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Beam and Spin Optics Simulation Tutorials, Using Zgoubi Exercises and Solutions 2 - RHIC Run 22 Spin Transparency Experiment

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Beam and Spin Optics Simulation Tutorials, Using Zgoubi

Exercises and Solutions

2 - RHIC Run 22 Spin Transparency Experiment

September 2022

A tutorial series held at BNL C-AD, following RHIC Run 22

Tech. Note C-A/AP/662

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Tutorial Part 1 Spin Transparency Experiment at RHIC

1.1 Introduction

High electron and ion polarizations are paramount design requirements for the future Electron Ion Collider (EIC) at BNL. A "spin transparency" mode of operation, inherited from the "figure-8" ring design [1], allows preservation and control of electron and ion spin polarization in a collider or storage ring [2, 3]. It makes the ring lattice "invisible" to the spin and allows for polarization control by small quasi-static magnetic fields with practically no effect on beam orbital parameters. Beam polarization can then be fully controlled by small adjustments of snake axis orientation (a few degrees) and snake strengths (a few percent); polarization orientation at IPs can be controlled without spin rotators, spins can be adiabatically flipped without the need of ac magnets.

The transparent spin mode has been demonstrated in simulations [2] for the purpose of being tested experimentally during RHIC Run 22. This experiment was aimed at providing data to validate the principles. Yellow RHIC ring (Fig. 1.1) was configured in the transparent spin mode by aligning the axes of its two helical snakes (located respectively in the 3 o'clock and 9 o'clock sextants) parallel to the longitudinal axis. Experiment goals and expected results, *ad hoc* procedures and hardware requirements, are addressed in Refs. [2, 3].

1 Spin Transparency Experiment at RHIC

Fig. 1.1 Locations of the helical snakes in RHIC Blue and Yellow rings, at 9 o'clock and 3 o'clock. Beam goes clockwise in Blue, counterclockwise in Yellow. Zgoubi frame is (O;X/long.,Y/radial,Z/vertic.). In Blue: X tangent to orbit points as velocity (CW), Y points outward, Z points up (curvature is negative/center at negative Y, dispersion is > 0); in Yellow: X tangent to orbit points as velocity (CCW), Y points outward, Z points down (curvature is negative/center at negative Y, dispersion is > 0).



1.2 These Simulations

Most importantly:

they require having Zgoubi Users' Guide at hand.

it can be found here:

https://sourceforge.net/p/zgoubi/code/HEAD/tree/trunk/guide/Zgoubi.pdf Navigating the INDEX is a convenient way to find out what the commands, keywords, and other numerical data found in the input data file do or represent.

Spin transparency mode of operation at RHIC had been demonstrated in simulations, prior to proposing Run 22 APEX. The goal of this tutorial is to go over these simulations in detail. They can be seen as an opportunity to review the computational methods and tools.

All the exercises and necessary files in these simulations are organized in folders, downloadable at

https://sourceforge.net/p/zgoubi/code/HEAD/tree/trunk/exemples/tutorials/BNLSpinTransparency_2022

Note: from here on, "[pathTo]/zgoubi-code/" will represent the absolute address of the sourceforge package on your computer.

Found there as well is a copy of the present document:

 $[pathTo]/zgoubi-code/exemples/tutorials/BNLSpinTransparency_2022/tutorialAssignments/tutorialAssignments.pdf$

Snake Field Maps

RHIC snakes are comprised of four identical 360°-twist helices (Fig. 1.2), with the following parameters [4] (Figs. 1.1, 1.3)

- helices are right-handed,
- a helix is 2.4 m long,

1.2 These Simulations

S =

Fig. 1.2 RHIC snake model in OPERA, a 4module structure, all four modules are righthanded helices, magnetic field sign alternates from one to the next. The two inner modules (2 and 3) are fed in series (I_{in} current), the two outer modules (1 and 4) are fed in series as well $(I_{out} \text{ current})$. In red, visible in the center and at the right end: helical coils of an inner and an outer module.



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Fig. 1.3 A sketch of RHIC snake and rotator layouts, each rectangle represents a 2.4 m long 360°twist helix. Field maps from the OPERA model extend an extra 0.764 m at both ends, to encompass field fall-offs.

- they are spaced 0.212/0.448/0.212 m,

- the central 0.448 m drift space includes a BPM,

hence an overall snake length of 10.472 m. Regarding the geometrical acceptance at the location of a snake: magnet bore is 10 cm.

OPERA field maps of the modules are used in these simulations. In this representation a full snake is a sequence of 4 field maps: field maps 1 and 4 have been computed at low field (100 A current), 2 and 3 have been computed at high field (322 A) [4]. Field signs to be assigned to module field maps, going counter-clockwise around RHIC Yellow, are as follows:

sign to be	e applied	field map file name
3 o'clock snake	9 o'clock snake	
(R+R-R+R-)	(R-R+R-R+)	
+	_	$model3a2a - x - 4_4_y - 4_4_z - 180_{180} - integral.table$
—	+	$model3a2a322a - x - 4_4_y - 4_4_z - 180_{180} - integral.table$
+	_	$model3a2a322a - x - 4_4y - 4_4z - 180_{180} - integral.table$
_	+	$model3a2a - x - 4_4_y - 4_4_z - 180_{180} - integral.table$

These OPERA maps are archived/available on C-AD computers at

/rap/lattice_tools/zgoubi/RHICZgoubiModel/snakeFieldMaps/161216_secondSet_inclSingleHelix

or in sourceforge at

[pathTo]/zgoubi - code/exemples/RHIC/snakesWithFieldMaps/fieldMaps/

Binary versions of these files are also available therein, same name preceded with a "b_" prefix; binary files offer the advantage of much faster reading.

Fig. 1.4 (Y,Z) projection of the helical orbit in a snake, at $G\gamma = 45.5$. Closed orbit entrance and exit points are at A. Note that the motion is a *non-circular* helix



Orbit and Spin Perturbation by Snakes

At injection energy ($G\gamma = 45.5$) the helical closed orbit along the inner two helices of a snake is centered on the snake axis, Fig. 1.4. This imposes presenting the closed orbit at a non-zero vertical excursion at the entrance of the snake (point "A" in Fig. 1.4), and the orbit will exit the snake at a similar vertical excursion (details in [4]). Snakes also introduce a small horizontal orbit defect. The subsequent orbit bump is closed locally, over ≈ 90 meters around the snake, this local orbit compensation in turn impacts on the spin closed orbit. These effects are dealt with as part of RHIC optics by accounting for detailed closed orbit geometry and spin motion throughout the 10.4 m snake extent, which requires using their field maps, this is the object of simulations in Sec. 2.

Regarding RHIC optics, the starting point for these spin transparency simulations is Run 22 MADX model, which has been translated to zgoubi. Preliminary checks of RHIC optics modeling with field maps are the object of simulations in Sec. 2.2.

Spin transparency simulations proper are worked out in Sec. 2.3. In a first simulation, Sec. 2.3.1, polarization is moved from vertical to radial. In a second simulation, Sec. 2.3.2, vertical polarization is flipped.

Tutorial Part 2 Simulation Exercises

2.1 Setting Up Snake Current Ramps

This first exercise aims at determining the snake current ramps required to move the polarization from vertical to radial in a first experiment, and for polarization flip in a second experiment.

Simulation files concerned in this Section can be found at,

regarding vertical to radial orientation:

[pathTo]/zgoubi-code/exemples/RHIC/spinTransparency/snakeSettings/adjustRadialPolar/ and, regarding polarization flipping:

[pathTo]/zgoubi-code/exemples/RHIC/spinTransparency/snakeSettings/reverseVerticalPolar/ In both folders, the two jobs to run are

 $[pathTo]/zgoubi-code/zgoubi/zgoubi-in\ snake3OCCW_scanMuPhi.dat\ and\$

[pathTo]/zgoubi-code/zgoubi/zgoubi -in snake9OCCW_scanMuPhi.dat

Note that regular currents in normal RHIC polarized proton operation, which yield snake axes at $\pm 45^{\circ}$ from longitudinal and spin rotation 180° , are

$$I_{\rm out} = 100 \,\mathrm{A}, \qquad I_{\rm in} = 322 \,\mathrm{A},$$

for both snakes. These currents undergo substantial changed for spin transparency operation.

• Question 2.1-1

First read the next question (Question 2.1-2), then devote some thinking to understanding the content of snake3OCCW_scanMuPhi.dat and snake9OCCW_scanMuPhi.dat data files, including the various keywords and their numerical arguments: OB-JET, PARTICUL, SPNTRK, OPTIONS, SPNPRT[MATRIX,PRINT], beam line sequence, FIT procedure, SYSTEM. Consult the Users' Guide for that.

In particular, explain

- the role of REBELOTE do-loop in this simulation, what parameter it changes from an iteration to the next,

- the role of the OPTIONS[.plt 2] command, specific to this orbit bump design simulation;

- what causes these jobs to end up with a graph of the orbits.

• Question 2.1-2

Solution: page 16

The first test of the spin transparency experiment, vertical to radial polarization, requires determining the snake currents needed to achieve the 11 different μ , ϕ snake angle couples given in Tab. 2.1.

The folder concerned is

[pathTo]/zgoubi-code/exemples/RHIC/spinTransparency/snakeSettings/adjustRadialPolar/

Table 2.1 Required 3 o'clock and 9 o'clock snake angle sequence for moving polarization from vertical (at step 0) to radial (at step 10).

 Table 2.2 Required 3 o'clock and 9 o'clock snake angle sequence for vertical polarization flip.

3 o'c	lock	9 o'clock		3 o'clo	ck	9 o'clock
μ	ϕ	$\mu \phi$	Step #	μ	ϕ	$\mu \phi$
180	0	180 170	0	180	0	180 -10
177	0	180 170	1	177.5	0	180 -10
174	0	180 170	2	175	0	180 -10
171	0	180 170	3	175	0	180 -5
168	0	180 170	4	175	0	180 -2
165	0	180 170	5	175	0	180 0
165	0	177 172	6	175	0	180 2
165	0	174 174	7	175	0	180 5
165	0	171 176	8	175	0	180 10
165	0	168 178	9	177.5	0	180 10
165	0	165 180	10	180	0	180 10
	3 o'c μ 180 177 174 171 168 165 170 170 160	$\begin{array}{cccc} 3 \text{ o'clock} & \mu & \phi \\ 180 & 0 \\ 177 & 0 \\ 174 & 0 \\ 171 & 0 \\ 168 & 0 \\ 165 & 0 \\ 165 & 0 \\ 165 & 0 \\ 165 & 0 \\ 165 & 0 \\ 165 & 0 \\ 165 & 0 \end{array}$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	3 o'clock9 o'clock3 o'cloc $\mu \phi$ $\mu \phi$ Step # μ 180180170018017701801701177.517401801702175171018017031751680180170417516501801705175165017717261751650174174717516501681789177.5165016518010180	3 o'clock9 o'clock3 o'clock $\mu \phi$ $\mu \phi$ Step # $\mu \phi$ 1800180170018017701801701177.5017401801702175017101801703175016801801704175016501801705175016501771726175016501741747175016501681789177.501650165180101800

The two jobs to run, reminder:

[pathTo]/zgoubi-code/zgoubi/zgoubi -in snake3OCCW_scanMuPhi.dat and

[pathTo]/zgoubi-code/zgoubi/zgoubi -in snake9OCCW_scanMuPhi.dat are respectively set up for these 9 o'clock and 3 o'clock snake current scans.

Run these files and check the following:

- FIT (or FIT2 - figure out the nature of both algorithms) finds the I_{out} , I_{in} snake currents (FIT variables) for a given (μ, ϕ) pair (FIT constraints);

- REBELOTE is used to repeat over the 11 different (μ, ϕ) values.

- gnuplot scripts under SYSTEM provide various graphs, inluding the 11 orbits across each snake - this allows verifying that they remain about centered throughout the scan (tight centering is unnecessary as far as spin motion is concerned); magnetic field along thee orbits, etc.

Complete Tabs. 2.1 with, for each snake, its corresponding Iout, Iin columns.

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2.1 Setting Up Snake Current Ramps

• Question 2.1-3 Solution: page 18

The second test of the spin transparency experiment, vertical spin flip, requires determining the snake currents needed to achieve the 11 different μ , ϕ snake angle couples given given in Tab. 2.2.

The folder concerned is

[pathTo]/zgoubi-code/exemples/RHIC/spinTransparency/snakeSettings/reverseVerticalPolar/ Here as well, the two jobs to run, reminder:

 $[pathTo]/zgoubi-code/zgoubi/zgoubi-in\ snake3OCCW_scanMuPhi.dat\ and\$

[pathTo]/zgoubi-code/zgoubi/zgoubi -in snake9OCCW_scanMuPhi.dat are respectively set up for these 9 o'clock and 3 o'clock snake current scans.

Repeat the procedure of Question 2.1-2 for this polarization flip case.

Complete Tab. 2.2 with, for each snake, the corresponding I_{out} , I_{in} columns.

2.2 Setting Up RHIC Yellow Optics Model

This preliminary simulation makes sure RHIC Run 22 Yellow optics, counerclockwise (CCW), is all set, ready to go!

The folder concerned is

[pathTo]/zgoubi-code/exemples/tutorials/ BNLSpinTransparency_2022/RHIC-run22_ppLattice/

This simulation of RHIC Yellow ring involves a main file,

pp22-yellow-CCW.INC.dat,

this file includes the complete Yellow optical sequence, CCW. It is a good idea to make sure that this file is correctly set up and yields the expected optical functions, as most of all other simulation files resort to INCLUDEs grabbing from that pp22-yellow-CCW.INC.dat file.

That file pp22-yellow-CCW.INC.dat also resorts itself to INCLUDEs, concerning namely the three ancillary files

- SCALING_snks100A-322A.inc, which sets the power supplies of the optical elements, including 100A/322A snake currents,

- snake3OCCW_Segment.inc,

- snake9OCCW_Segment.inc.

The optical sequences in the latter two files are ~ 90 meter long segments of RHIC lattice encompassing, respectively, the 3 o'clock snake (snake 2 in the following, coming first when going around Yellow counter-clockwise, see Fig. 1.1) and the 9 o'clock snake (snake 1, coming second when going around Yellow counter-clockwise). These ~ 90 meter segments include each 4 upstream and 4 downstream H and V kickers which allow designing a local closed orbit bump. They are stand-alone files, and allow the design of these orbit bumps by means of a fitting procedure (FIT command, at the bottom of the file).

• Question 2.2-1

This question addresses the setting up of the local $\approx 90 \text{ m}$ extent closed orbit bumps at the snakes.

Run snake3OCCW_Segment.inc. Get from that

(i) a graph of the projection of the helical motion in each snake;

(ii) a graph of the closed orbit in the snake region.

Repeat for snake9OCCW_Segment.inc,

• Question 2.2-2

The file pp22-yellow-CCW.INC.dat is set for regular RHIC optics, which means regular snake currents, $I_{out} = 100A$, $I_{in} = 322A$.

1. Describe the (O;X,Y,Z) frame in this this Yellow-CCW model: the X axis points in the direction of the motion by definition; clarify orientation of Y axis (inward or outward) and Z axis (up or down).

- 2.2 Setting Up RHIC Yellow Optics Model
- 2. Make sure about that (snake currents are set by TOSCA power supplies under SCALING command).
- Produce the closed orbit and optical functions around the ring. In other words: [pathTo]/zgoubi-code/zgoubi/zgoubi -in pp22-yellow-CCW.INC.dat In passing: that creates as always a zgoubi.res listing. Copy it to temp. Run temp, check any difference between temp and its new zgoubi.res (use 'diff -u temp zgoubi.res'). Explain.
- 4. Figure out what is going on, what zgoubi does when going through pp22-yellow-CCW.INC.dat.
- 5. Right before TWISS, following the sequence in pp22-yellow-CCW.INC.dat (bottom of the file), a FIT command has been commented. What would it do? In view of the previous observations regarding closed orbits, should it be un-commented?

• Question 2.2-3

While we are in that folder,

 and dealing with paraxial optics, find the stable spin precession axis n₀ at IP6. In other words: [pathTo]/zgoubi-code/zgoubi/zgoubi -in pp22-yellow-CCW_spinN0.INC.dat.

Figure out what zgoubi does when going through pp22-yellow-CCW_spinN0.INC.dat.

2. Propagate $\mathbf{n}_0(IP6)$ around the ring, give a graph of the three components $\mathbf{n}_{0, X, Y, Z}(s)$.

2 Simulation Exercises

2.3 Spin Transparency Simulations

2.3.1 Vertical to radial polarization

In order to manipulate a slimmer (and clearer) main input file, arrange it under the form of a series of INCLUDEs, namely:

pp22-yellow-CCW_spinN0.INC.dat

In that file, 5 RHIC segments are subject to INCLUDE commands, namely

- Clock 6 to 3 o'clock snake
- 3 o'clock snake segment proper,
- 3 o'clock snake to 9 o'clock snake,
- 9 o'clock snake segment proper,
- 9 o'clock snake to Clock6.

The snake segments remain unchanged, namely, snake3OCCW_Segment.inc and snake9OCCW_Segment.inc as used in the previous simulations. The other 3 RHIC lattice segments above are grabbed from the previously used optical sequence file pp22-yellow-CCW.INC.dat. Note that the 3 o'clock snake to 9 o'clock snake segment can be split at POL3 and the 6 segments permuted circularly, in order to start the sequence at pC polarimeter (this will be necessary in upcoming questions).

• Question 2.3.1-1

In SCALING.inc, set the snake currents to the values needed at step 0 of the vertical to radial polarization adjustment experiment, namely,

- snake 2 (3 o'clock): $I_{out} = 164.16 \text{ A}, I_{in} = 220.455;$

- snake 1 (9 o'clock): $I_{out} = 184.08 \text{ A}, I_{in} = 199.07.$

A consequence of this change of snake currents is that the orbit kickers need be adjusted, for proper centering of the helix in the snake, and proper local closed orbit bump. To achieve this, run the snake segment jobs to find (a FIT does it) the proper orbit kicker settings (as was done in Sec. 2.1 in the case of the regular 100A/322A snake currents).

Update SCALING.inc with these new kicker values.

Note that FIT produces zgoubi.FIT.out.dat. Explain the goal in doing so.

• Question 2.3.1-2

It does not hurt to check RHIC closed orbit once snake currents have been updated (in SCALING.inc) and local orbit kickers have been updated (in SCALING.inc as well).

Do this check of RHIC closed orbit, by running the job pp22-yellow-CCW_spinN0.INC.dat.

• Question 2.3.1-3

Find the spin closed orbit with these snake currents, running pp22-yellow-CCW_spinN0.INC.dat.

Explain what pp22-yellow-CCW_spinN0.INC.dat does, in particular, explain the arguments in OBJET, SPNTRK, and SPNPRT[MATRIX].

2.3 Spin Transparency Simulations

Explain in detail the arguments of the FIT procedure in pp22-yellow-CCW_spinN0.INC.dat; this FIT command is commented as can be seen. Uncommented and run the job again. What does this add, what is the interest?

• Question 2.3.1-4

Get the 1-turn spin matrix with origin at the pC polarimeter.

• Question 2.3.1-5

Using REBELOTE command, set up a scan of the 1-turn spin matrix over the 11 snake angle steps of Tab. 2.1.

Produce a graph of the spin tune and spin precession vector components so obtained (with step number as horizontal axis).

• Question 2.3.1-6

Produce a fast simulation of the experiment, as follows: launch a single particle on the closed orbit with its initial spin aligned on \mathbf{n}_0 at step 0; track over 5000 turns, while snake currents follow steps 0 to 10, Tab. 3.1. Use SCALING to update current values during tracking. Take the origin of the optical sequence at pC polarimeter, as this is where the polarization measurements are done during the APEX.

Produce a graph of the spin tune and spin vector components along the snake current ramp. A discrete Fourier transform of spin motion over a few tens of turns can be used to compute the spin motion spectrum along the current ramp. The expected results include that (i) the particle remain on the closed orbit, (ii) 5000 turns is slow enough that the particle's spin vector follow the stable spin precession direction.

• Question 2.3.1-7

Replace the snake field maps, which induce orbital motion perturbation, by SPINR which has no effect on orbital motion. Leave H and V local closed orbit bump corrector settings unchanged.

2.3.1-7.a - repeat the scan of question 2.3.1-5. Compare the results.

2.3.1-7.b - repeat the ramp of question 2.3.1-6. Compare the results.

• Question 2.3.1-8

It can be observed from the results of questions 2.3.1-5, 6, that although prescribed snake angles follow from theory, the spin which should come out constant, does not: - find an explanation to this seemingly discrepancy with theory;

- devise a fitting method which results in accurately constant spin tune, by relaxing on snake angles.

2.3.2 Vertical polarization flip

The folder concerned in this simulation is

[pathTo]/zgoubi-code/exemples/tutorials/

BNLSpinTransparency_2022/spinTransparency_2_reverseVerticalPolarization/ The jobs concerned are

pp22-yellow-CCW_spinN0_reverseVPol_pCPol.INC.dat (Question 2.3.2-1) sweep_origin-pCPol_0-10.INC.dat (Question 2.3.2-2)

Snake settings are to be taken from the answer to Question 2.1-4 (Tab. 3.2). Note that, because the snake currents do not change much over step 0-step 10, closed orbit bump settings obtained for step 0 in Sec. 2.1-2 can still be used here.

Otherwise, the simulation method is the same as in the Sec. 2.3.1, which can be referred to.

• Question 2.3.2-1

Produce a scan of the spin closed orbit vector components, and spin tune, for the 11 snake current steps. Plot the results.

• Question 2.3.2-2

Produce a fast simulation of the experiment, as follows: launch a single particle on the closed orbit with its initial spin aligned on \mathbf{n}_0 at step 0; track over 5000 turns, while snake currents follow steps 0 to 10 values, Tab. 3.2. Use SCALING to update current values during tracking. Take the origin of the optical sequence at pC polarimeter, as this is where the polarization measurements are done during the APEX.

Produce a graph of the spin tune and spin vector components along the ramp. A discrete Fourier transform of spin motion over a few tens of turns can be used to compute the spin motion spectrum along the current ramp. The expected results include that (i) the particle remain on the closed orbit, (ii) 5000 turns is slow enough that the particle's spin vector follow the stable spin precession direction.

Tutorial Part 3 Solutions of Simulation Exercises

Setting Up Snake Current Ramps

Question 2.1 series, answers

• 2.1-1:

OPTIONS[.plt,IL=2] forces IL=2 flag at all optical elements, so causing, for all elements, logging of stepwise particle data in zgoubi.plt. The content of zgoubi.plt is detailed in the Users' Guide [5, Sec. 8.3]. A 0 or 1 flag in column 50 of zgoubi.plt allows distinguishing from one another, if needed, particle data along the optical sequence (coordinates, spin vector, etc.) produced during the first pass through the latter (before reaching FIT) or during the final pass following FIT (thus, with matched variable values).

Note the following:

1/ this final pass through the input data sequence occurs once FIT has been completed, and uses the updated variable values; the final pass can be skipped if explicitly requested by specifyig 'noFinal' under FIT[2];

2/ zgoubi.FIT.out is a log of constraint values and final values of the FIT variales; 3/ an updated version of the input data file, with FIT instruction commented, is logged in zgoubi.FIT.out.dat once FIT is completed.

The gnuplot scripts under the SYSTEM command produce graphs; looking into these scripts shows that plotted data are read from zgoubi.FITVALS.out or from zgoubi.plt.

Navigating the INDEX in Zgoubi Users' Guide will allow completing this question.

• 2.1-2:

The first test of the spin transparency experiment, vertical to radial polarization, requires the snake currents given in Tab. 3.1. Graphs of the various parameters including snake currents, produced by the gnuplot script gnuplot_FITVALS.gnu under the SYSTEM command, are given in Figs. 3.1, 3.2.

Table 3.1 Snake angles and corresponding currents, for moving polarization from vertical (at step 0) to radial (at step 11)

	3 o'clock snake, CCW							9 o'clock snake, CCW					
Step #	μ	Þ	Iout	I _{in}		μ	ϕ	Iout	$I_{\rm in}$				
0	180 (0	164.16759	220.4533	5	180	170	184.08966	199.07334				
1	177 (0	166.17474	222.7973	9	180	170	184.08967	199.07334				
2	174 (0	168.19734	225.1434	4	180	170	184.08966	199.07336				
3	171 (0	170.23614	227.4925	5	180	170	184.08966	199.07335				
4	168 (0	172.29233	229.8460	2	180	170	184.08967	199.07334				
5	165 (0	174.36709	232.2053	3	180	170	184.08966	199.07334				
6	165 (0	174.36707	232.2053	1	177	172	178.43276	200.72111				
7	165 (0	174.36709	232.2053	1	174	174	172.63753	202.52287				
8	165 (0	174.36712	232.2054	0	171	176	166.69559	204.46703				
9	165 (0	174.36710	232.2053	5	168	178	160.59563	206.54226				
10	165 (0	174.36709	232.2053	4	165	180	154.32192	208.73700				

During the scan, the orbits are logged in zgoubi.plt (this is an effect of IL=2 under TOSCA keywords, or OPTIONS[.plt,IL=2]). They are plotted reading from zgoubi.plt, Fig. 3.3.

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Fig. 3.1 Vertical to radial polarization adjustment, case of 3 o'clock snake, step 0 to 10: coil currents, snake angles, closed orbit coordinate at snake entrance, and (right vertical axis) FIT penalty to control the convergence of the fitting





Fig. 3.3 Case of vertical to radial polarization adjustment: vertical helical orbits through 3 o'clock (left) and 9 o'clock (right) snakes, for the 11 different snake current steps. A graph obtained using zpop, stepwise particle data read from zgoubi.plt: menu 7; 1/1 to open zgoubi.plt; 2/[6,4] to choose Z versus s; 7 to plot. An alternate possibility is to use the gnuplot script gnuplot_Zplt_sYZ.gnu provided in the sourceforge folder

• 2.1-3:

The second test of the spin transparency experiment, vertical spin flip, requires the snake currents given in Tab. 3.2. Graphs of various parameters including snake currents, produced by the gnuplot script gnuplot_FITVALS.gnu under the SYSTEM command, are given in Figs. 3.4, 3.5.

 Table 3.2
 Snake angles and corresponding currents, for vertical polarization flip

	3	0'0	clock snake	, CCW	9 o'clock snake, CCW				
Step #	μ	ϕ	Iout	$I_{\rm in}$	μ	ϕ	Iout	I _{in}	
0	180	0	164.16759	220.45335	180	-10	184.08967	199.07333	
1	177.5	0	165.83915	222.40659	180	-10	184.08967	199.07334	
2	175	0	167.52137	224.36109	180	-10	184.08966	199.07335	
3	175	0	167.52137	224.36111	180	-5	173.87827	209.78901	
4	175	0	167.52137	224.36111	180	-2	167.99538	216.19137	
5	175	0	167.52134	224.36106	180	0	164.16805	220.45281	
6	175	0	167.52141	224.36113	180	2	160.41133	224.71226	
7	175	0	167.52137	224.36111	180	5	154.90344	231.10352	
8	175	0	167.52135	224.36106	180	10	146.03570	241.81008	
9	177.5	0	165.83916	222.40660	180	10	146.03569	241.81009	
10	180	0	164.16758	220.45335	180	10	146.03571	241.81005	

During the scan, the orbits are logged in zgoubi.plt (this is an effect of IL=2 under TOSCA keywords, or OPTIONS[.plt,IL=2]). They are plotted reading from zgoubi.plt, Fig. 3.6.

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Fig. 3.4 Vertical polarization flip, case of 3 o'clock snake, step 0 to 10: coil currents, snake angles, closed orbit coordinate at snake entrance, and (right vertical axis) fit penalty

Fig. 3.5 Vertical polarization flip, case of 9 o'clock snake, step 0 to 10: coil currents, snake angles, closed orbit coordinate at snake entrance, and (right vertical axis) FIT penalty



Fig. 3.6 Case of vertical polarization flip: : horizontal and vertical helical orbits through 3 o'clock (left) and 9 o'clock (right) snakes, for the 11 different snake current steps.

Setting Up RHIC Yellow Optics Model

Question 2.2 series, answers

• 2.2-1:

Looking up the field map regions in zgoubi.res (lookup TOSCA for instance), for the respective snake3OCCW_Segment.inc and snake9OCCW_Segment.inc jobs, allows finding the azimuthal extent of the field map region, namely,

3 o'clock snake: 37.001996 < *s* < 48.840015 m;

9 o'clock snake: 37.041440 < *s* < 48.879459 m.

These ranges are accounted for in gnuplot script gnuplot_Zplt_YZ_modified.gnu which produces the graph and saves it in a .eps file. The expected results are shown in Fig. 3.7.

Fig. 3.7 (Y,Z) projections of the helical orbits in 3 o'clock and 9 o'clock snakes. In the case of the 9 o'clock snake, the initial trajectory was slightly off-center, it shows in addition to the final one following from FIT





Y(s) and Z(s) particle coordinates (before and after FIT on the same graph) are plotted by gnuplot_Zplt_sYZ.gnu script, Figs. 3.8, 3.9.



Fig. 3.8 Horizontal (red) and vertical (blue) local closed orbit bump at 3 o'clock snake. Particle coordinates are in the magnet frame, a Cartesian frame in the case of MULTIPOL, which results in curved Y(s) trajectories along the kicker dipoles



Fig. 3.9 Horizontal (red) and vertical (blue) local orbit bump at 9 o'clock snake. The initial trajectory (before FIT) and final one (closed orbit, following from FIT) both show on this graph. Using the flag in column 50 of zgoubi.plt would allow to eliminate one or the other

• 2.2-2:

Zgoubi (O;X,Y,Z) direct triedra is oriented as follows:

- X points in the direction of the motion (CCW),

- Y points outward (as a consequence, the dispersion function $\eta(s)$ is positive, Fig. 3.10),

- Z points down (correlatively, the magnetic field in bends is positive, curvature is negative).

The complete optical sequence, all INCLUDEs deployed (if any), is logged in the execution listing zgoubi.res, always. Note that the latter can be run as is, namely,

cp zgoubi.res blahblah ; [pathTo]/zgoubi-code/zgoubi/zgoubi -in blahblah does work and produces a similar zgoubi.res to blahblah - try it?

The reason is that zgoubi.res starts with a copy of the complete input data file, down to the END command, which ends the execution - whatever follows 'END' is ignored.

Zgoubi execution strictly follows that sequence, the execution won't move to the next keyword until execution of the previous one is completed. This applies as well to FIT, however FIT is an implicit loop on the sequence, only when it is converged, or stopped for boundary reasons, will the execution move beyond FIT keyword, *i.e.* here, FAISCEAU, SPNPRT[MATRIX], etc.

About field modeling: during stepwise integration of motion, whereas TOSCA is used to produce local field B(X, Y, Z) at particle location by interpolation from a field map [5, p. 135], BEND and MULTIPOL provide B(X, Y, Z) from built-in analytical field models [5, pp. 74, 122].

The TWISS command (bottom of the main input data file) is an implicit doloop, it causes a computation of the periodic optical functions, and logs these data in zgoubi.TWISS.out (in a similar format to MADX twiss command output). The header part of zgoubi.TWISS.out is as follows (an excerpt):

0	LENGTH	%le	3833.849630							
0	ALFA	%le	0.1914832878E-02							
0	ORBIT5	%le	-0							
0	GAMMATR	%le	22.85254444							
0	Q1	%le	0.6910416027 [fractional]							
0	Q2	%le	0.7083241286 [fractional]							
0	DQ1	%le	9.043350134							
0	DQ2	%le	1.501993566							
0	DXMAX	%le	1.89765150E+00	0	DXMIN %le	-2.906	62088E-01			
0	DYMAX	%le	1.96194743E-01	0	DYMIN %le	-1.982	09723E-01			
0	XCOMAX	%le	1.12487732E-01	0	XCOMIN %le	-2.02	526362E-03			
0	YCOMAX	%le	0.0000000E+00	0	YCOMIN %le	0.00	000000E+00			
0	BETXMAX	%le	1.47936731E+02	0	BETXMIN	%le	2.46555235E+00			
0	BETYMAX	%le	1.63219155E+02	0	BETYMIN	%le	3.23642550E+00			
0	XCORMS	%le	1.66593610E-04							
0	YCORMS	%le	not computed							
0	DXRMS	%le	6.78335062E-01							
0	DYRMS	%le	5.54089006E-02							
0	DELTAP	%le	0.0000000E+00							

A FIT may precede a TWISS command, allowing to accurately find the onmomentum and chromatic closed orbits (otherwise, (i) OBJET[KOBJ=5] is assumed to provide the on-momentum particle 1 with closed orbit coordinates, and (ii) chromatic closed orbit coordinates are deduced from the periodic dispersion which TWISS derives in its first pass through the sequence [5, p. 198]). In the present case the closed orbit is small thus particle 1 coordinates are taken null, with marginal effect on first order transport coefficients computed from particle trajectories.

Additional results of the TWISS command can be found in zgoubi.res listing (bottom of the file). In particular it can be checked there that, at injection rigidity, snakes slightly change the tunes and chromaticities; the 1-turn particle transport mapping, namely,

TRANSFER	MATRIX	ORDRE	1	(MKSA	units)	
TIGHNOTER	IMIKIA	OIUDIGL	-	(Incon	unitics)	

-0.194162	-9.31691	-2.586613E-02	-0.137013	0.00000	6.823047E-02
9.658110E-02	-0.499288	-2.703870E-05	-3.964016E-02	0.00000	9.277359E-04
-4.171478E-02	0.200229	-6.923506E-02	-9.17961	0.00000	1.133383E-02
-5.384989E-03	-1.286964E-02	0.105113	-0.478062	0.00000	4.315142E-03
-7.108407E-03	2.726700E-02	-1.717272E-03	-3.051211E-02	1.00000	7.34140
0.00000	0.00000	0.00000	0.00000	0.00000	1.00000

and its analysis show that snakes also introduce coupling, coupling strength C=0.01216169.

Once TWISS is done, the execution moves to the next command, SYSTEM[gnuplot < ./gnuplot_TWISS.gnu] here, which causes a plot of orbits and optical functions as read from zgoubi.TWISS.out (Fig. 3.10).



Fig. 3.10 Closed orbits and optical functions around RHIC Yellow, counter-clockwise, case of regular snake settings for polarized proton physics runs, *i.e.* $I_{out} = \pm 100 \text{ A}$, $I_{in} = \mp 322 \text{ A}$ in both snakes

• 2.2-3:

Two different ways to obtain the stable spin precession at the start of the optical sequence are,

(i) using SPNPRT[MATRIX], in this case 3 particles need be defined in OBJET, all three identical orbit-wise: launched on the closed orbit, on-momentum, but with their respective initial spins aligned on the each of the Serret-Frénet frame axis. Zgoubi input data are as follows:

```
aĂŻOBJETAĂŻ
79.366778931425273 * 1d3
2
3 1
0. 0. 0. 0. 0. 1. AĂŻOAĂŻ
0. 0. 0. 0. 0. 1. AĂŻOAĂŻ
1 1 1
AŻPARTICULAĂŻ
PROTON
AĂŻSPNTRKAŚŻ
4
1. 0. 0.
0. 1. 0.
```

(ii) using a single particle launched on the closed orbit and FIT, to find the periodic spin vector of that particle.

OBJET in pp22-yellow-CCW_spinN0.INC.dat has been designed to allow the computation of the spin matrix following (i) above: it includes a set of 3 particles with identical initial coordinates (on the on-momentum closed orbit, here), and

orthogonal spins as specified under SPNTRK. However, OBJET also includes a 4th particle, which would be used if the FIT procedure at the end of pp22-yellow-CCW_spinN0.INC.dat is un-commented; both procedure can be run at once, that allows to verify that the spin precession axis computed by SPNRT[MATRIX] on the one hand, and the spin closed orbit \mathbf{n}_0 computed by FIT do coincide.

The answer is found at the SPNPRT[MATRIX] command which follows the optical sequence, just before 'END', namely at the bottom of zgoubi.res:

**** 3053 Keyword, label(s) : SPNPRT MATRIX TPASS= 1 -- 1 GROUPS OF MOMENTA FOLLOW Momentum group #1 (D= 1.000000E+00; particles 1 to 3; Spin components of the 3 particles, spin angles : INITIAL FINAL SZ SY ISI GAMMA |Si,Sf| (Z,Sf_yz) (Z,Sf) SZ |S| SX SX SY (deg.) (deg.) (deg.) (Sf_yz : projection of Sf on YZ plane) 1.000000 0.000000 0.000000 1.000000 -0.990752 0.056078 -0.123557 1.000000 25.3786 -172.202 132.321 97.097 1 25.3786 -176.600 91.497 25.3786 7.255 45.005 0.000000 1.000000 0.000000 1.000000 -0.053248 -0.998240 -0.026097 1.000000 91.495 1 1 0.000000 0.000000 1.000000 1.000000 -0.124803 -0.019276 0.991994 1.000000 7.255 3 Spin transfer matrix, momentum group # 1 : -0 990752 -0.990752 -5.324753E-02 -0.124803 5.607821E-02 -0.998240 -1.927646E-02 -2.609690E-02 0.991994 -0.123557 Determinant = 1.0000000000 Deceminant = 1.0000000000 Trace = -0.9969976995; spin precession acos((trace-1)/2) = 176.8601850189 d Precession axis : (-0.0623, -0.0114, 0.9980) -> angle to (X,Y) plane, to X axis : Spin precession/2pi (or Qs, fractional) : 4.9128E-01 176.8601850189 deg 86.3712, 93.5696 deg Remaining 1 particles ; Spin components of the 1 particles, spin angles : INITIAL FINAL SX SZ |S| SX SY SZ. ISI GAMMA |Si,Sf| (Z,Sf_yz) (Z,Sf) SY (deg.) (deg.) (deg.) (deg.) (Sf_yz : projection of Sf on YZ plane)

o 1 -0.062259 -0.011371 0.997990 0.999994 -0.062264 -0.011378 0.997995 1.000000 25.3786 0.000 45.002 3.629 4

What we see there:

- the first 3 particles have been used to compute the "Spin transfer matrix, momentum group # 1". A sub-product of this matrix calculation is the stable spin precession direction:

```
Precession axis : (-0.0623, -0.0114, 0.9980)
```

- the 4th particle is just let go through the ring. However it has been launched with its spin aligned on the stable precession axis (SPNTRK command at the beginning of pp22-yellow-CCW_spinN0.INC.dat), thus it ends up with the same spin coordinates after 1 turn around the ring, see the bottom in zgoubi.res excerpt lines above.

Spin Transparency Simulations

Vertical to radial polarization

• Question 2.3.1 series, answers

• 2.3.1-1:

Snake currents are set to the values needed at step 0 of the vertical to radial polarization adjustment. The gnuplot scripts called by the SYSTEM command save the graphs in .eps files. The outcomes are shown in Figs. 3.11, 3.12.



Fig. 3.11 Horizontal (red) and vertical (blue) local orbit bumps at 3 o'clock and 9 o'clock snakes. Orbits resulting from kicker values at start and end of FIT are plotted



Fig. 3.12 (Y,Z) projections of the helical orbits in 3 o'clock and 9 o'clock snakes. Off-centered helices at start of FIT (*i.e.*, with orbit kickers set for the earlier 100A/322A snake currents) are displayed together with the centered helices resulting from kicker values adjusted for the new snake currents

The orbits inside the snakes are part of the data logged in zgoubi.plt. Looking up the field map regions in zgoubi.res (lookup "TOSCA ", for instance), for the respective snake3OCCW_Segment.inc and snake9OCCW_Segment.inc jobs, allows finding the azimuthal extent of the field map region, namely,

3 o'clock snake': 37.001996 < *s* < 48.840015 m,

9 o'clock snake': 37.041440 < s < 48.879459 m.

These ranges are accounted for in gnuplot script gnuplot_Zplt_YZ.gnu which produces the graph and saves it in a .eps file. The expected results are shown in Fig. 3.11.

An excerpt of SCALING.inc files, with proper orbit kicker settings:

MULTIPOL YO9_TV5	! Next 6 elements:	9 o'clock snake orbit kiMUMeFEPOL YI3_TV4	! Next 6 elements:	3 o'clock snake orbit kickers
-1		-1		
1.7905968411E+05		-5.0364070518E+05		
1		1		
MULTIPOL Y09_TV7		MULTIPOL YI3_TV6		
-1		-1		
3.6564632690E+05		-2.4489762740E+05		
1		1		
MULTIPOL Y09_TH8		MULTIPOL YI3_TV8		
-1		-1		
6.4252488673E+03		-2.9093216368E+05		
1		1		
MULTIPOL Y09_TV9		MULTIPOL YI3_TH9		
-1		-1		
5.2125941079E+04		1.9964797598E+03		
1		1		
MULTIPOL Y09_TH10		MULTIPOL YI3_TV10		
-1		-1		
6.7996064758E+03		-1.3881781797E+05		
1		1		
MULTIPOL Y09_TV11		MULTIPOL YI3_TH11		
-1		-1		
5.0732776649E+05		4.1869407887E+03		
1		1		

The file zgoubi.FIT.out.dat: an input data file, produced by FIT once done. It is a replica of the original input data file, updated with variable values found by FIT.

• 2.3.1-2:

Running the job pp22-yellow-CCW_spinN0.INC.dat produces the orbits and optical functions displayed in Fig. 3.13.



Fig. 3.13 Closed orbits and optical functions around RHIC Yellow, counter-clockwise. This accounts for step 0 of the snake settings for vertical to radial polarization adjustment; 3 o'clock snake: $I_{out} = 164.16 \text{ A}$, $I_{in} = 220.455$, 9 o'clock) snake: $I_{out} = 184.08 \text{ A}$, $I_{in} = 199.07$.

Because the option IL=2 under TOSCA keywords has been maintained (look up "'TOSCA'" in

snake3OCCW_Segment.inc and snake9OCCW_Segment.inc files), particle data are still logged in zgoubi.plt when running pp22-yellow-CCW.INC.dat. Thus the local vertical orbit can be plotted, reading from zgoubi.plt. The script gnuplot_Zplt_sYZ.gnu is used for that; the orbital coordinate range for each snake is read from zgoubi.res, namely (look up "TOSCA " in zgoubi.res): 3 o'clock snake : 753.10910 < s < 764.781084 m;

9 o'clock snake : 2669.60052 < s < 2681.27252 m



Fig. 3.14 Horizontal (red) and vertical (blue) helical orbits, centered, across 3 o'clock and 9 o'clock snake, at step 0 of the spin transparency experiment

• 2.3.1-3:

The job pp22-yellow-CCW_spinN0.INC.dat computes the 1-turn spin matrix. The command SPNPRT[MATRIX] performs that computation, from spin coordinates. For SPNPRT[MATRIX] to work, the transport of the 3 different spins: (1,0,0), (0,1,0) and (0,0,1), is required, this requires in turn OBJET to define 3 times the on-orbit particle, and SPNTRK to assign these different initial spin values to the three particles.

The results are found under SPNPRT, bottom of zgoubi.res execution listing:

Spin	transfer matrix,	<pre>momentum group # 1 :</pre>	
0.926849	0.348378	0.139942	
-0.344618	0.937354	-5.105082E-02	
-0.148960	-9.101234E-04	0.988843	
Determinant = Trace = 2.8530 Precession axis : (Spin precession/2pi	1.0000000000 455354; spin pr 0.0666, 0.3839, (or Qs, fractiona	ecession acos((trace-1)/2) = 22.1008928920 deg -0.9210) -> angle to (X,Y) plane, to X axis : -67.0658, 1) : 6.1391E-02	80.1540 deg

The FIT procedure works on particle number 4, as the first 3 particles can not be touched (they are used for 1-turn spin matrix computation by SPNPRT). FIT constrains the spin vector associated with particle 4 to be periodic: initial coordinates identical to initial ones. For this it varies the initial coordinates.

FIT is commented as it happens to be redundant with SPNPRT[MATRIX] computing the spin closed orbit from the spin matrix. Anyway, FIT can be run for cross-check with the latter, letting it go yields the following final FIT state (there are three possible ways to find the FIT status as copy-pasted below: it is saved, by the FIT command, in fitVals_n0_IP6; lookup "FIT" in zgoubi.res listing; it appears on the computer screen in real-time as FIT is running).

				FIT	varia	ables	and	con	strair	its	in	good	order,	FIT	wi	ll proceed
STAT	rus (OF VA	ARIABL	.ES ([terat:	ion #		0 /	999	max	:.)					
LMNT	VAR	PARA	AM MI	NIMUM	INI	ITIAL		F	INAL			MAXIMUN	M S	STEP		NAME
3	1	4	40 -	1.11		0.00		-6.66	319420)E-0)2	1.11	2.7	736E-0	5 S	PNTRK
3	2	4	41 -	1.11		0.00		-0.38	393333	;		1.11	2.7	764E-0	5 S	PNTRK
3	3	4	12 -	1.11		1.00		0.92	096090)		1.11	2.3	819E-0	5 S	PNTRK
STAT	rus (OF CC	ONSTRA	INTS	(Target	t pena	lty	= 1	.0000E	2-10))					
TYPE	I	JI	.MNT#	DI	ESIRED			WEIGH	Т		RE/	ACHED		KI2	N	AME
10	4	1	3050	0.0	0000001	E+00	1.	000E+	00	1.7	0490	04E-06	Infi	nity	OPTI	ONS
10	4	2	3050	0.0	0000001	E+00	1.	000E+	00	1.3	8429	96E-06	Infi	nity	OPTI	ONS
10	4	3	3050	0.0	0000001	E+00	1.	000E+	00	6.6	7580	09E-06	Infi	nity	OPTI	ONS
10	4	4	3050	1.0	0000001	E+00	1.	000E-	01	1.0	0000	00E+00		NaN	OPTI	ONS
Fit	read	ched	penal	ty va	lue 4	4.9389	E-11									

The periodic spin vector found by FIT appears to be (FINAL column in the spin status above)

periodic $\mathbf{S} = (-0.0666319, -0.383933, 0.920960)$

and does coincide with the spin precession axis as computed by SPNPRT[MATRIX], namely,

$$\mathbf{n}_0 = (0.0666, 0.3839, -0.9210)$$

• 2.3.1-4:

The 1-turn spin mapping is computed by SPNPRT[MATRIX], taking the optical sequence as a whole, and assuming it periodic. As a consequence it is necessary to move "'MARKER' YO12_POL3.INST", which is the location of the pC polarimeters, to the end of the optical sequence.

This requires,

(i) splitting pp22-yellow-CCW.INC.dat[DRIFT_250:YO9_QS4] at the polarimeter, yielding two files,

pp22-yellow-CCW.INC.dat[DRIFT_250:YO12_POL3.INST] and

pp22-yellow-CCW.INC.dat[YO12_POL3.INST:YO9_QS4]

(ii) circularly permuting the INCLUDE statements to bring pp22-yellow-CCW.INC.dat[YO12_POL3.INST:YO9_QS4] to be the first INCLUDE of the Yellow ring series, starting at pC polarimeter. This yields the file

pp22-yellow-CCW_spinN0_origin-pCPol.INC.dat

available in the same folder, namely,

[pathTo]/zgoubi-code/exemples/tutorials/BNLSpinTransparency_2022/spinTransparency_1_adjustRadialPolarisation

The results are found under SPNPRT, bottom of zgoubi.res execution listing:

Spin	ı transfer matrix,	<pre>momentum group # 1 :</pre>	
0.928391 0.338901 0.152432	-0.347719 0.936958 3.465804E-02	-0.131077 -8.517969E-02 0.987706	
Determinant = 1 Trace = 2.85305 Precession axis : (Spin precession/2pi (.0000000000 56616; spin pre 0.1593, -0.3768, or Qs, fractional	cession acos((trace-1)/2) = 22.1001218426 deg 0.9125) -> angle to (X,Y) plane, to X axis : 65.8544, -67.) : 6.1389E-02	0865 deg

• 2.3.1-5:

Make sure the END statement preceding REBELOTE at the bottom of pp22yellow-CCW_spinN0.INC.dat is commented, this will allow the execution to carry on and execute the REBELOTE command.

The data for a graph are extracted from the execution listing zgoubi.res, using linux "grep" command. This is done by the gnuplot script gnuplot_ZRes_spinPrecAxis.gnu, results are given in Figs. 3.15, 3.16.



Fig. 3.15 Components of the stable spin precession direction at IP6, and spin tune, at the 11 different steps of the vertical to radial polarization adjustment scan



Fig. 3.16 Components of the stable spin precession direction at pC-pol polarimeter in IR12, and spin tune, at the 11 different steps of the vertical to radial polarization adjustment scan

• 2.3.1-6:

First the earlier input data file pp22-yellow-CCW_spinN0.INC.dat is saved to sweep_origin-pCPol_0-10.INC.dat, as a starting point. This file can also be down-loaded from sourceforge. A few things need to be changed in order to perform the ramp, namely,

- OBJET is set to launch a single particle:

```
äÅźOBJETäÅź
79.366778931425273 * 1d3
2
1 1
0.0.0.
0.0.
0.1. åÅźoāÅź
1
```

- the initial spin component is set to \mathbf{n}_0 values (Tab. 3.1):

ažáspntrkažá 4 -5.93769E-02 -0.42047 0.90535

- the file name under FAISTORE: remove any âĂIJb_âĂİ prefix, to allow easy use of gnuplot. FAISTORE[zgoubi.fai] is adopted here: turn by turn particle data will be logged in zgoubi.fai. The TOSCA components under SCALING are

```
        TOSCA
        snkl1.ow8
        snkl = 9'o

        11
        14.0896
        184.0896
        184.0896
        184.0896
        184.0896
        184.0896
        184.0896
        172.6373
        166.5953
        160.5953
        154.3212

        1
        501
        1001
        1501
        2001
        2501
        3001
        3501
        4001
        4501
        5001

        105CA
        snklHighB
        !
        snkl = 9'o

        501
        4001
        4501
        5001

        11
        199.07334
        199.07335
        199.07335
        199.07334
        200.7211
        202.52287
        204.46703
        206.54226
        28.73700

        10
        501
        1001
        1501
        2001
        2501
        3001
        3501
        4001
        4501
        5001

        105CA
        snkl2cow
        !
        snk2 = 3'o
        !
        snk2
        3'o
        !
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709
        174.36709</td
```

It is advised to create a modified version of the earlier, e.g. SCALING_radialPolarization_sweep.inc, with these changes included. The sequence is directly followed by a REBELOTE loop for multiturn tracking, and a request for particle (FAISCEAU) and spin coordinate (SPNPRT) print out in the execution listing zgoubi.res:

```
àĂŹREBELOTEâĂŹ
5000 0.3 99
àĂŹFAISCEAUàĂŹ
àĂŹSPNPRTâĂŹ
àĂŹENDâĂŹ
```

Note: the execution can be speeded up by setting IL=0 under TOSCA keyword in the snake segment files (or using OPTIONS[.plt,IL=0]): that avoids stepwise particle data storage (in zgoubi.plt) during execution, which would eat up CPU time (file I/Os are much time consuming).

A Fortran program, spinTuneFromFai_iterate, is available in zgoubi toolbox to compute the turn-by-turn spin motion DFT. Its input file should be

1 5001 100	98 !	first turn, last turn, turn step, DFT sampling
0.0 0.499999	1	spin tune spectrum range
2500 ! nbin	1	spectrum sampling over the spin tune spectrum range
zgoubi.fai	!	input data file name

Outcomes of this job are logged in spinTuneFromFai_iterate.Out, and can be plotted using the following gnuplot script, to produce the requested graph (displayed in Fig. 19):

```
# gnuplot_spinTuneFromFai.gnu
set tit "Spin tune and spin vector versus turn number "
set xlabel "Turn"; set ylabel "n_(0,X), n_{0,Y}, n_{0,Z}, Q_{sp}"
set xtaics; set ytics nomirror; set key maxcol 1
set xrange [1:6000]; set yrange [-1:1.]
plot \
    "spinTuneFromFai_iterate.Out" u (10* $8):($2) w lp pt 11 tit "5000 turns; n_{0,X}", \
    "spinTuneFromFai_iterate.Out" u (10* $8):($3) w lp pt 13 tit "n_{0,Y}", \
    "spinTuneFromFai_iterate.Out" u (10* $8):($4) w lp pt 15 tit "n_{0,Z}", \
    "spinTuneFromFai_iterate.Out" u (10* $8):($1) w lp pt 17 ps .8 tit "Q_{sp}"
pause 10
```



Fig. 3.17 Evolution of spin n_0 vector coordinates at pC-polarimeter (left vertical axis) and spin tune (from a DFT of turn-by-turn spin motion - right axis) over 50,000 turns tracking.



Fig. 3.18 Turn-by-turn spin components at pCpolarimeter, from zgoubi.fai, using zpop

Vertical polarization flip

• Question 2.3.2 series, answers

• 2.3.2-1:

The data for a graph are extracted from the execution listing zgoubi.res, using linux "grep" command. This is done by the gnuplot script gnuplot_ZRes_spinPrecAxis.gnu, results are given in Fig. 3.15.

Fig. 3.19 Components of the stable spin precession direction at pC-pol polarimeter in IR12, and spin tune, at the 11 different steps of the vertical polarization flip scan. Solid lines are to guide the eye



• 2.3.2-2:

Fig. 3.20 Components of the stable spin precession direction at pC-pol polarimeter in IR12, and spin tune, over a 5000-turn continuous ramp of snake currents from step 0 to step 10. Data plotted from zgoubi.fai, using zpop



References

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