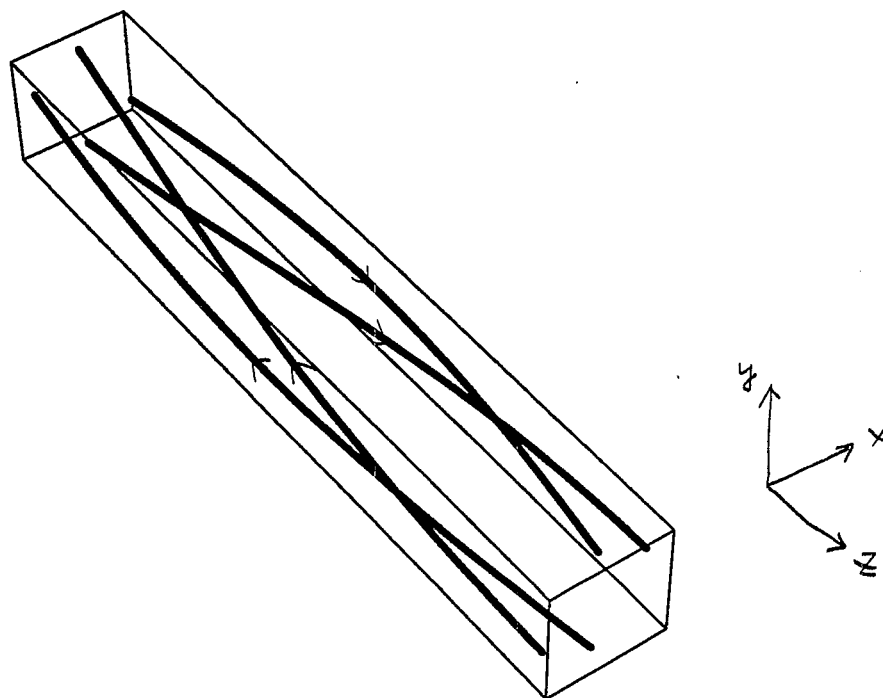


Fig.1-1 3-dimensional view of a helical dipole

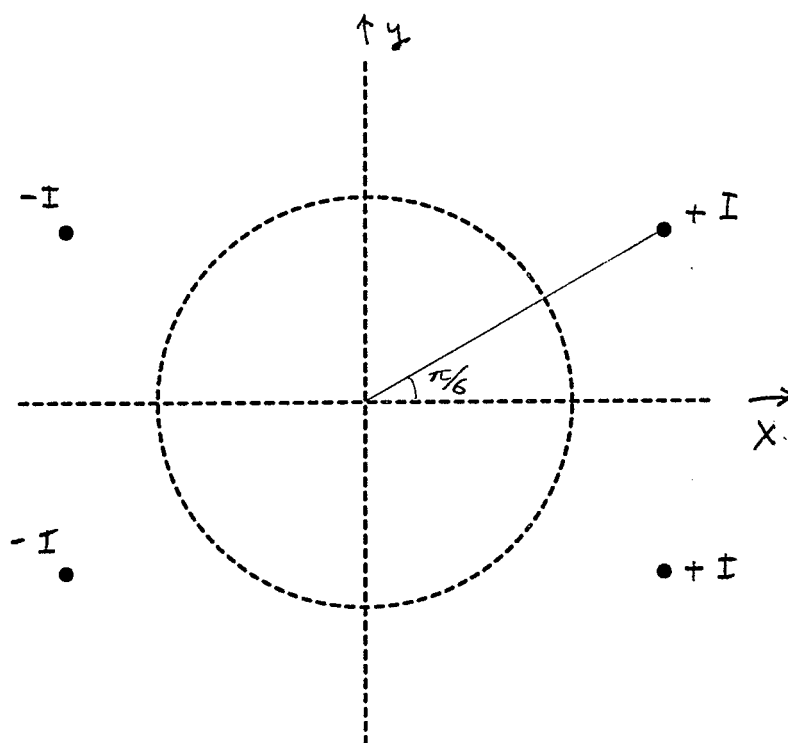


Fig.1-2 Four helical line currents with dipole symmetry

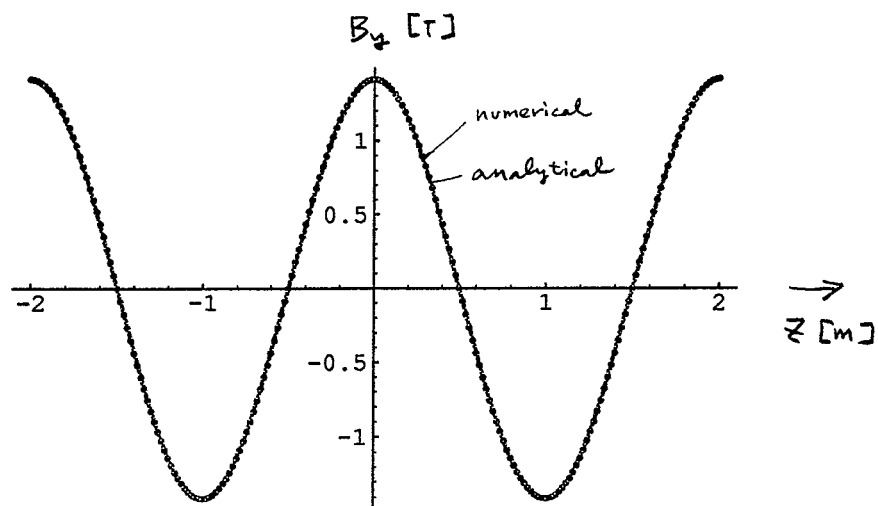


Fig.1-3 Distribution of B_y along the z axis

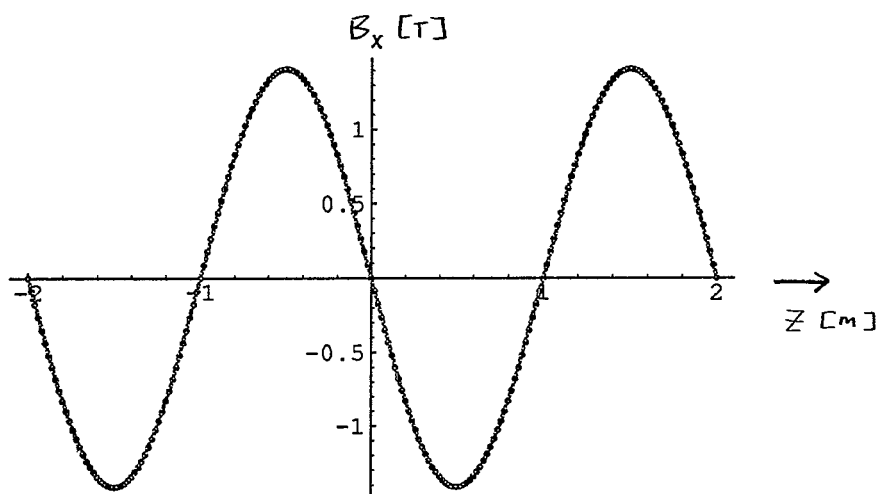


Fig.1-4 Distribution of B_x along the z axis

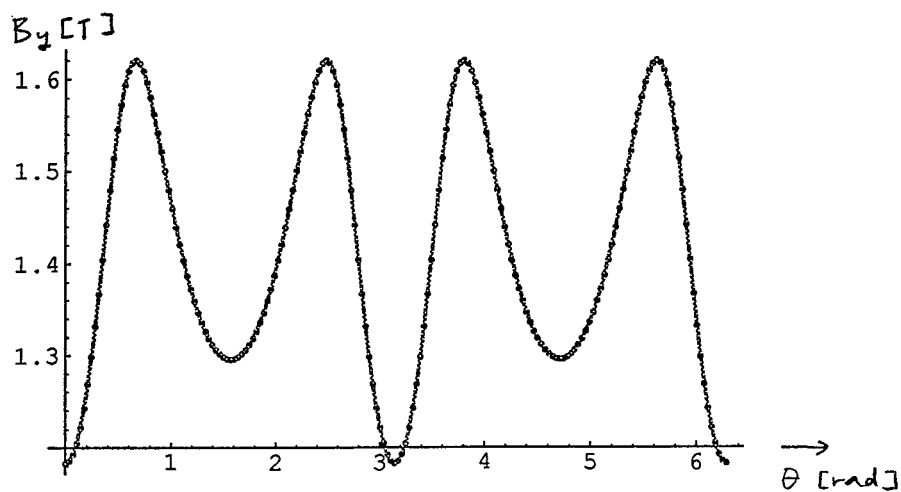


Fig.1-5 Distribution of B_y on the circle of radius $r_0 = 0.03$ m at $z = 0$

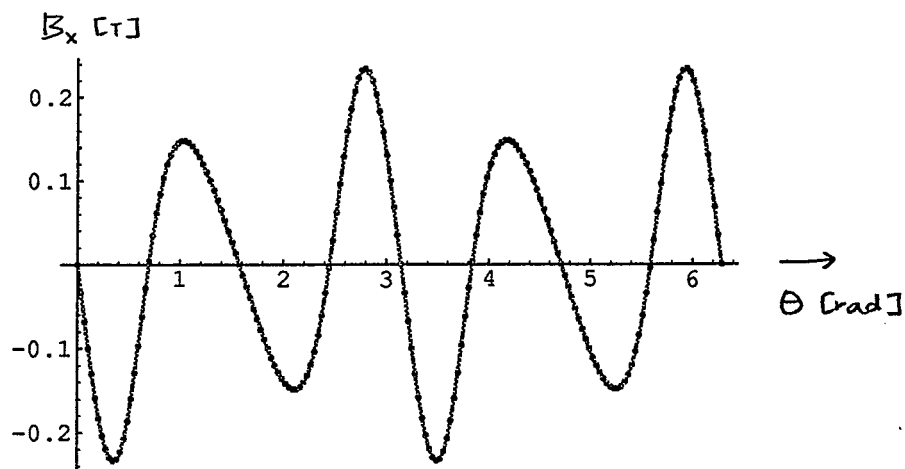


Fig.1-6 Distribution of B_x on the circle of radius $r_0=0.03$ m at $z = 0$

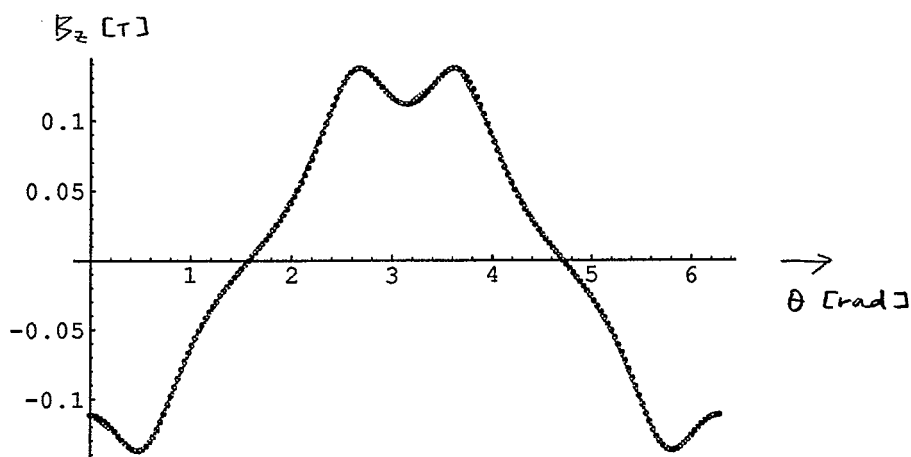


Fig.1-7 Distribution of B_z on the circle of radius $r_0=0.03$ m at $z = 0$

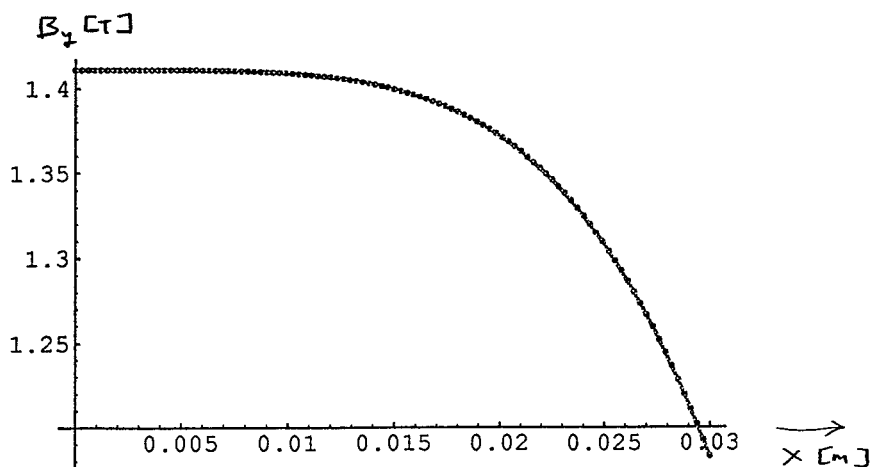


Fig.1-8 Distribution of B_y on the x axis at $z = 0$

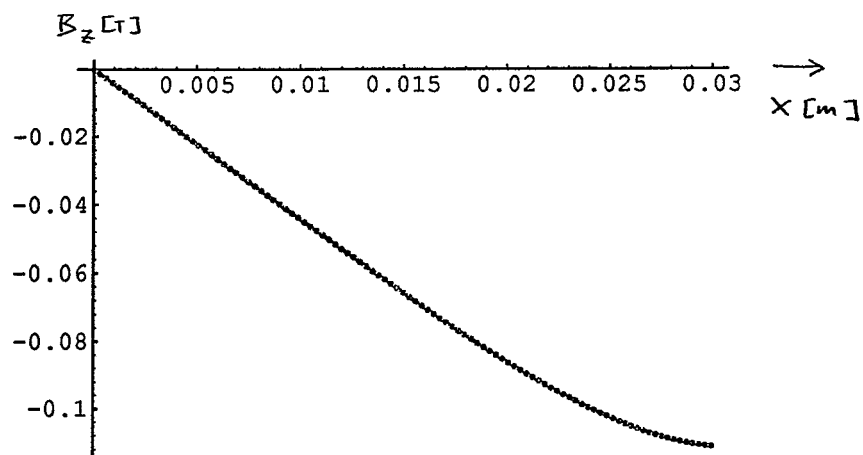


Fig.1-9 Distribution of B_z on the x axis at $z = 0$

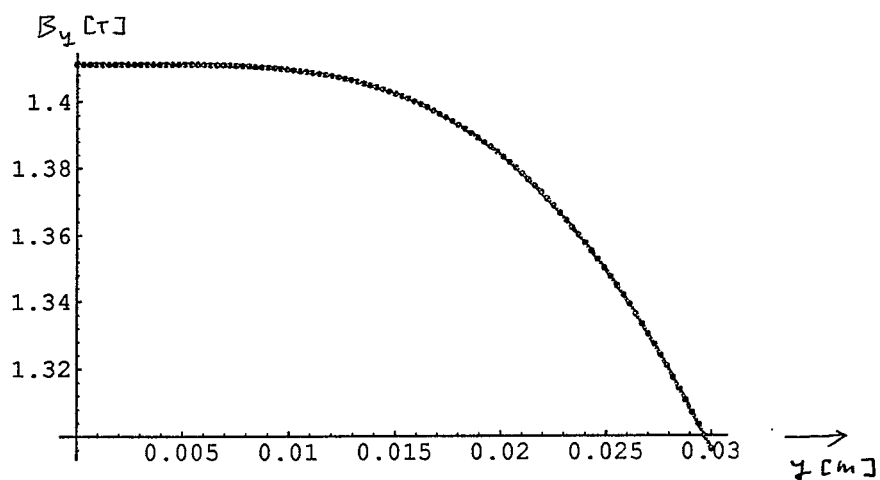


Fig.1-10 Distribution of B_y on the y axis at $z = 0$

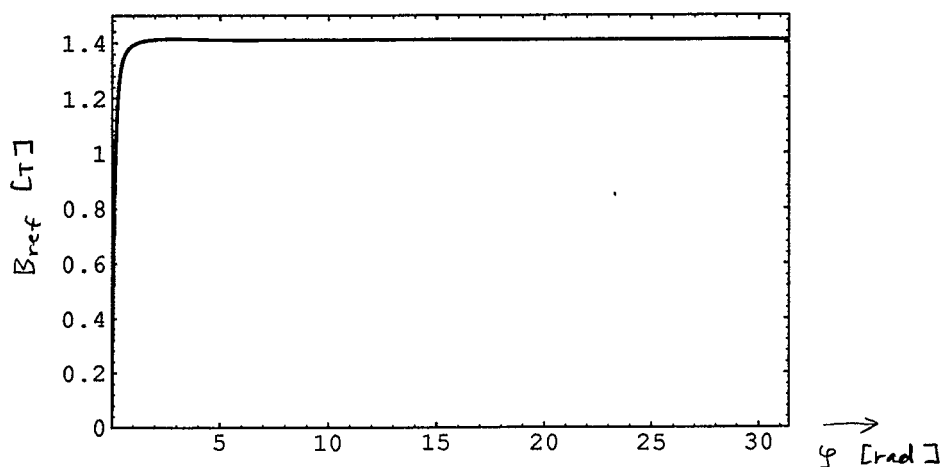


Fig.1-11 Length dependence of B_{ref} at $z = 0$
(half length = $a \tan \alpha \phi = \phi / 2\pi$)

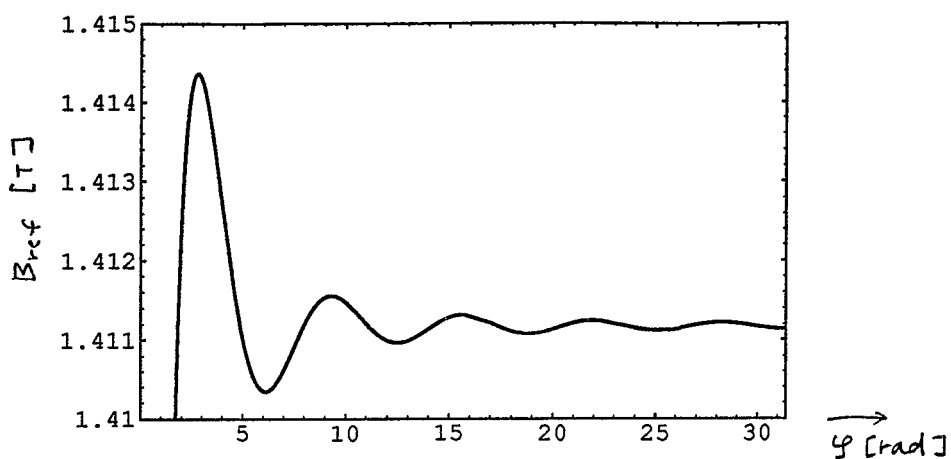


Fig.1-12 Length dependence of B_{ref} at $z = 0$
(half length = $a \tan \alpha \phi = \phi/2\pi$), enhanced of Fig.1-10

Table 1-1 Normal multipole coefficients derived from the numerical calculation for a infinitely long helical dipole

n	b-r	b-theta	b-z
1	0.999829	0.999829	0.999848
3	$1.17709 \cdot 10^{-10}$	$-2.85882 \cdot 10^{-10}$	$2.30424 \cdot 10^{-7}$
5	-0.123864	-0.123864	-0.123864
7	-0.0438636	-0.0438636	-0.0438631
9	$1.46902 \cdot 10^{-10}$	$-1.72114 \cdot 10^{-10}$	$5.28806 \cdot 10^{-7}$
11	0.00548344	0.00548344	0.00548422
13	0.0019353	0.0019353	0.00193623
15	$4.85152 \cdot 10^{-11}$	$-6.91257 \cdot 10^{-11}$	$9.62863 \cdot 10^{-7}$
17	-0.000240154	-0.000240154	-0.000239159
19	-0.0000844321	-0.0000844323	-0.0000832915

Table 1-2 Normal multipole coefficients derived from the numerical calculation for a helical dipole with the length of one period $L = 2$ m

n	b-r	b-theta	b-z
1	0.999839	0.999843	0.997408
3	5.56122 10^{-12}	1.69874 10^{-12}	-6.57707 10^{-10}
5	-0.123603	-0.123603	-0.123603
7	-0.043771	-0.043771	-0.043771
9	7.85488 10^{-12}	-9.24768 10^{-13}	-6.24984 10^{-10}
11	0.00547187	0.00547187	0.00547187
13	0.00193122	0.00193122	0.00193122
15	-1.5853 10^{-12}	-1.91519 10^{-12}	-5.70833 10^{-10}
17	-0.000239648	-0.000239648	-0.000239648
19	-0.0000842539	-0.0000842539	-0.0000842544

Table 1-3 Normal multipole coefficients derived from the analytical calculation for the helical and non helical coils

n	b-helix	b-2d
(Bref)	1.41117	1.38564
1	1.	1.
3	0	0
5	-0.124337	-0.1296
7	-0.044193	-0.046656
9	0	0
11	0.00558607	0.00604662
13	0.00198621	0.00217678
15	0	0
17	-0.000251127	-0.000282111
19	-0.0000892971	-0.00010156

$$a_1 = 0.05 \text{ m}$$

$$a_2 = 0.06 \text{ m}$$

$$\phi_1 = 0$$

$$\phi_2 = 60^\circ$$

$$L = 2 \text{ m}$$

$$h = \frac{2\pi}{L} = \pi$$

$$I = -2 \times 10^5 \text{ A} \times 2$$

$$j = 347 \text{ A/mm}^2$$

$$r_0 = 0.03 \text{ m}$$

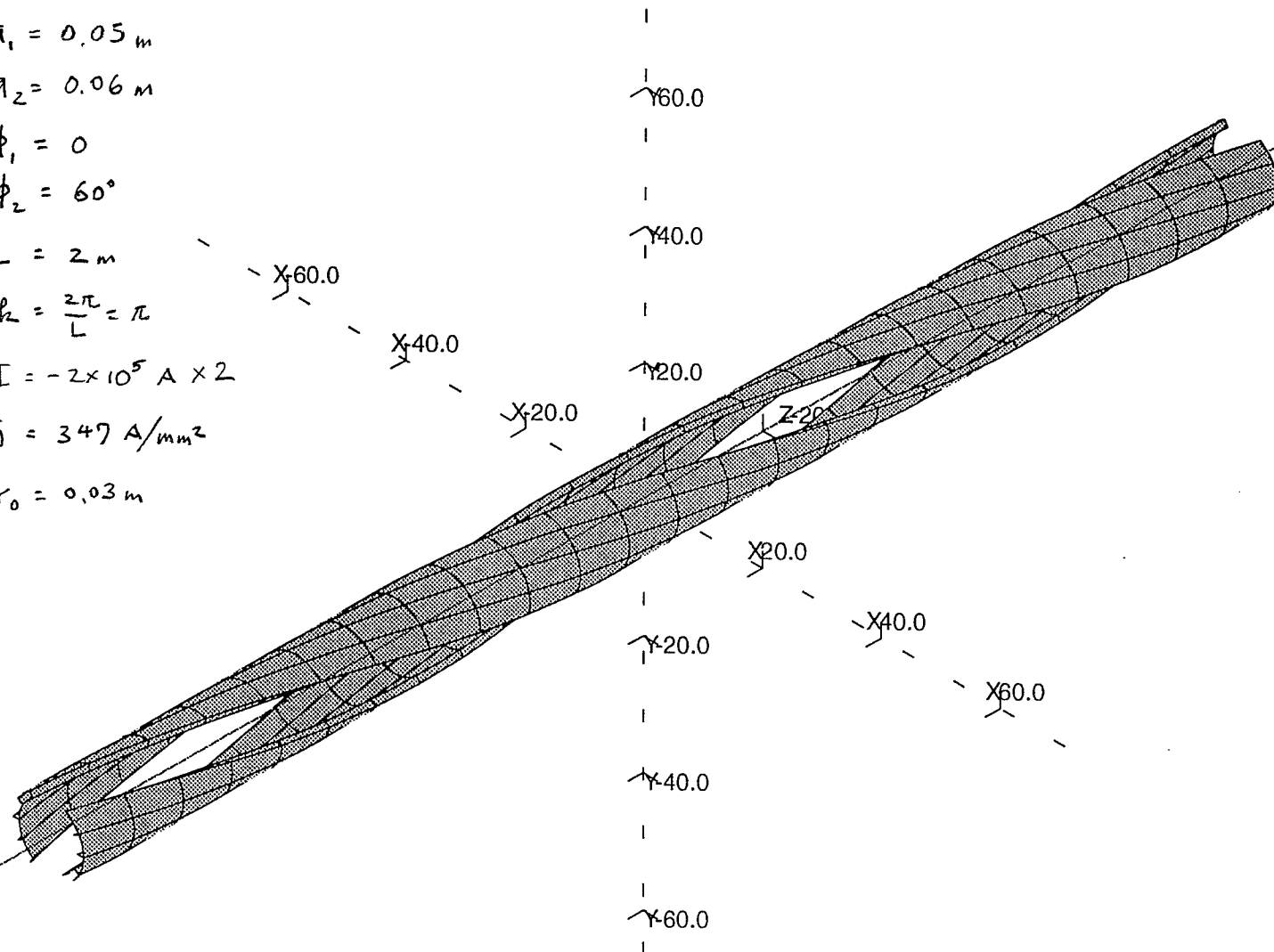


Fig. 2-1 3-dimensional view of a helical dipole

UNITS
Length
Flux density
Magnetic field
Scalar potential
Vector potential
Conductivity
Current density
Power
Force
Energy
Electric field

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Ylocal = 0.0
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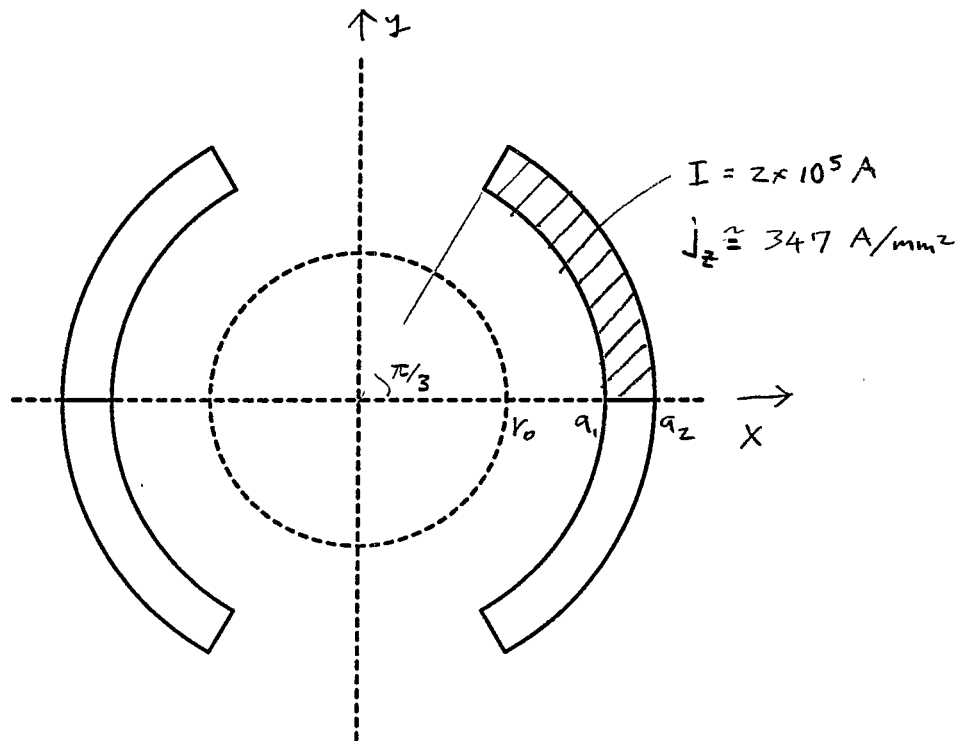


Fig.2-2 Cross section of a helical dipole

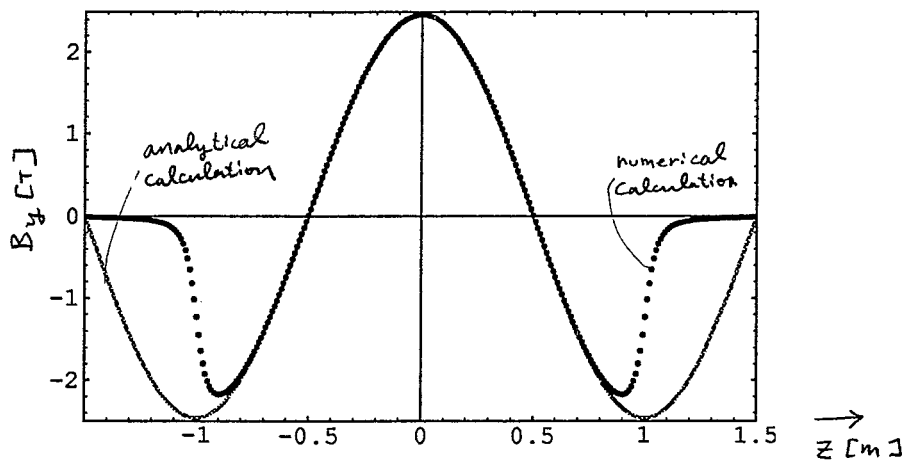


Fig.2-3 Distribution of B_y along the z axis

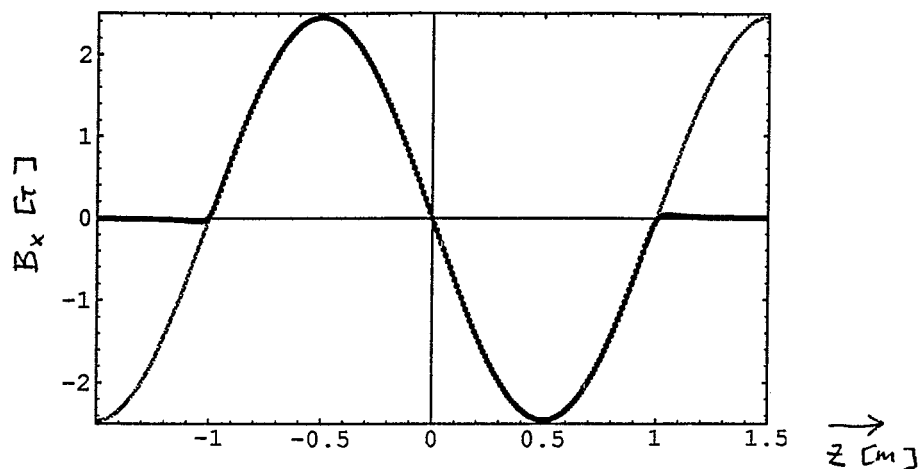


Fig.2-4 Distribution of B_x along the z axis

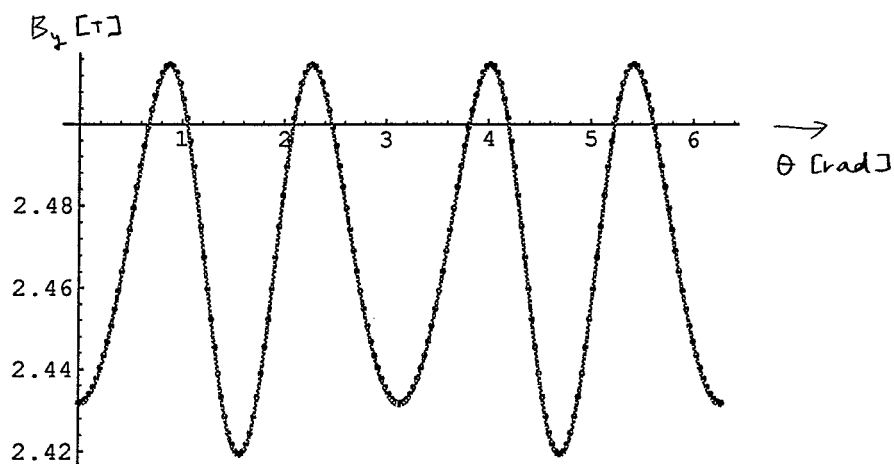


Fig.2-5 Distribution of B_y on the circle of radius $r_0=0.03$ m at $z = 0$

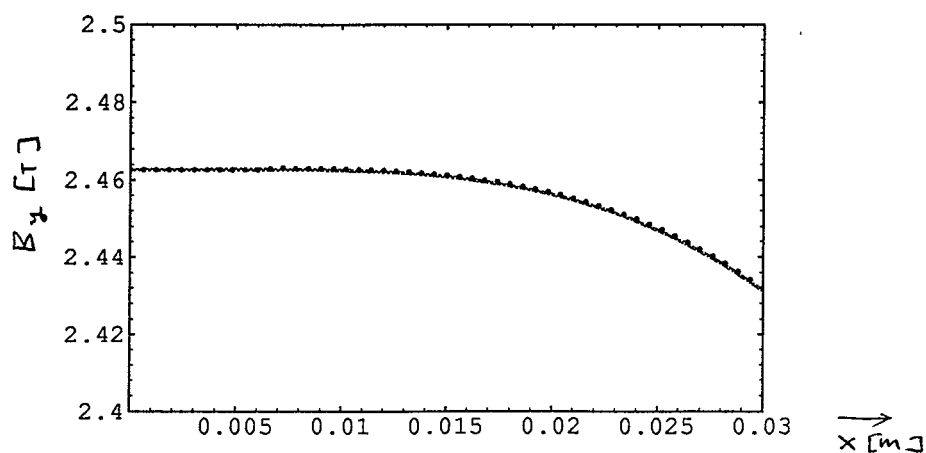


Fig.2-6 Distribution of B_y on the x axis at $z = 0$

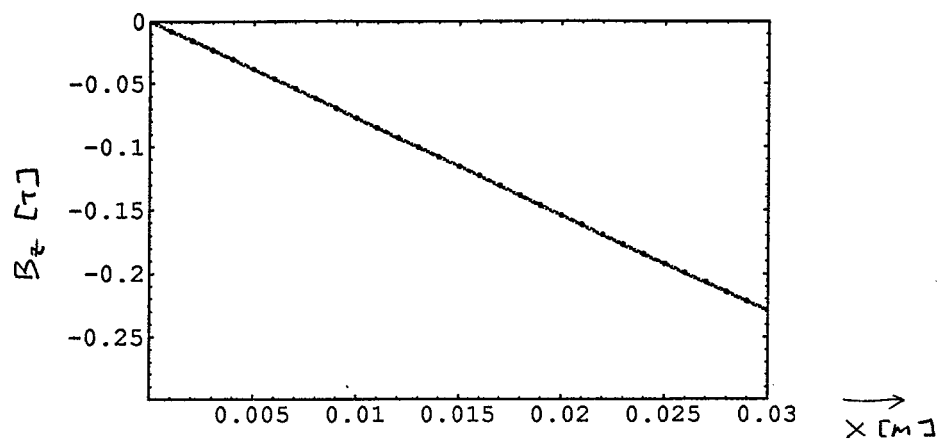


Fig.2-7 Distribution of B_z on the x axis at z = 0

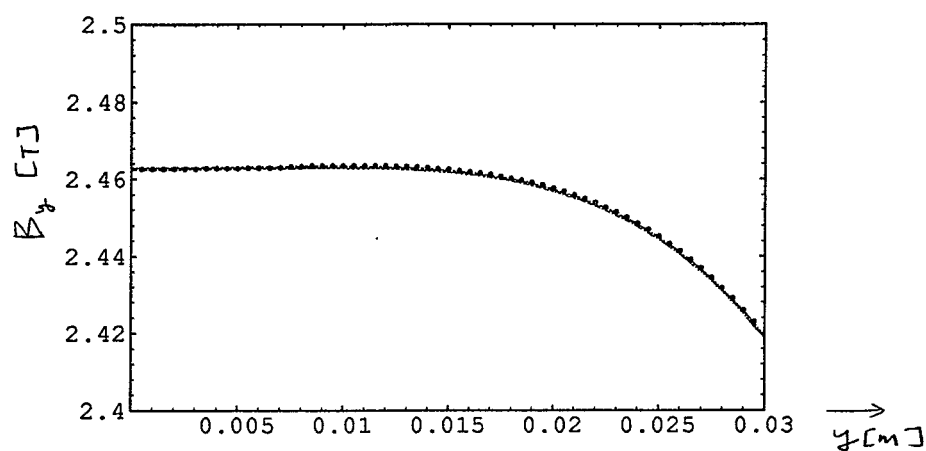


Fig.2-8 Distribution of B_y on the y axis at z = 0

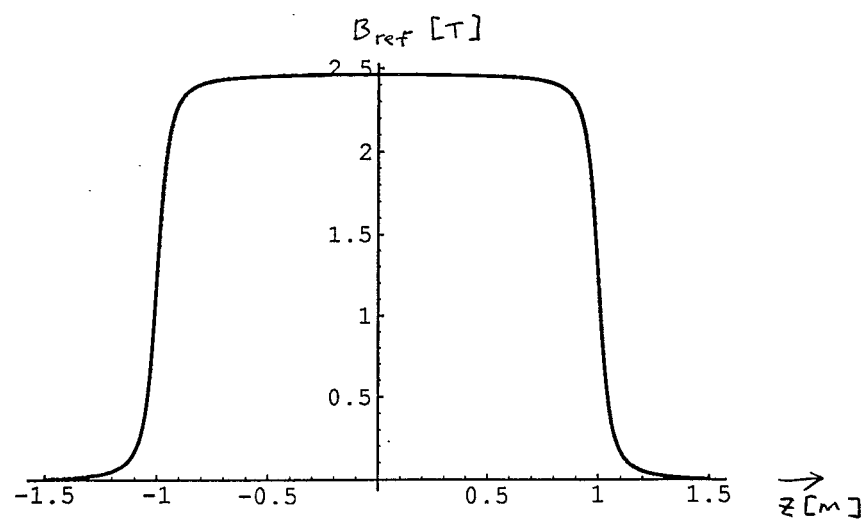


Fig.2-9 Distribution of B_{ref} along the z axis

Table 2-1 Normal multipole coefficients derived from the numerical calculation

n	b-r	b-theta	b-z
1	1.00007	1.00007	0.997985
3	2.131 10 ⁻⁶	-1.00099 10 ⁻⁶	-3.48087 10 ⁻⁷
5	-0.0172713	-0.0172738	-0.017302
7	0.00371776	0.00371768	0.00372466
9	-5.2623 10 ⁻⁶	-3.24599 10 ⁻⁶	-7.38791 10 ⁻⁷
11	-0.00021577	-0.000220001	-0.000222324
13	0.0000631848	0.0000645796	0.0000570429
15	-1.46767 10 ⁻⁶	3.99728 10 ⁻⁶	1.11228 10 ⁻⁶
17	-4.26972 10 ⁻⁶	-4.27167 10 ⁻⁶	-4.07128 10 ⁻⁶
19	4.42199 10 ⁻⁷	2.20902 10 ⁻⁶	3.01335 10 ⁻⁷

Table 2-2 Normal multipole coefficients derived from the analytical calculation for the helical and non helical coils

n (Bref)	b-helix 2.45618	b-2d 2.4058
1	1.	1.
3	1.36929 10 ⁻¹⁷	1.4141 10 ⁻¹⁷
5	-0.0173424	-0.0182
7	0.00374336	0.00398657
9	3.77454 10 ⁻¹⁹	4.07687 10 ⁻¹⁹
11	-0.000224835	-0.000246199
13	0.00005935	0.0000658676
15	1.14528 10 ⁻²⁰	1.28792 10 ⁻²⁰
17	-4.54038 10 ⁻⁶	-5.17256 10 ⁻⁶
19	1.301 10 ⁻⁶	1.50127 10 ⁻⁶